

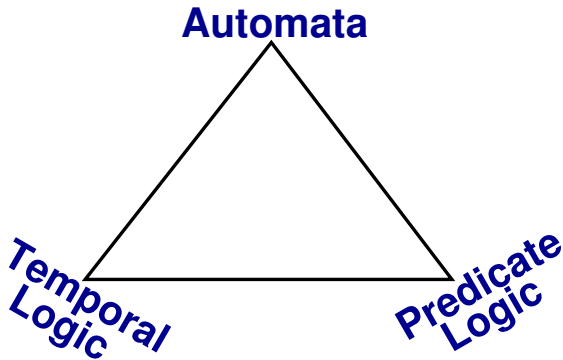
# Tutorial on Timed Systems Verification

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MoVeP, July 2010

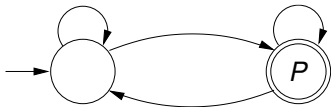
# The Classical Theory of Verification



- ▶ Qualitative (order-theoretic), rather than quantitative (metric).
- ▶ Time is modelled as the naturals  $\mathbb{N} = \{0, 1, 2, 3, \dots\}$ .
- ▶ Note: focus on linear time (as opposed to branching time).

# A Simple Example

*'P occurs infinitely often'*



$$\square \diamond P$$
$$\forall x \exists y (x < y \wedge P(y))$$

# Specification and Verification

Assume the system is modelled by an automaton  $M$ .  
The specification can be given by:

- ▶ A **Linear Temporal Logic (LTL)** formula  $\theta$ .

$$\theta ::= P \mid \theta_1 \wedge \theta_2 \mid \theta_1 \vee \theta_2 \mid \neg\theta \mid \theta_1 \mathcal{U} \theta_2 \mid \theta_1 \mathcal{S} \theta_2$$

For example,  $\Box(REQ \rightarrow \Diamond ACK)$ .

Verification is then **model checking**:  $M \models \theta$  ?

- ▶ A **First-Order Logic (FO(<))** formula  $\varphi$ .

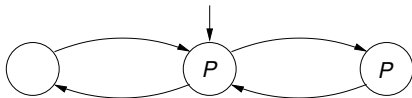
$$\varphi ::= x < y \mid P(x) \mid \varphi_1 \wedge \varphi_2 \mid \varphi_1 \vee \varphi_2 \mid \neg\varphi \mid \forall x \varphi \mid \exists x \varphi$$

For example,  $\forall x (REQ(x) \rightarrow \exists y (x < y \wedge ACK(y)))$ .

Verification is again **model checking**:  $M \models \varphi$  ?

## Another Example

*'P holds at every even position  
(and may or may not hold at odd positions)'*



- ▶ It turns out it is **impossible** to capture this requirement using LTL or FO(<).
- ▶ LTL and FO(<) can however capture the specification: *'Q holds precisely at even positions'*:

$$Q \wedge \square(Q \rightarrow \bigcirc \neg Q) \wedge \square(\neg Q \rightarrow \bigcirc Q)$$

- ▶ So one way to capture the original specification would be to write: *'Q holds precisely at even positions **and**  $\square(Q \rightarrow P)$ '*.
- ▶ Finally, need to existentially quantify Q out:

$$\exists Q (Q \text{ holds precisely at even positions } \mathbf{and} \square(Q \rightarrow P))$$

# More Specification and Verification

Monadic Second-Order Logic (MSO(<>):

$\varphi ::= x < y \mid P(x) \mid \varphi_1 \wedge \varphi_2 \mid \varphi_1 \vee \varphi_2 \mid \neg \varphi \mid \forall x \varphi \mid \exists x \varphi \mid \forall P \varphi \mid \exists P \varphi$

Theorem (Büchi 1960)

*Any MSO(<) formula  $\varphi$  can be effectively translated into an equivalent automaton  $A_\varphi$ .*

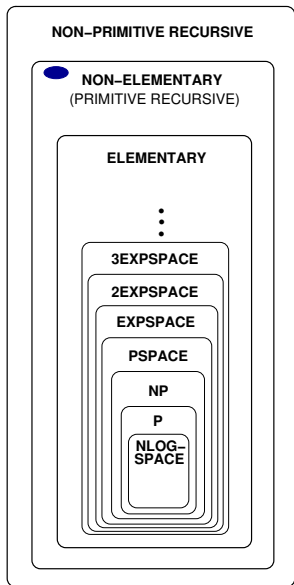
Corollary (Church 1960)

*The model-checking problem for automata against MSO(<) specifications is decidable:*

$$M \models \varphi \quad \text{iff} \quad L(M) \cap L(A_{\neg\varphi}) = \emptyset$$

# Algorithmic Complexity

UNDECIDABLE



▶ Most problems in Computer Science sit within PSPACE.

▶ Hierarchy extends much beyond:

▶ EXPSPACE:  $2^{p(n)}$

▶ 2EXPSpace:  $2^{2^{p(n)}}$

▶ 3EXPSpace:  $2^{2^{2^{p(n)}}}$

▶ ...

▶ ELEMENTARY:  $\bigcup_{k \in \mathbb{N}} \{k\text{EXPSpace}\}$

▶ NON-ELEMENTARY:  $2^{\underbrace{2^{2^{\dots^n}}}_n}$

▶ NON-PRIMITIVE RECURSIVE:

Ackerman: 3, 4, 8, 2048,  $2^{\underbrace{2^{2^{\dots^2}}}_{2048}}, \dots$

# Complexity and Equivalence

In fact:

Theorem (Stockmeyer 1974)

*FO( $<$ ) satisfiability has non-elementary complexity.*

Theorem (Kamp 1968;

Gabbay, Pnueli, Shelah, Stavi 1980)

*LTL and FO( $<$ ) have precisely the same expressive power.*

But amazingly:

Theorem (Sistla & Clarke 1982)

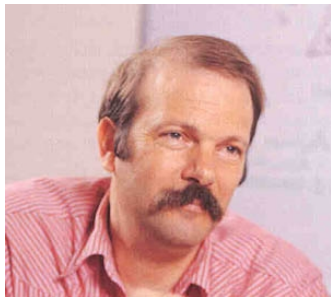
*LTL satisfiability and model checking are PSPACE-complete.*



# Logics and Automata

*“The paradigmatic idea of the **automata-theoretic approach to verification** is that we can compile high-level logical specifications into an equivalent low-level finite-state formalism.”*

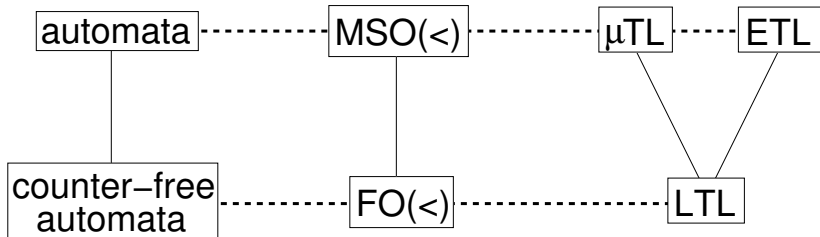
Moshe Vardi



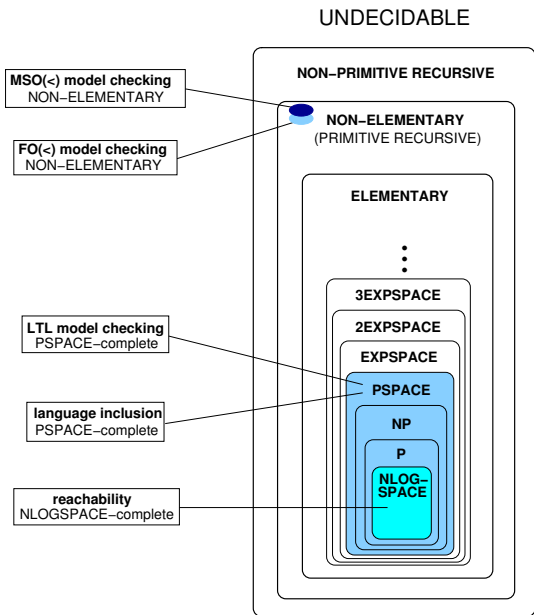
## Theorem

*Automata are closed under all Boolean operations. Moreover, the language inclusion problem ( $L(A) \subseteq L(B) ?$ ) is PSPACE-complete.*

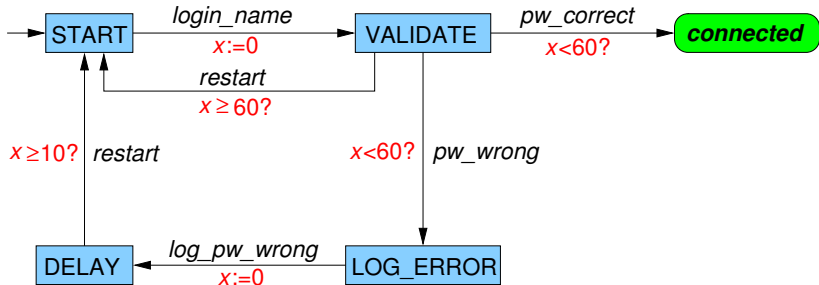
# The Classical Theory: Expressiveness



# The Classical Theory: Complexity



# A Login Protocol



SPECIFICATION:  $\square(pw\_wrong \longrightarrow \square_{[0,10)} \neg restart)$





# Timed Systems

Timed systems occur in:

- ▶ Hardware circuits
- ▶ Communication protocols
- ▶ Cell phones
- ▶ Plant controllers
- ▶ Aircraft navigation systems
- ▶ ...

In many instances, it is **crucial** to accurately model the timed behaviour of the system.

# From Qualitative to Quantitative

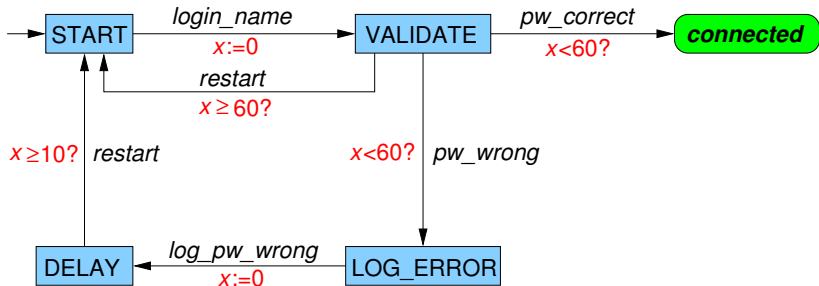
*“Lift the classical theory  
to the real-time world.”*

Boris Trakhtenbrot, LICS 1995





# Timed Automata



# Timed Automata

**Timed automata** were introduced by Rajeev Alur at Stanford during his PhD thesis under David Dill:

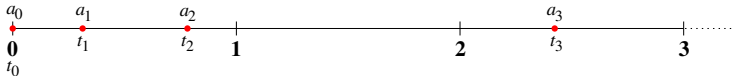
- ▶ Rajeev Alur, David L. Dill: *Automata For Modeling Real-Time Systems*. ICALP 1990: 322-335
- ▶ Rajeev Alur, David L. Dill: *A Theory of Timed Automata*. TCS 126(2): 183-235, 1994



# Timed Words

- ▶ A *timed word* is a finite or infinite sequence of *timed events*:

$$\langle (t_0, a_0), (t_1, a_1), (t_2, a_2), (t_3, a_3), \dots \rangle$$



# Timed Automata

Timed automata are language acceptors for timed words

Theorem (Alur, Courcourbetis, Dill 1990)

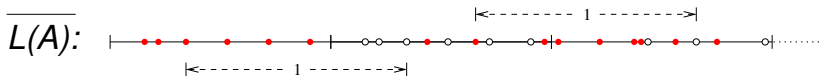
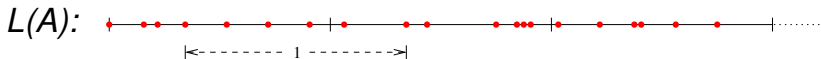
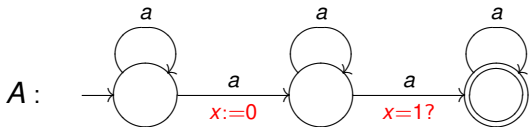
*Reachability is decidable, in fact PSPACE-complete.*

Unfortunately:

Theorem (Alur & Dill 1990)

*Language inclusion is undecidable for timed automata.*

# An Uncomplementable Timed Automaton



**A cannot be complemented:**

There is no timed automaton  $B$  with  $L(B) = \overline{L(A)}$ .

# Metric Temporal Logic

**Metric Temporal Logic (MTL)** [Koymans; de Roever; Pnueli ~1990] is a central **quantitative** specification formalism for timed systems.

- ▶ MTL = LTL + **timing constraints on operators**:

$$\square(\boxplus_{[0,1]} PEDAL \rightarrow \diamond_{[5,10]} BRAKE)$$

- ▶ Widely cited and used (over seven hundred papers according to `scholar.google.com!`).

Unfortunately:

**Theorem (Alur & Henzinger 1992)**

*MTL satisfiability and model checking are undecidable over  $\mathbb{R}_{\geq 0}$ . (Decidable but non-primitive recursive under certain semantic restrictions [Ouaknine & Worrell 2005].)*

# Metric Predicate Logic

The **first-order metric logic of order** ( $FO(<, +1)$ ) extends  $FO(<)$  by the unary function '+1'.

For example,  $\Box(PEDAL \rightarrow \Diamond_{[5,10]} BRAKE)$  becomes

$$(PEDAL(x) \rightarrow \exists y (x + 5 \leq y \leq x + 10 \wedge BRAKE(y)))$$

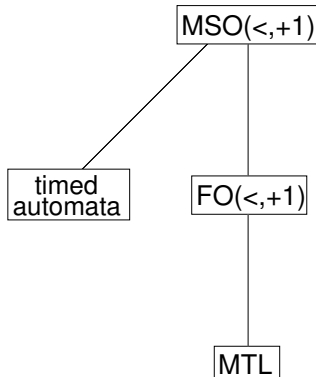
**Theorem (Hirshfeld & Rabinovich 2007)**

*$FO(<, +1)$  is strictly more expressive than MTL over  $\mathbb{R}_{\geq 0}$ .*



**Corollary:**  $FO(<, +1)$  and  $MSO(<, +1)$  satisfiability and model checking are undecidable over  $\mathbb{R}_{\geq 0}$ .

# The Real-Time Theory: Expressiveness





# Key Stumbling Blocks

Theorem (Alur & Dill 1990)

*Language inclusion is undecidable for timed automata.*

Theorem (Hirshfeld & Rabinovich 2007)

*$FO(<, +1)$  is strictly more expressive than MTL over  $\mathbb{R}_{\geq 0}$ .*

## **Part II: Negative Results**

# Undecidability

## Theorem (Alur & Dill 1990)

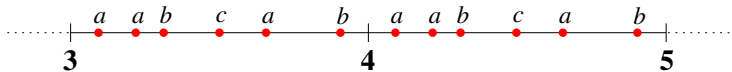
*Language inclusion is undecidable for timed automata.*

### **Proof.**

- ▶ Encode halting computations of two-counter machine  $M$  as timed language  $L(M)$ .
- ▶ Define timed automaton  $A$  accepting the **complement** of  $L(M)$ .
- ▶  $A$  is universal if and only if  $L(M)$  has no halting computation.

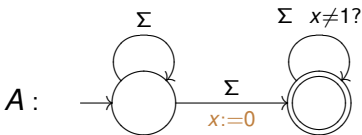
# Undecidability

Suppose that at time 3, the current tape contents of  $M$  is  $\langle aabcab \rangle$ .



# Undecidability

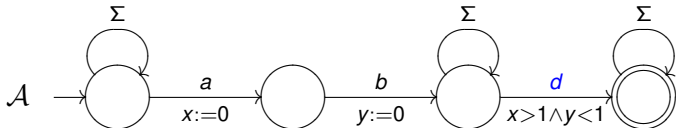
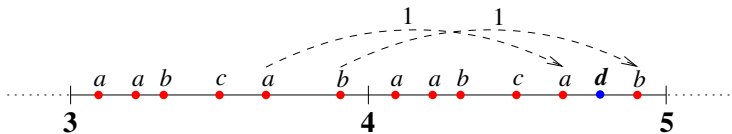
To correctly propagate the tape contents we require that every event in the current time interval have a matching event one time unit later.



A accepts all timed words that *violate* this property

# Backward Propagation

This not sufficient: we have only enforced *forward* propagation of events.



# Observations

The undecidability proof required

- ▶ Dense Time
- ▶ Infinite Precision
- ▶ Two clocks
- ▶ Timed words of unbounded duration

# Inexpressiveness

## Theorem (Hirshfeld & Rabinovich 2007)

*$FO(<, +1)$  is strictly more expressive than any temporal logic with finitely many modalities definable in  $FO(<, +1)$  over  $\mathbb{R}$ .*

Build your own temporal logic:

- ▶  $(X \mathcal{U} Y)(t) \equiv \exists s > t (Y(s) \wedge \forall u (t < u < s \rightarrow X(u)))$
- ▶  $(X \mathcal{S} Y)(t) \equiv \exists s < t (Y(s) \wedge \forall u (s < u < t \rightarrow X(u)))$
- ▶  $C_n(X)(t) \equiv \exists x_1 \cdots \exists x_n$   
 $(t < x_1 < \cdots < x_n < t + 1 \wedge X(x_1) \wedge \cdots \wedge X(x_n))$



# Inexpressiveness

## Theorem (Hirshfeld & Rabinovich 2007)

Let  $TL$  be a temporal logic with **finitely many modalities** definable in  $FO(<, +1)$ . Then  $TL$  is strictly less expressive than  $FO(<, +1)$ .

- ▶ One free predicate variable  $P$ .
- ▶ Four **simple formulas**  $P(t)$ ,  $\neg P(t)$ , True and False.
- ▶ Model  $\mathcal{M}_k$  interprets  $P$  as  $\mathbb{N}/k$ .
- ▶ In  $\mathcal{M}_k$  every formula  $\varphi(t)$  of  $FO(<, +1)$  is equivalent to a simple formula.

# Inexpressiveness

- ▶ TL-modality  $O(X_1, \dots, X_n)$  interpreted by FO( $<, +1$ )-formula  $\psi(X_1, \dots, X_n, t)$ .
- ▶ Semantics of  $\psi$  in  $\mathcal{M}_k$  defined by **truth table**.

$X_1$	$\dots$	$X_n$	$\psi$
$P$	$\dots$	True	$\neg P$

- ▶ There exists  $k \neq \ell$  such that any TL-formula is equivalent to the same simple formula on both  $\mathcal{M}_k$  and  $\mathcal{M}_\ell$ .
- ▶ But  $C_n$  distinguishes  $\mathcal{M}_k$  from  $\mathcal{M}_\ell$  for some  $n$ .

## **Part II: One-Clock Automata**

## Mind the Gap

Timed automata language inclusion:  $L(B) \stackrel{?}{\subseteq} L(A)$

- $A$  has *no* clocks: PSPACE-Complete [Alur *et al.* 90]
- $A$  has *two* clocks: Undecidable [Alur, Dill 94]

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This result is somewhat surprising: in most computational structures, deciding language inclusion normally uses:

$$L(B) \subseteq L(A) \iff L(B) \cap \overline{L(A)} = \emptyset$$

However, one-clock timed automata cannot be complemented ...

## Some Applications

- Hardware and software systems are often described via high-level **functional specifications**, describing their intended global behavior.
- Functional specifications are often given as **finite-state machines**.  
A proposed implementation *IMP* meets its specification *SPEC* iff

$$L(IMP) \subseteq L(SPEC).$$

**Finite-state machines** are often used as **specifications** of systems:

$$IMP \text{ meets } SPEC \text{ iff } L(IMP) \subseteq L(SPEC)$$

- Our work enables us to handle **timed** functional specifications:  
**timed automata with a single clock**.
- (Further potential applications to verification described later on.)

## Sketch of the Algorithm

- Reduce the language inclusion question  $L(B) \stackrel{?}{\subseteq} L(A)$  to a **reachability** question on an infinite graph  $\mathcal{H}$ .



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  - Whenever  $W \preceq W'$ : if  $W$  is safe, then  $W'$  is safe.
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- Explore  $\mathcal{H}$ , looking for unsafe nodes. The search must eventually terminate.
- For simplicity, we focus on **universality**:  $L(A) \stackrel{?}{=} \mathbf{TT}$

## Higman's Lemma

Let  $\Lambda = \{a_1, a_2, \dots, a_n\}$  be an alphabet.

Let  $\preceq$  be the **subword order** on  $\Lambda^*$ , the set of finite words over  $\Lambda$ .

Ex.: HIGMAN  $\preceq$  HIGHMOUNTAIN

Then  $\preceq$  is a **well-quasi-order** on  $\Lambda^*$ :

Any infinite sequence of words  $W_1, W_2, W_3, \dots$  must eventually have two words  $W_i \preceq W_j$ , with  $i < j$ .

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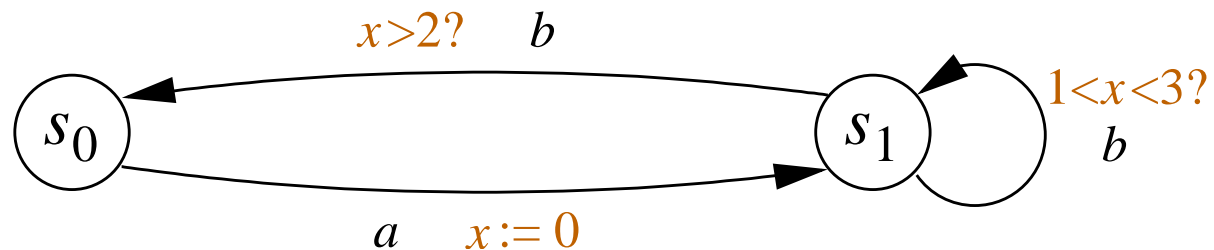
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## Timed Automata Configurations

Let  $A$  be a timed automaton with a single clock  $x$ ,  
and discrete **locations**  $s_0, s_1, \dots, s_n$ .

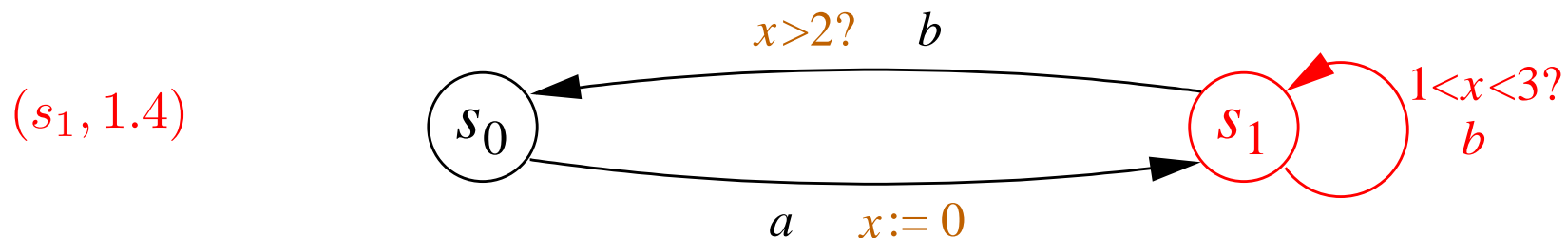
- A **state** of  $A$  is a pair  $(s, v)$ :
  - $s$  is a location.
  - $v \in \mathbb{R}^+$  is the value of clock  $x$ .
- A **configuration** of  $A$  is a finite set of states.



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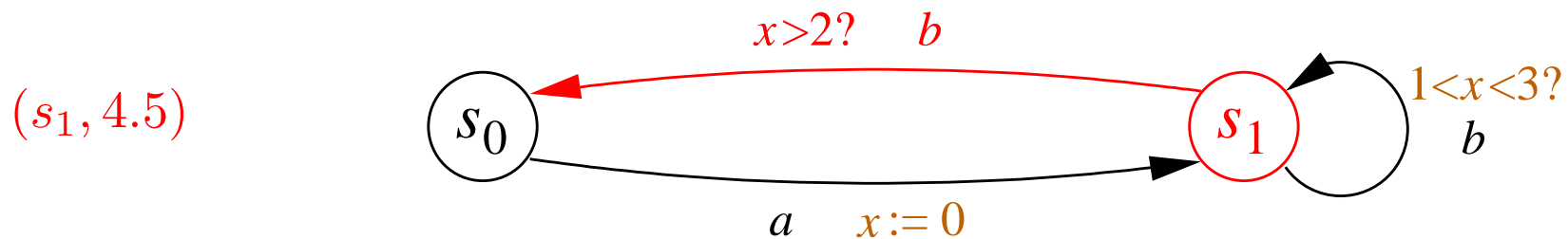
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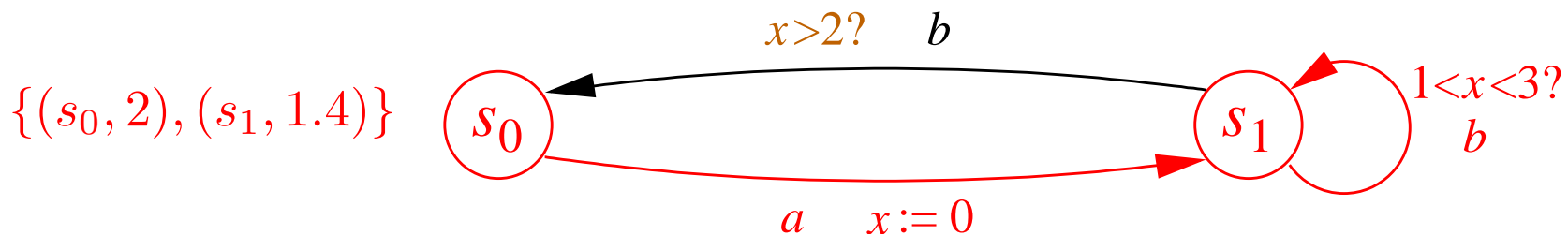




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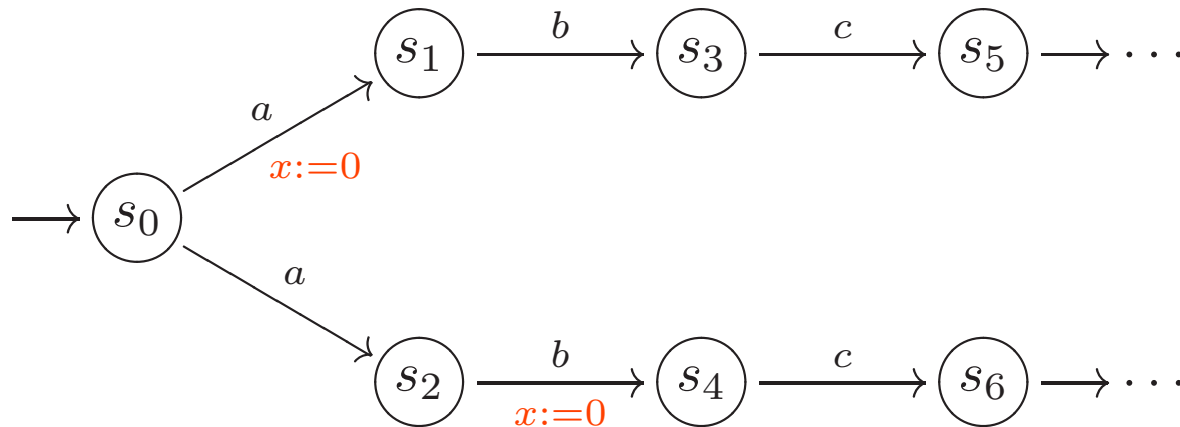
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## Timed Automata Configurations

Every timed trace  $u$  gives rise to a configuration of  $A$ .

Ex.:  $u = \langle 0.5, a, 0.2, b, 0.4, c \rangle$  leads to  $\{(s_5, 0.6), (s_6, 0.4)\}$ .



## Bisimilar Configurations

If  $C$  is a configuration, let  $A[C]$  be  $A$  ‘started’ in configuration  $C$ .

**Definition.** A relation  $\mathcal{R}$  on configurations is a **bisimulation** if, whenever  $C_1 \mathcal{R} C_2$ , then

- $\forall a \in \Sigma, \forall t_1 \in \mathbb{R}^+, \exists t_2 \in \mathbb{R}^+$  such that  
if  $A[C_1] \xrightarrow{t_1, a} A[C'_1]$ , then  $A[C_2] \xrightarrow{t_2, a} A[C'_2]$ , and  $C'_1 \mathcal{R} C'_2$ .
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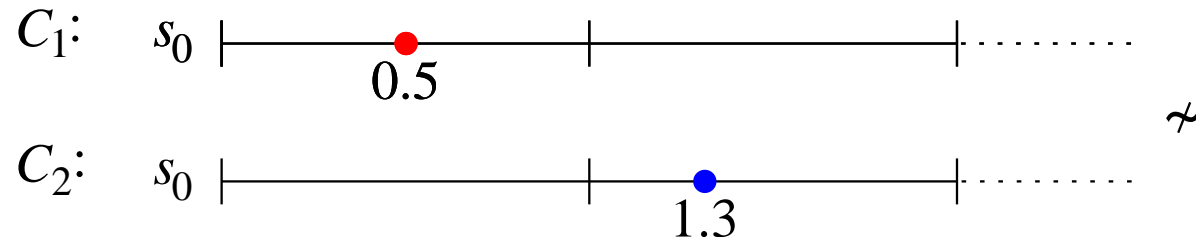
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**Theorem.** If  $C_1 \sim C_2$ , then

$$A[C_1] \text{ is universal} \iff A[C_2] \text{ is universal.}$$

## Bisimilar Configurations: Examples

$$C_1 = \{(s_0, 0.5)\} \approx C_2 = \{(s_0, 1.3)\}.$$

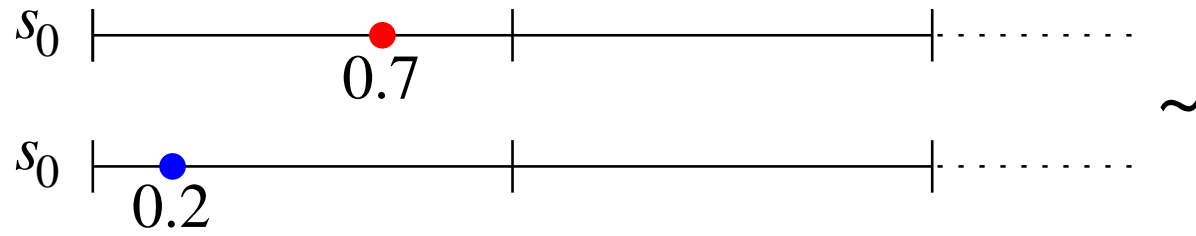




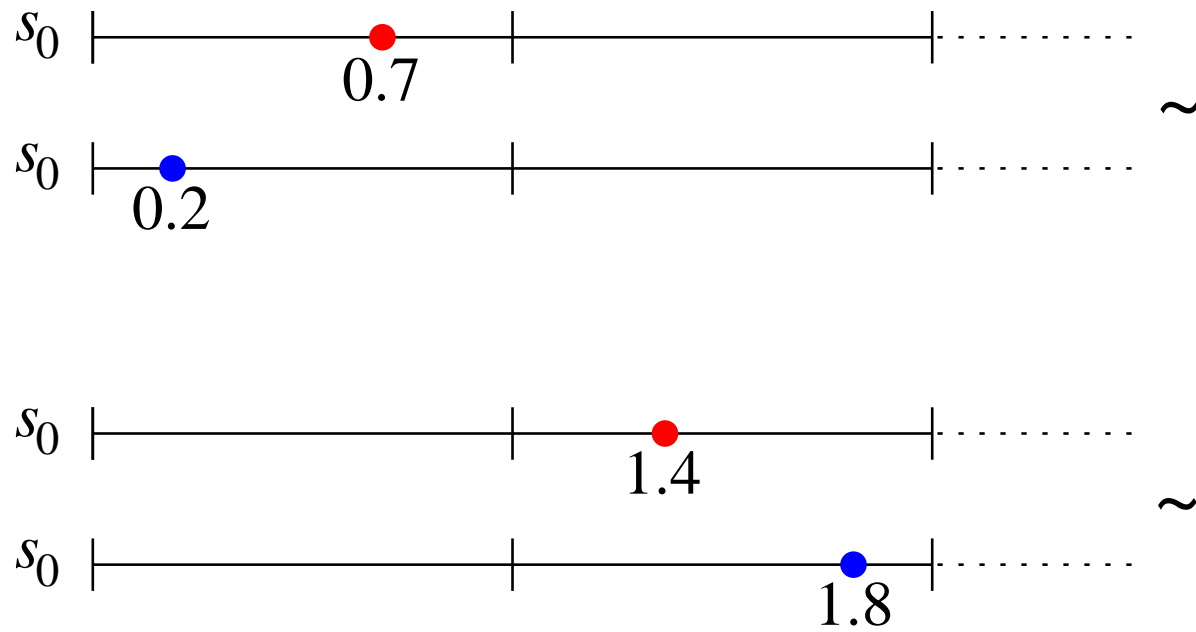




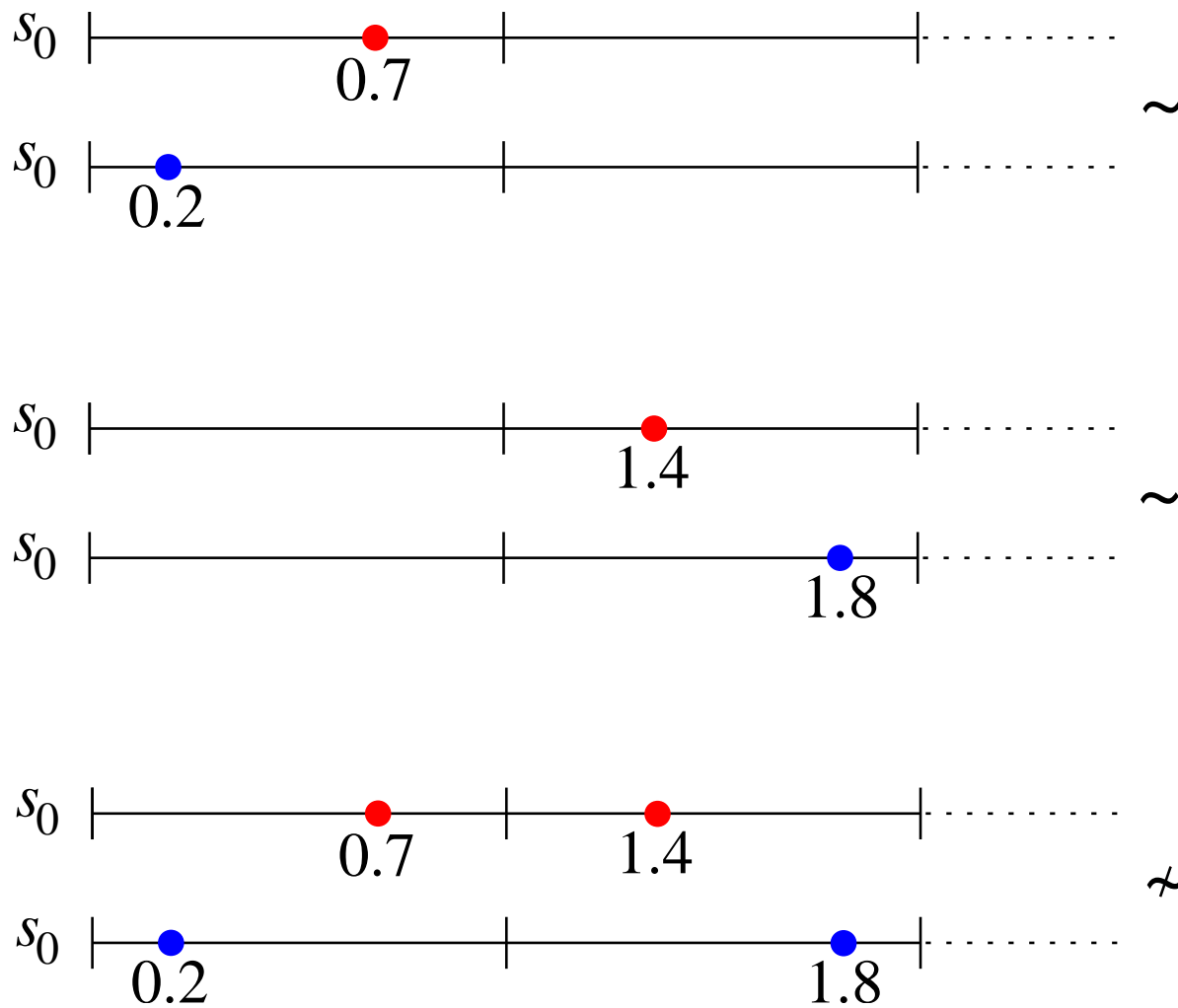
## Bisimilar Configurations: Examples



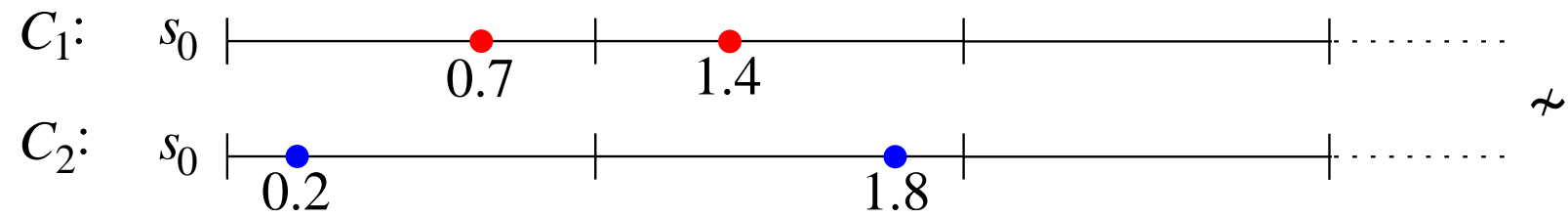
# Bisimilar Configurations: Examples



## Bisimilar Configurations: Examples



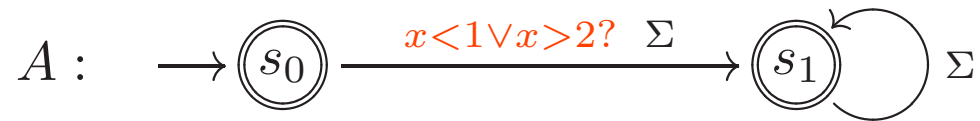
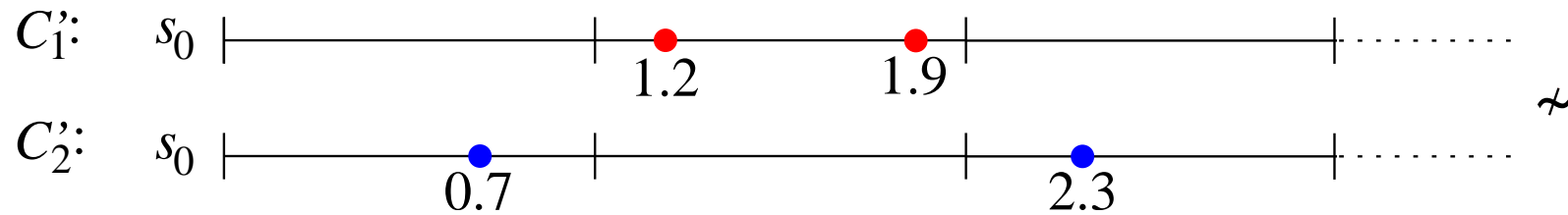
## Bisimilar Configurations: Examples







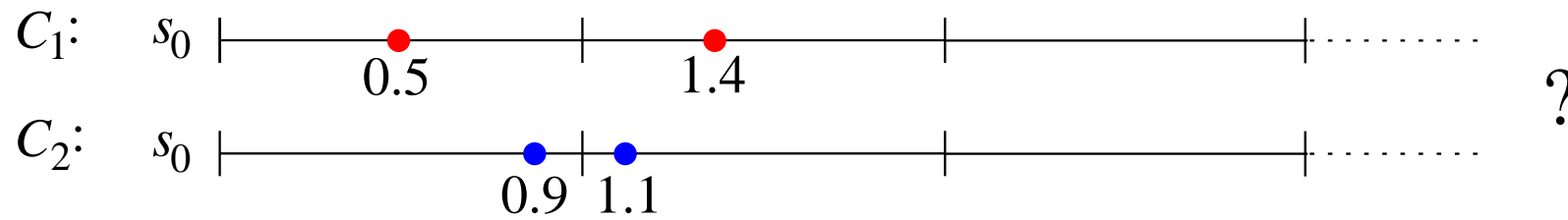
## Bisimilar Configurations: Examples



$A[C_2]$  is universal, but  $A[C_1]$  rejects  $\langle 0.5, a \rangle$ .

## Bisimilar Configurations: Examples

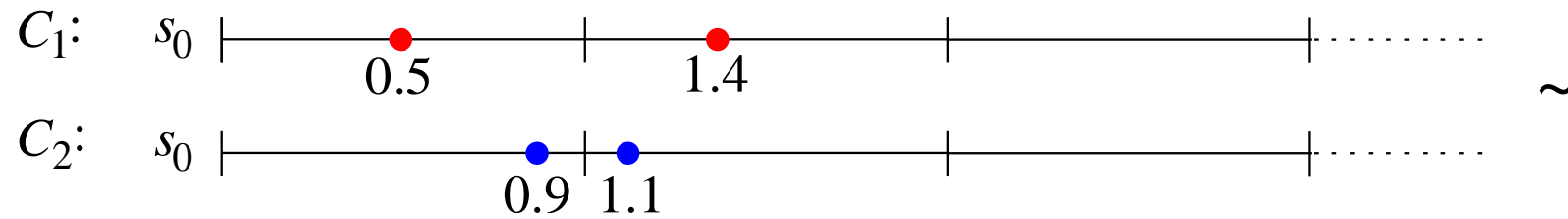
What about ...





## Bisimilar Configurations: Examples

What about ...



They **are** bisimilar:  $C_1 \sim C_2$ .

## Constructing a Decidable Bisimulation Relation

Let  $K \in \mathbb{N}$  be the largest constant appearing in clock constraints of  $A$ .

**Theorem.** Let  $C$  and  $C'$  be configurations of  $A$ .

If there exists a bijection  $f : C \rightarrow C'$  that preserves

- locations:  $f(s, v) = (s', v') \implies s = s'$ ,
- integer parts of clock  $x$ , up to  $K$ :  
$$f(s, v) = (s', v') \implies ((\lceil v \rceil = \lceil v' \rceil \wedge \lfloor v \rfloor = \lfloor v' \rfloor) \vee v, v' > K),$$
- the ordering of the fractional parts of clock  $x$ :  
$$f(s_i, v_i) = (s'_i, v'_i) \implies (v_i < v_j \iff v'_i < v'_j),$$

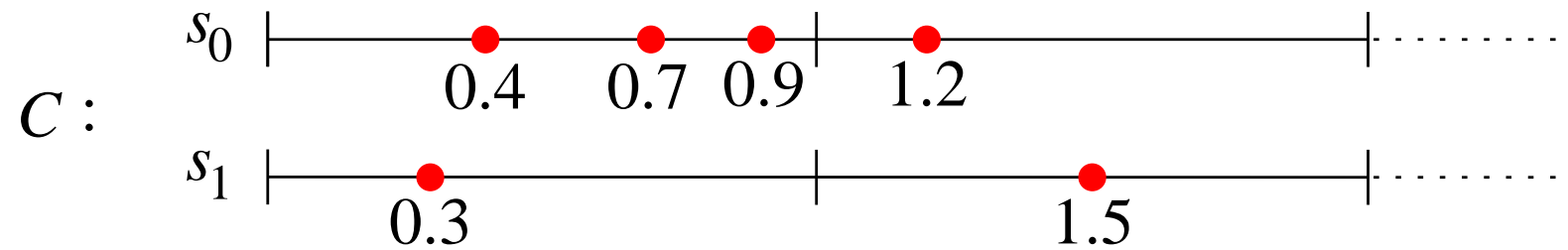
then  $C \sim C'$ .

## Constructing a Decidable Bisimulation Relation

- Let  $K$  be the largest constant appearing in clock constraints of  $A$ .
- Let  $REG = \left\{ \{0\}, (0, 1), \{1\}, (1, 2), \dots, \{K\}, (K, \infty) \right\}$  be the collection of ‘one-dimensional regions’ of  $A$ .
- Let  $S = \{s_0, s_1, \dots, s_n\}$  be the set of locations of  $A$ .
- Let  $\Lambda = S \times REG$ .
- Let  $C$  be a configuration of  $A$ . For simplicity, assume all the fractional parts of states in  $C$  are distinct.
- Note that each state in  $C$  has a unique matching letter in  $\Lambda$ .
- Encode  $C$  as a word  $H(C) \in \Lambda^*$ , ordered by increasing fractional parts of states.

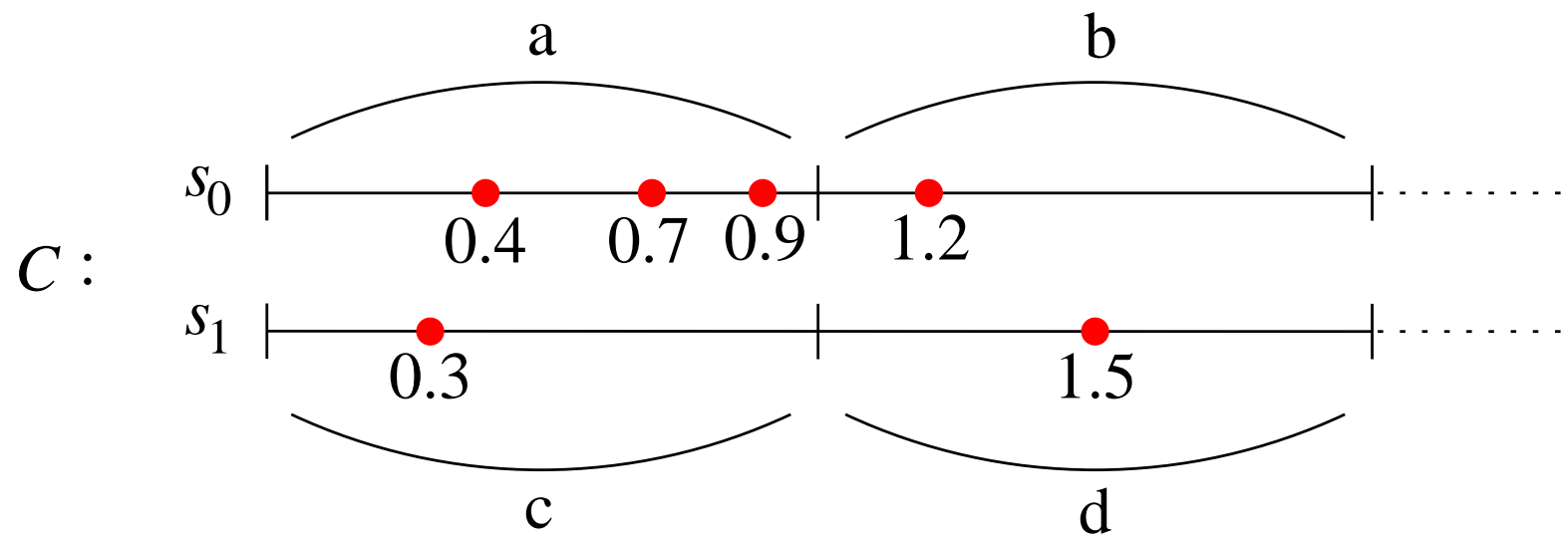
# Encoding Configurations as Words: Example

Consider the configuration  $C$ :



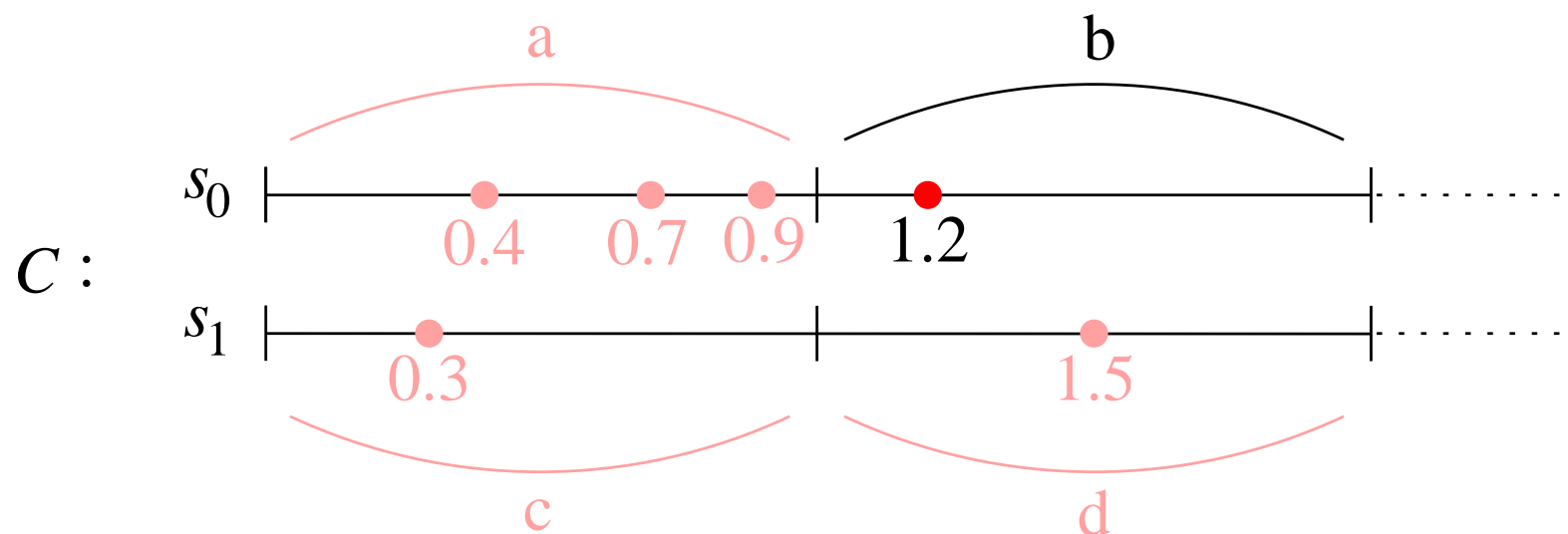
## Encoding Configurations as Words: Example

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## Encoding Configurations as Words: Example

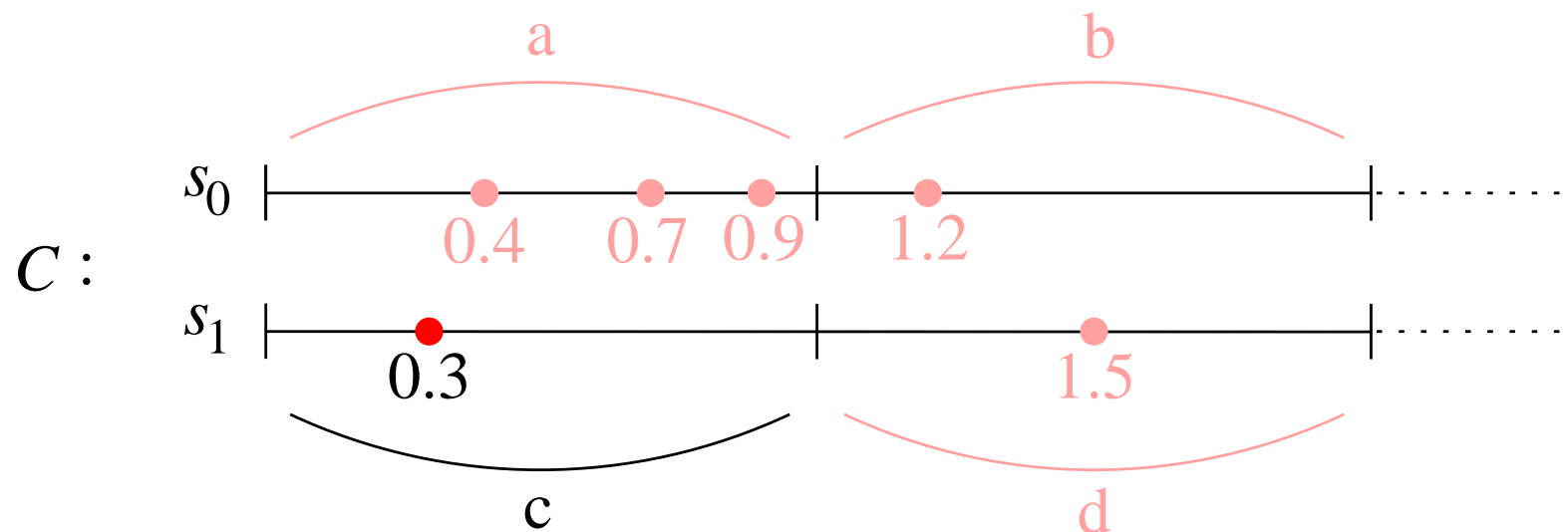
Consider the configuration  $C$ :



We encode  $C$  as  $H(C) = b \dots$

## Encoding Configurations as Words: Example

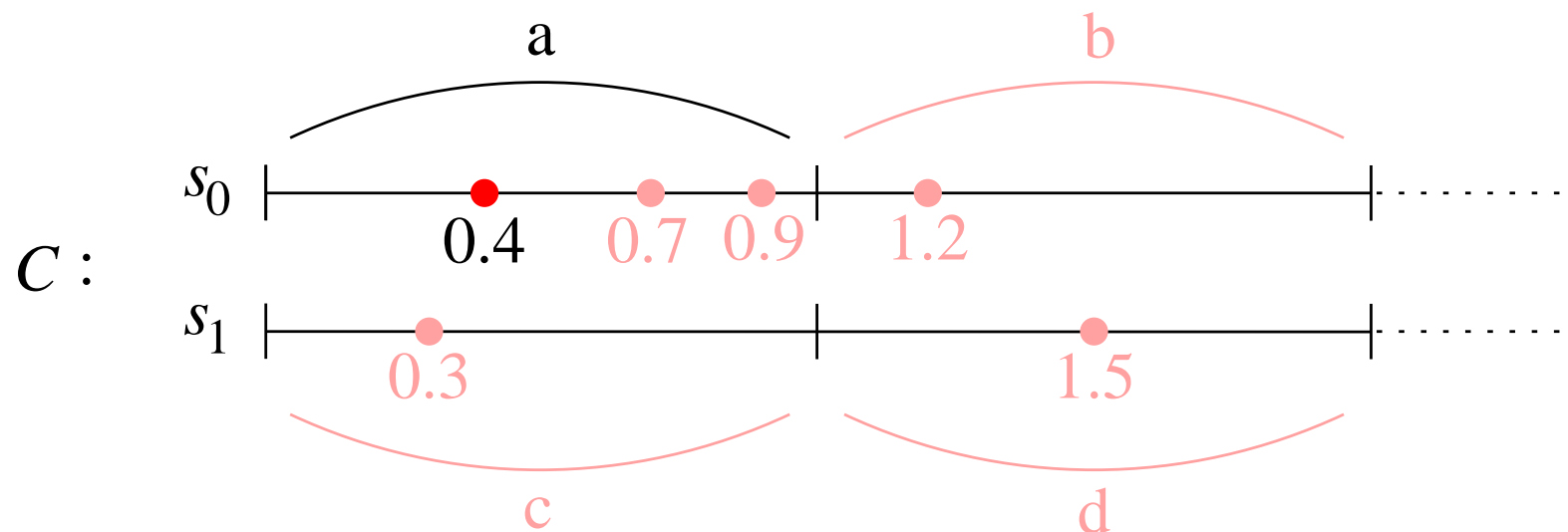
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## Encoding Configurations as Words: Example

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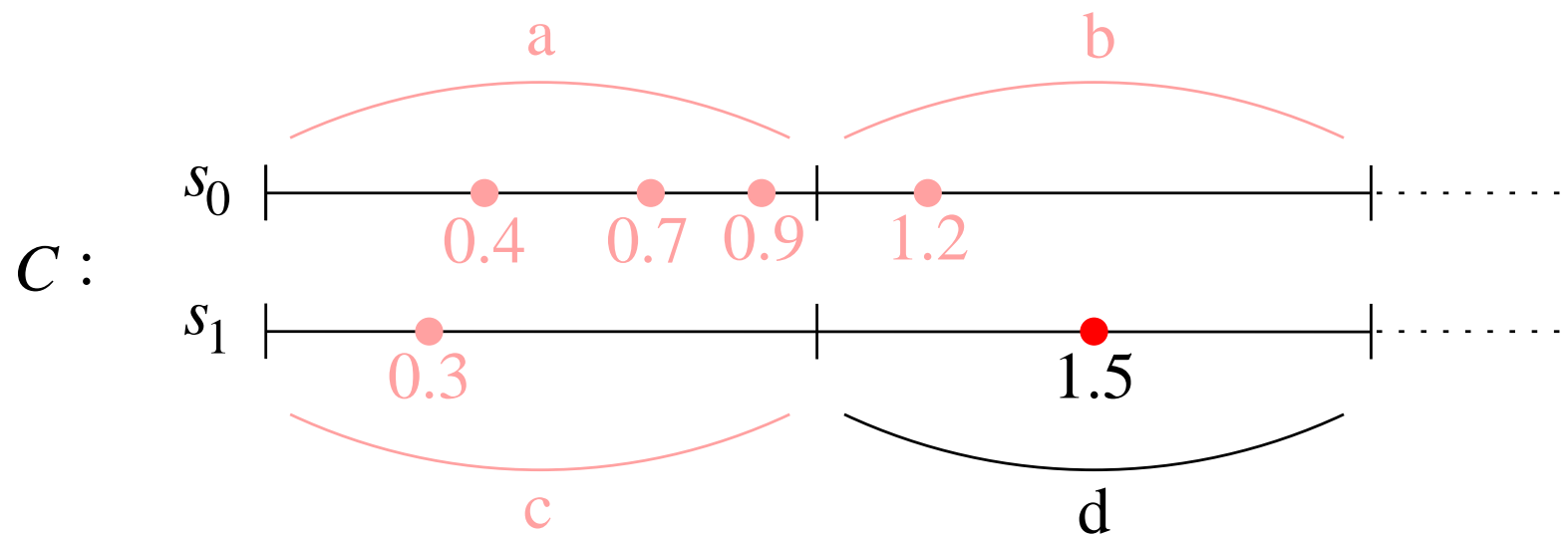


We encode  $C$  as  $H(C) = bca \dots$



## Encoding Configurations as Words: Example

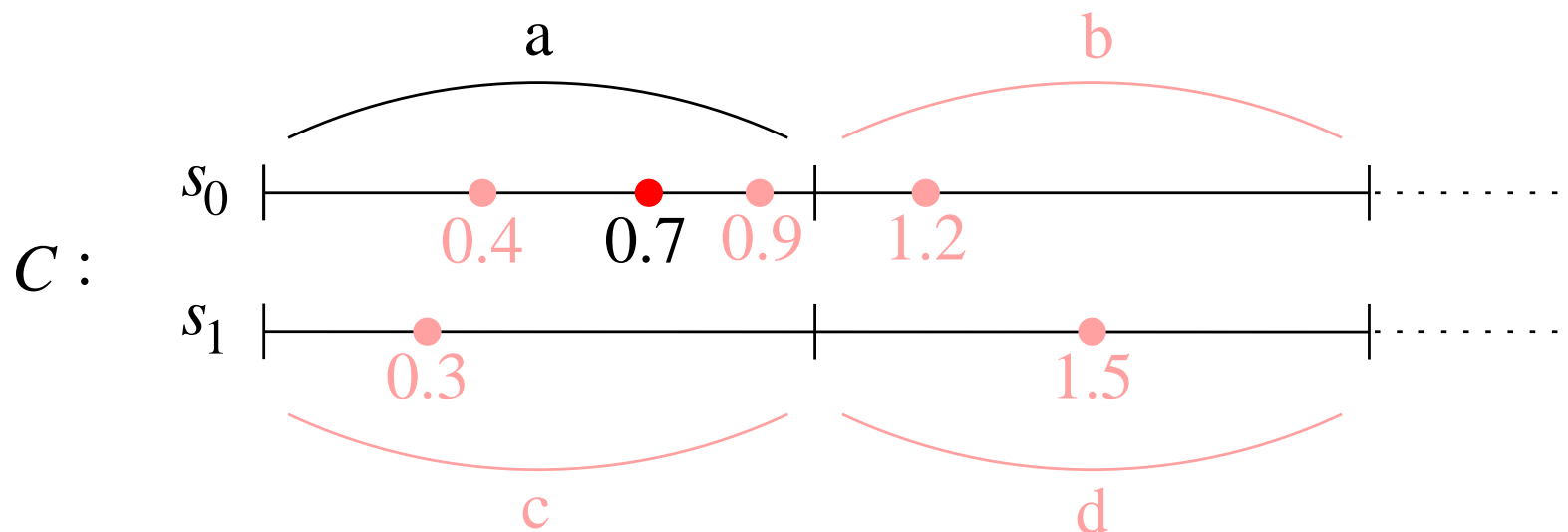
Consider the configuration  $C$ :



We encode  $C$  as  $H(C) = \text{bcad} \dots$

## Encoding Configurations as Words: Example

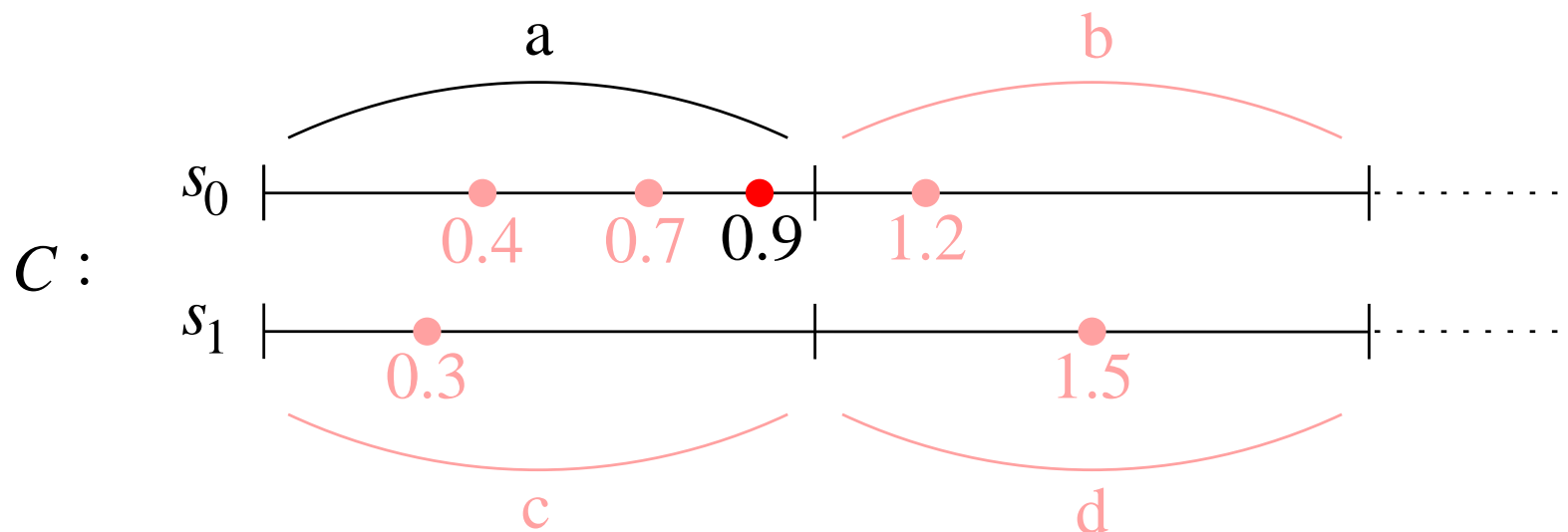
Consider the configuration  $C$ :



We encode  $C$  as  $H(C) = bcada \dots$

## Encoding Configurations as Words: Example

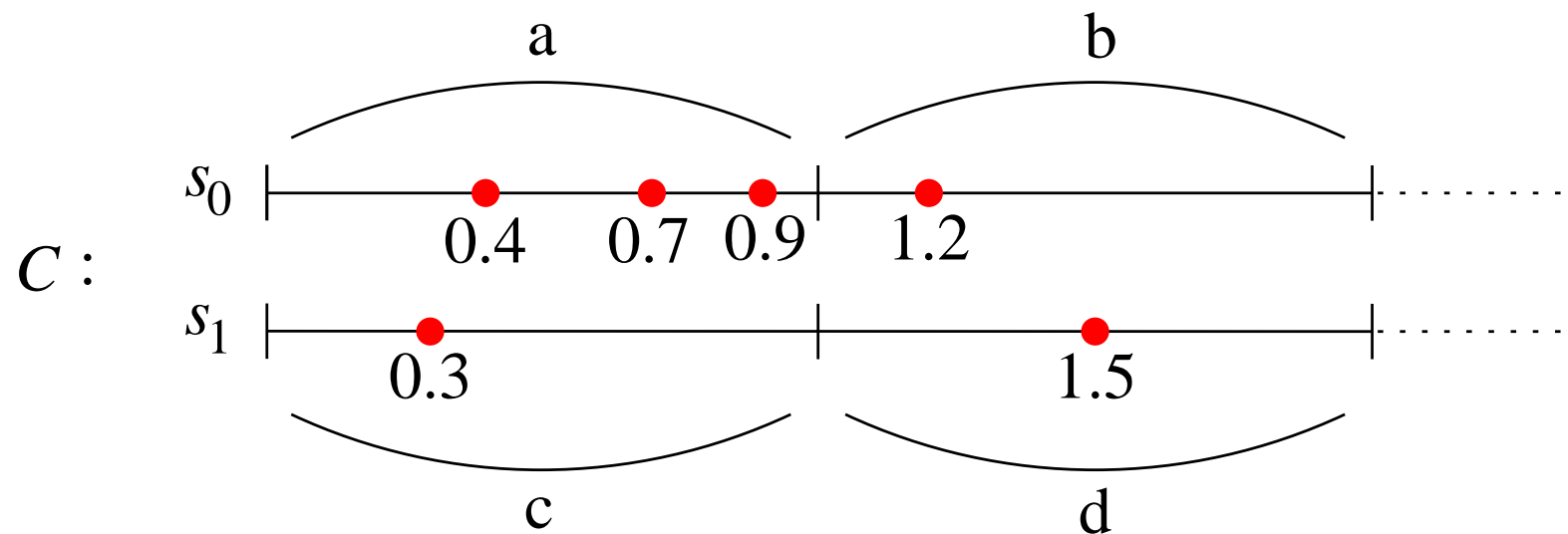
Consider the configuration  $C$ :



We encode  $C$  as  $H(C) = bcadaa$

## Encoding Configurations as Words: Example

Consider the configuration  $C$ :



We encode  $C$  as  $H(C) = bcadaa$ .

## From Bisimulation to Simulation

**Theorem.** If  $H(C) = H(C')$ , then  $C \sim C'$ .

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$A[C]$  is universal  $\iff A[C']$  is universal.

## From Bisimulation to Simulation

**Theorem.** If  $H(C) = H(C')$ , then  $C \sim C'$ .

**Corollary.** If  $H(C) = H(C')$ , then

$$A[C] \text{ is universal} \iff A[C'] \text{ is universal.}$$

**Corollary.** If  $H(C) \preceq H(C')$ , then

$$A[C] \text{ is universal} \implies A[C'] \text{ is universal.}$$

## The Algorithm: Recapitulation

- Reduce the universality question  $L(A) \stackrel{?}{=} \mathbf{TT}$  to a reachability question on an infinite graph of words.
- The subword order  $\preceq$  on this graph is a compatible well-quasi-order:
  - Whenever  $H(C) \preceq H(C')$ :  
if  $A[C]$  is universal, then  $A[C']$  is universal.
  - Any infinite sequence  $H(C_1), H(C_2), H(C_3), \dots$  eventually saturates: there exists  $i < j$  such that  $H(C_i) \preceq H(C_j)$ .
- Explore the graph, looking for a word/configuration from which  $A$  cannot perform some event. The search must eventually terminate.



## Timed Automata Language Inclusion

**Theorem.** The language inclusion problem  $L(B) \stackrel{?}{\subseteq} L(A)$  is **decidable**, provided  $A$  has at most one clock.

The complexity is **non-primitive recursive**.

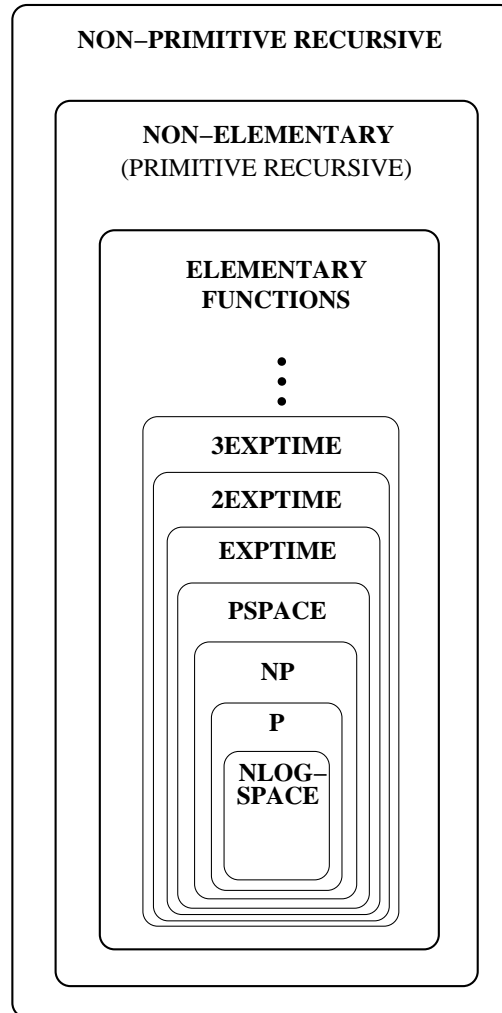
Non-primitive recursive complexity lower bound is established by reduction from reachability problem for lossy channel systems.

# Algorithmic Complexity

Emptiness/  
Reachability

UNDECIDABLE

Universality/  
Language Inclusion

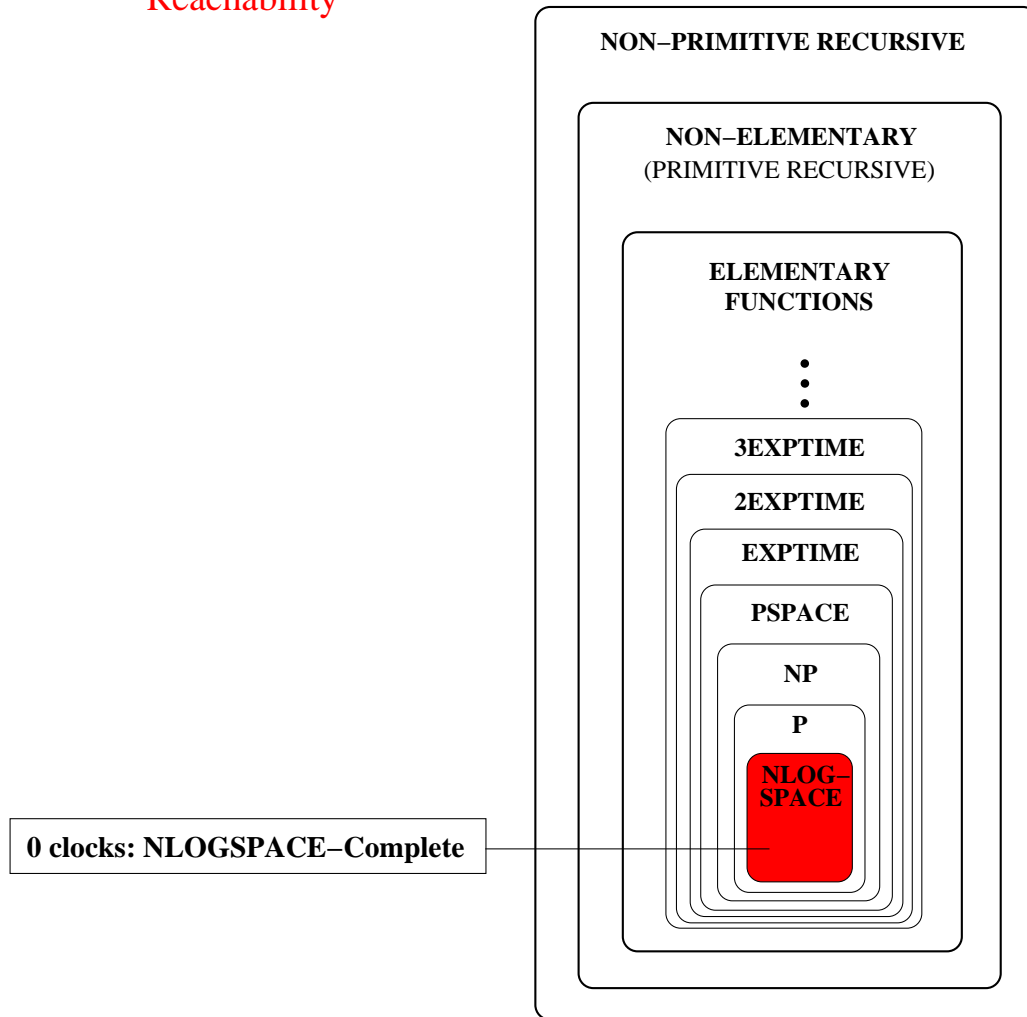


# Algorithmic Complexity

Emptiness/  
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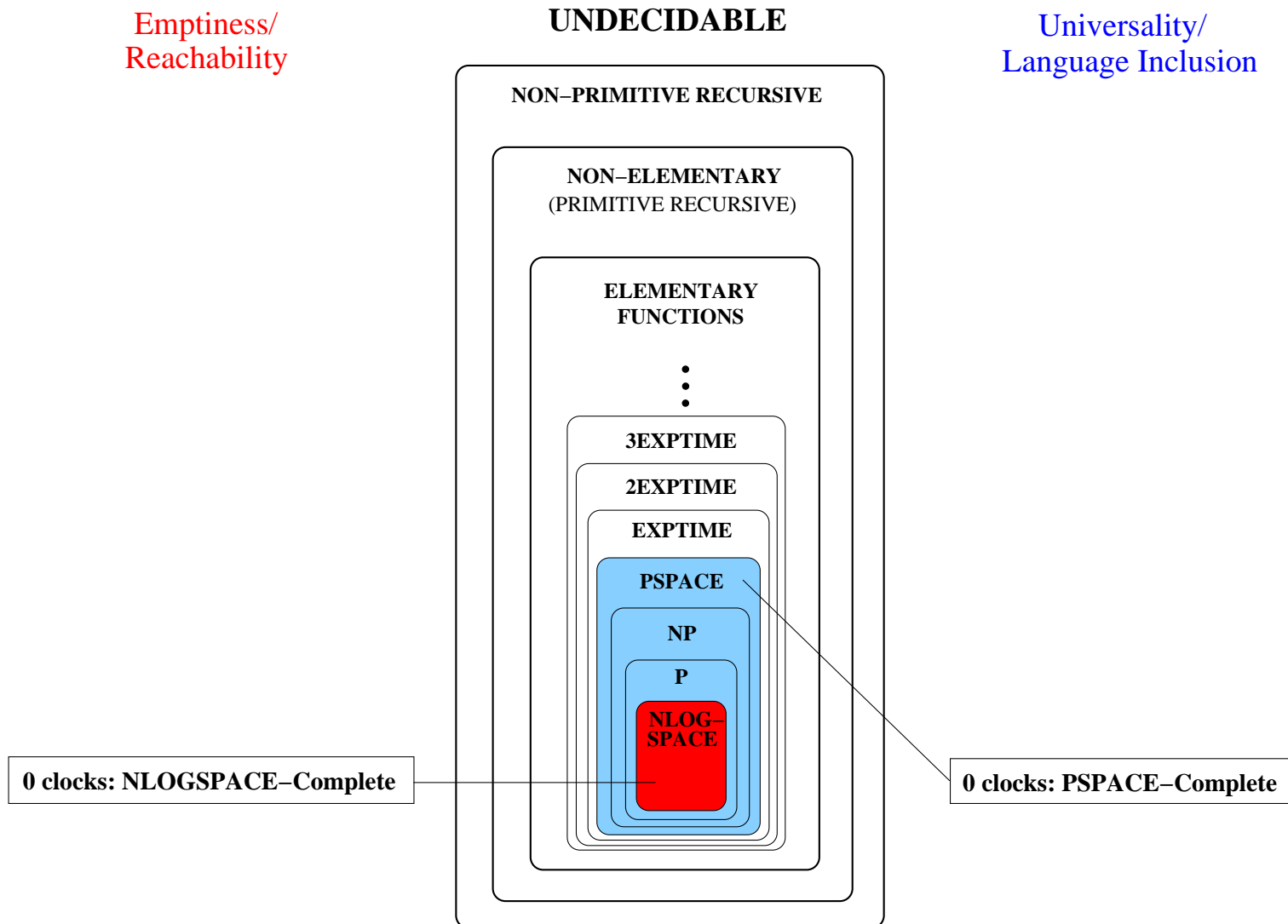
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# Algorithmic Complexity

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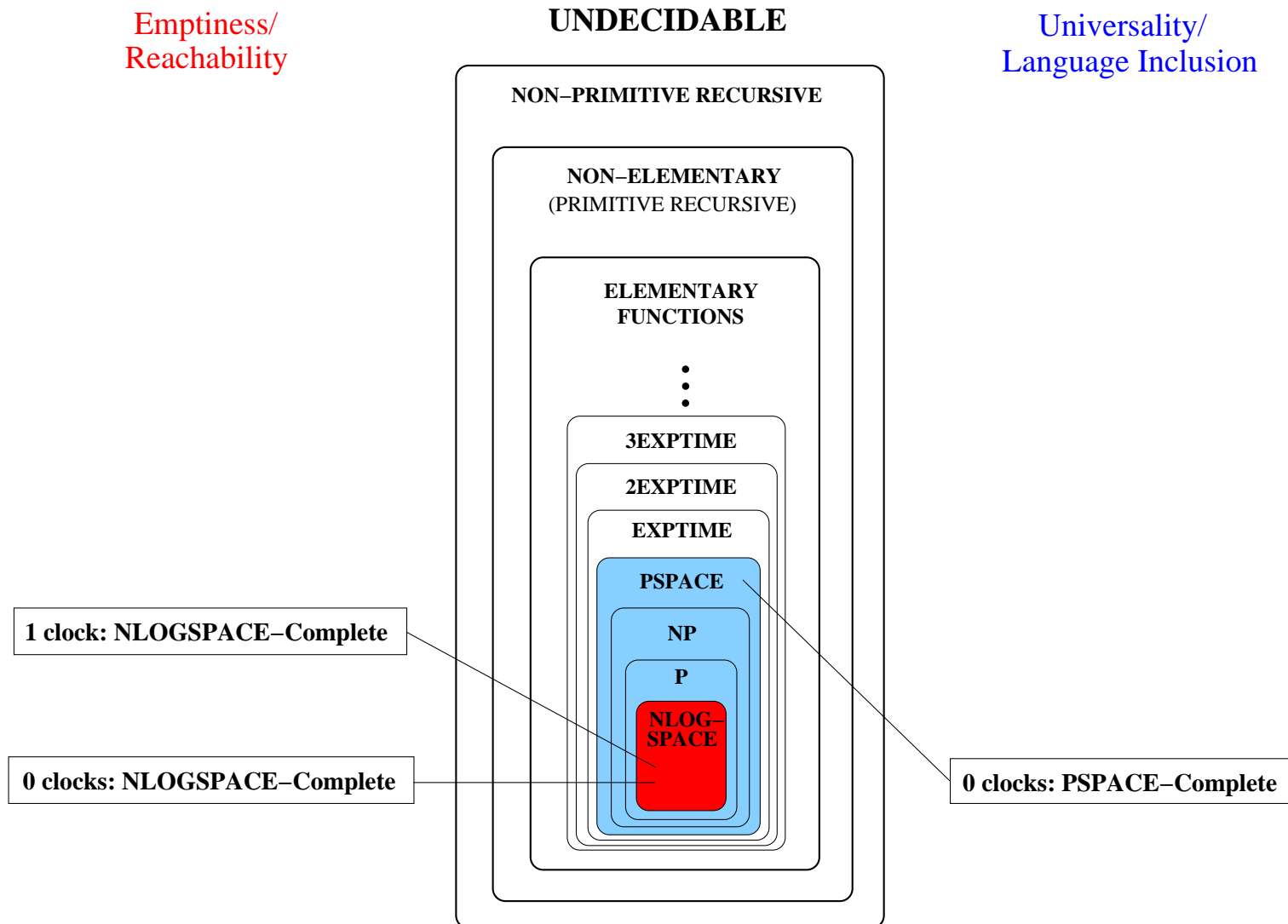
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# Algorithmic Complexity

Emptiness/  
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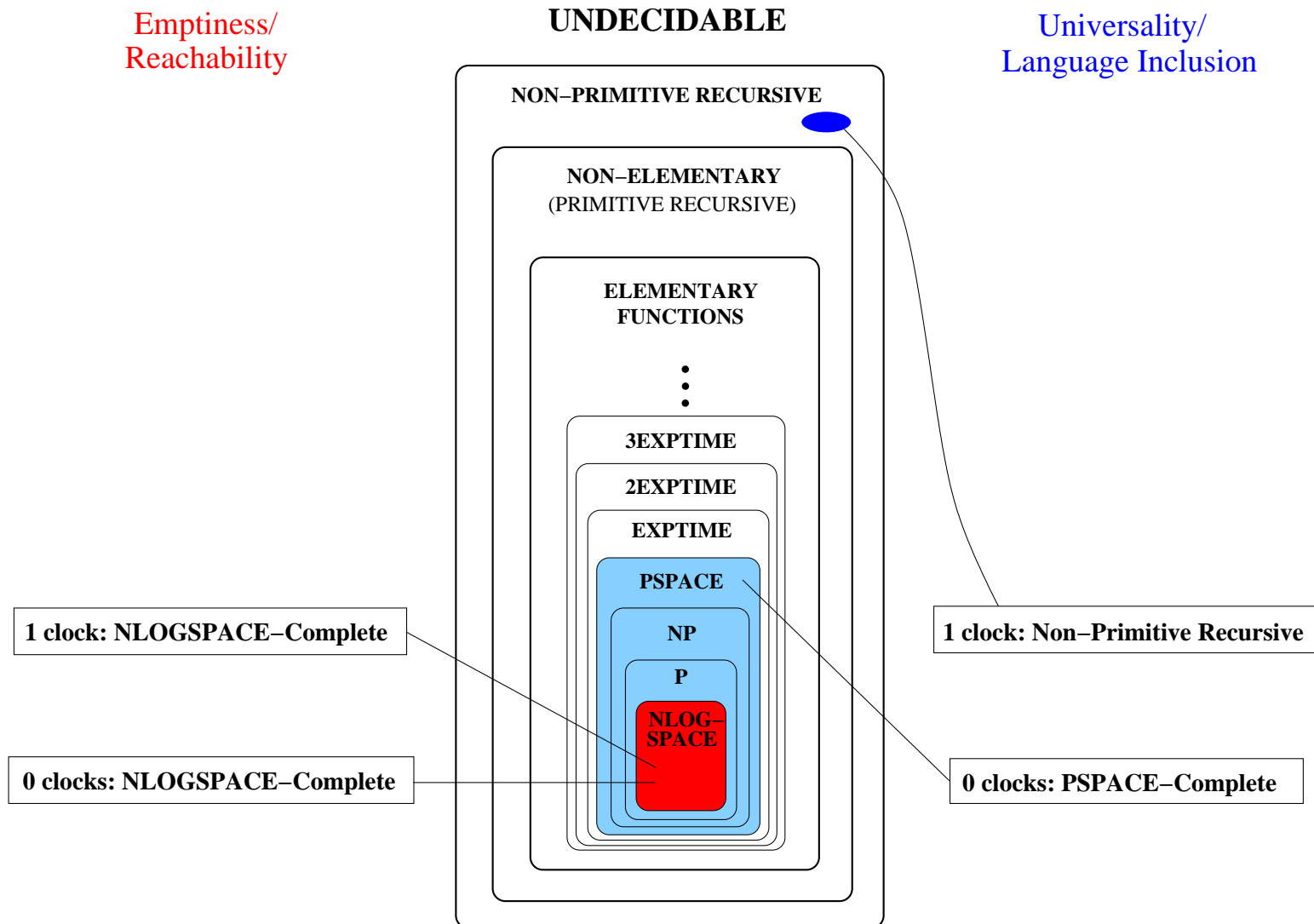
Universality/  
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# Algorithmic Complexity

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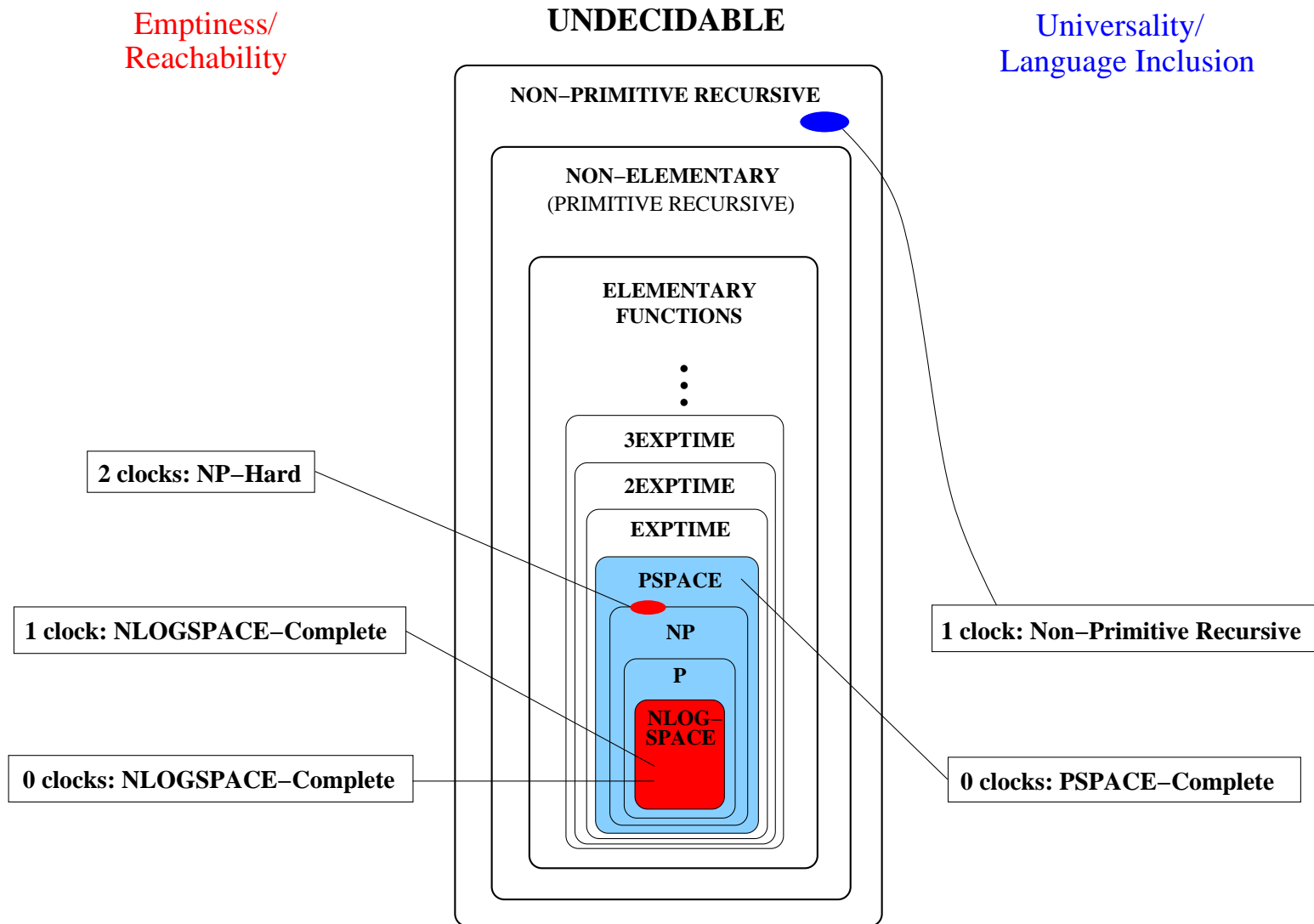
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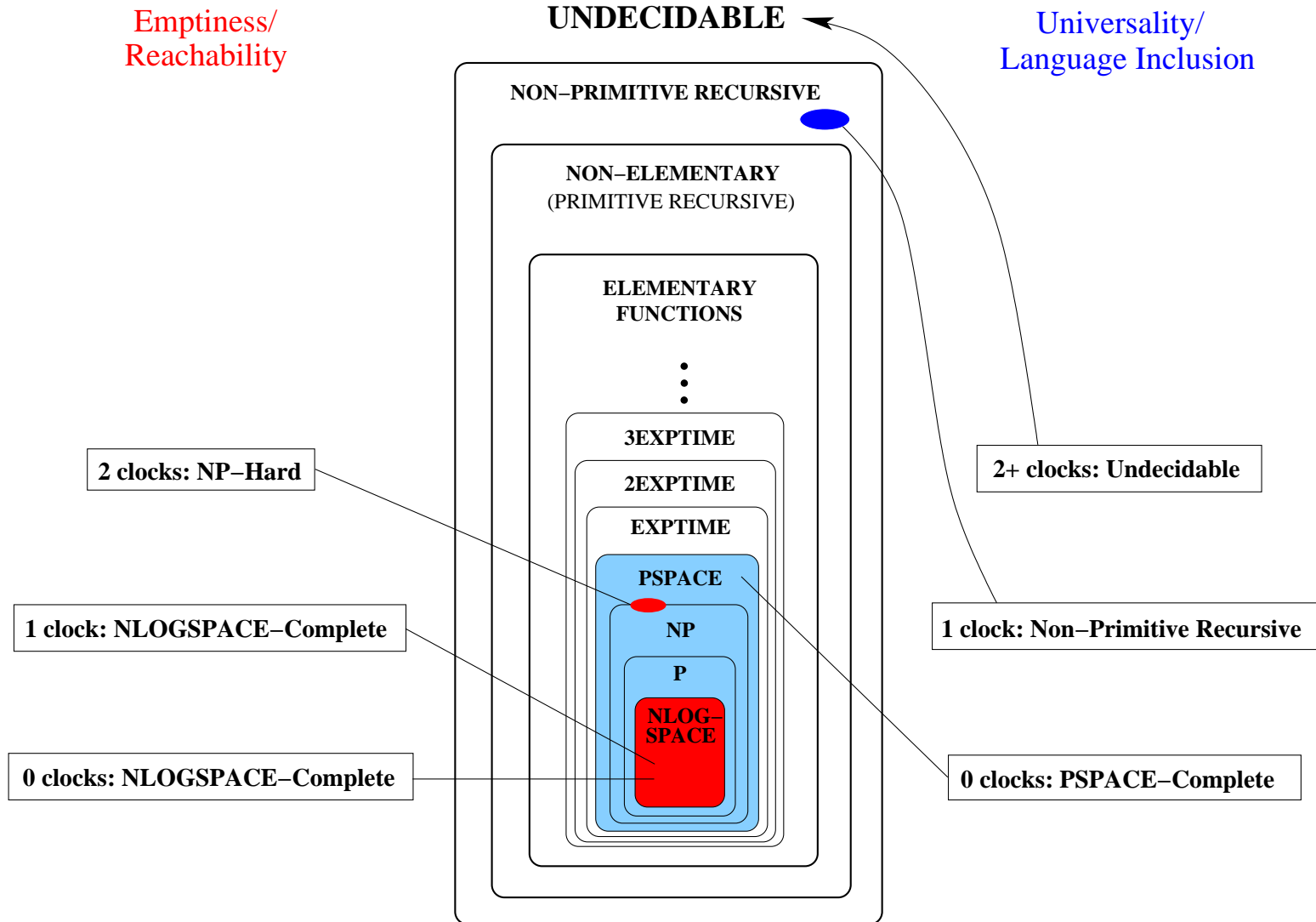
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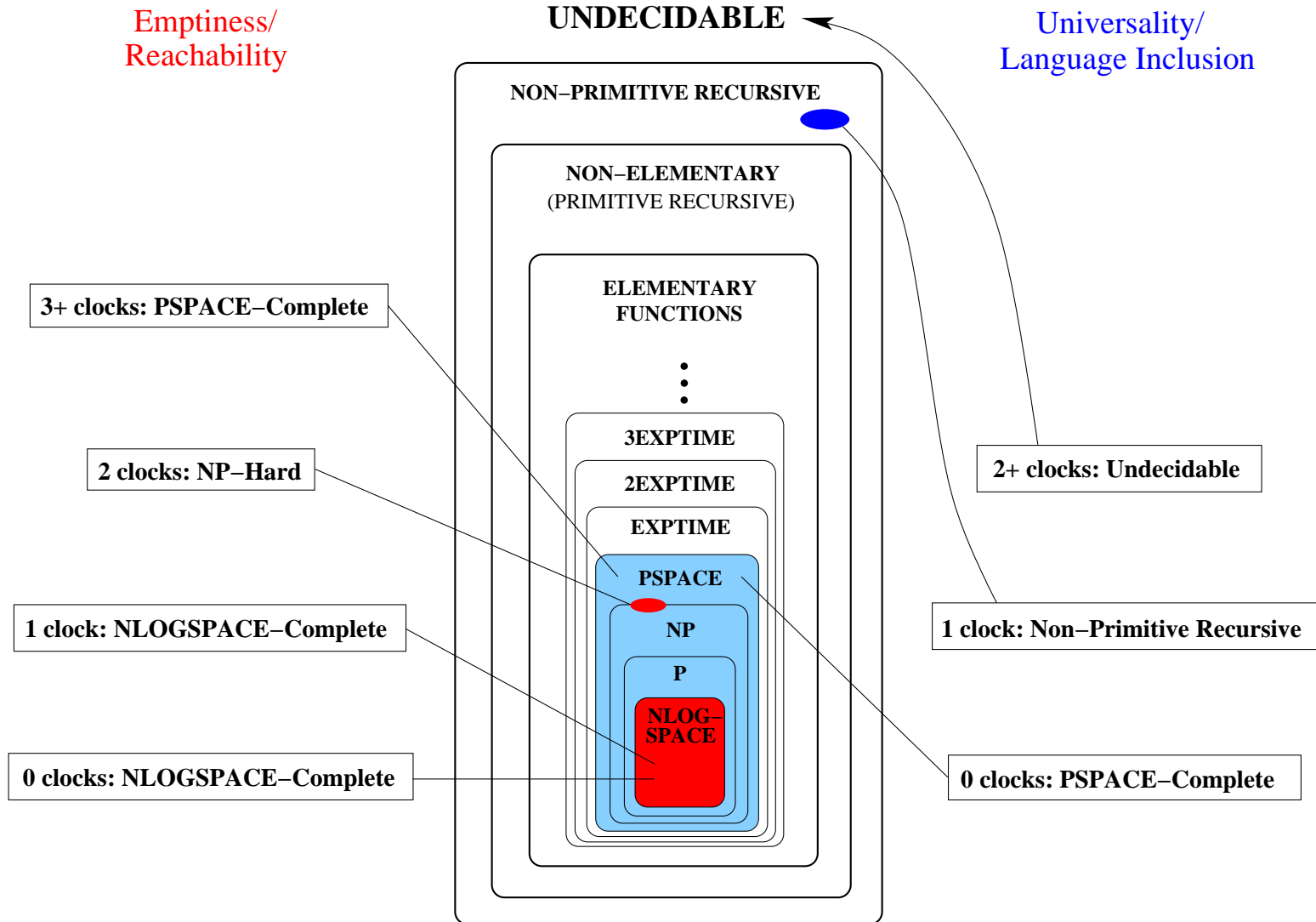


# Algorithmic Complexity





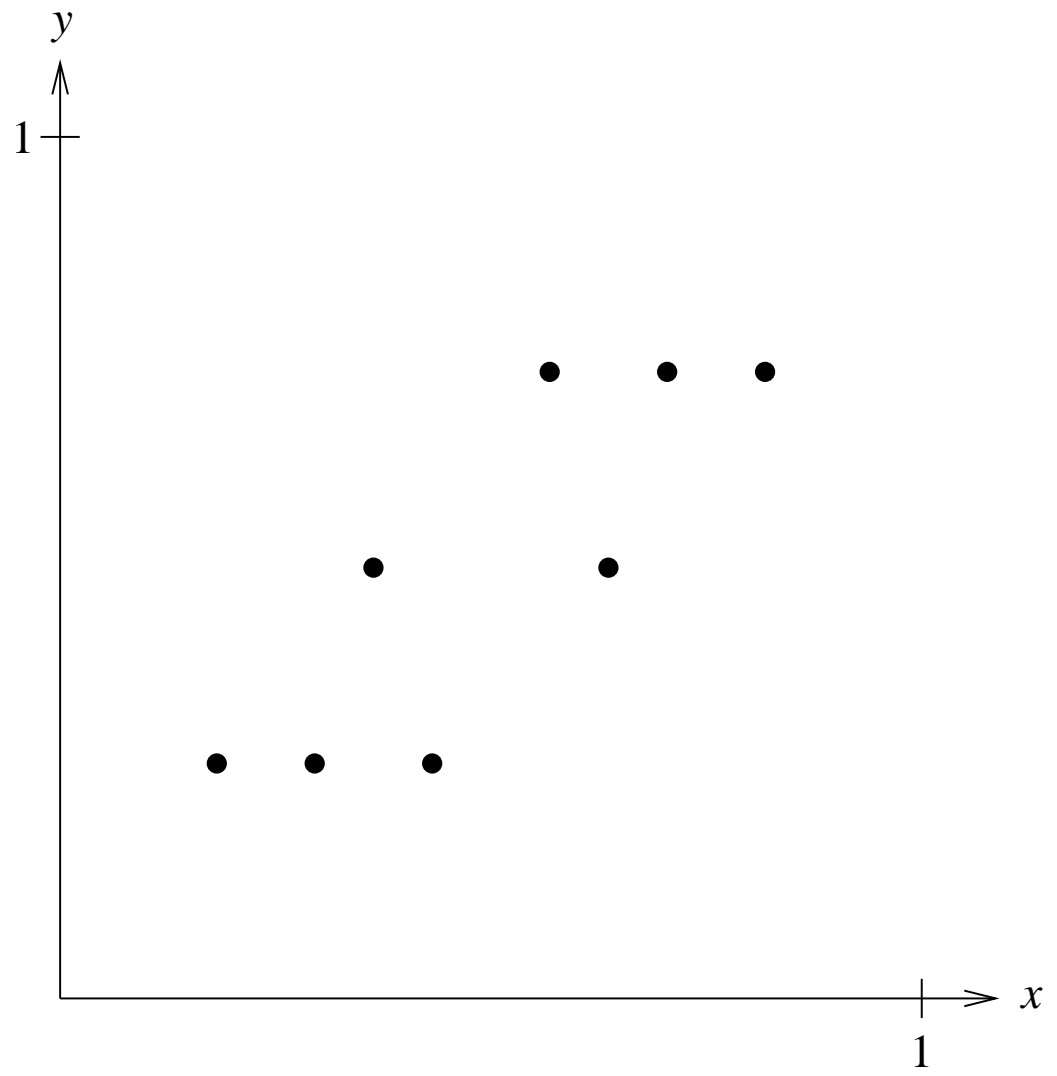
# Algorithmic Complexity



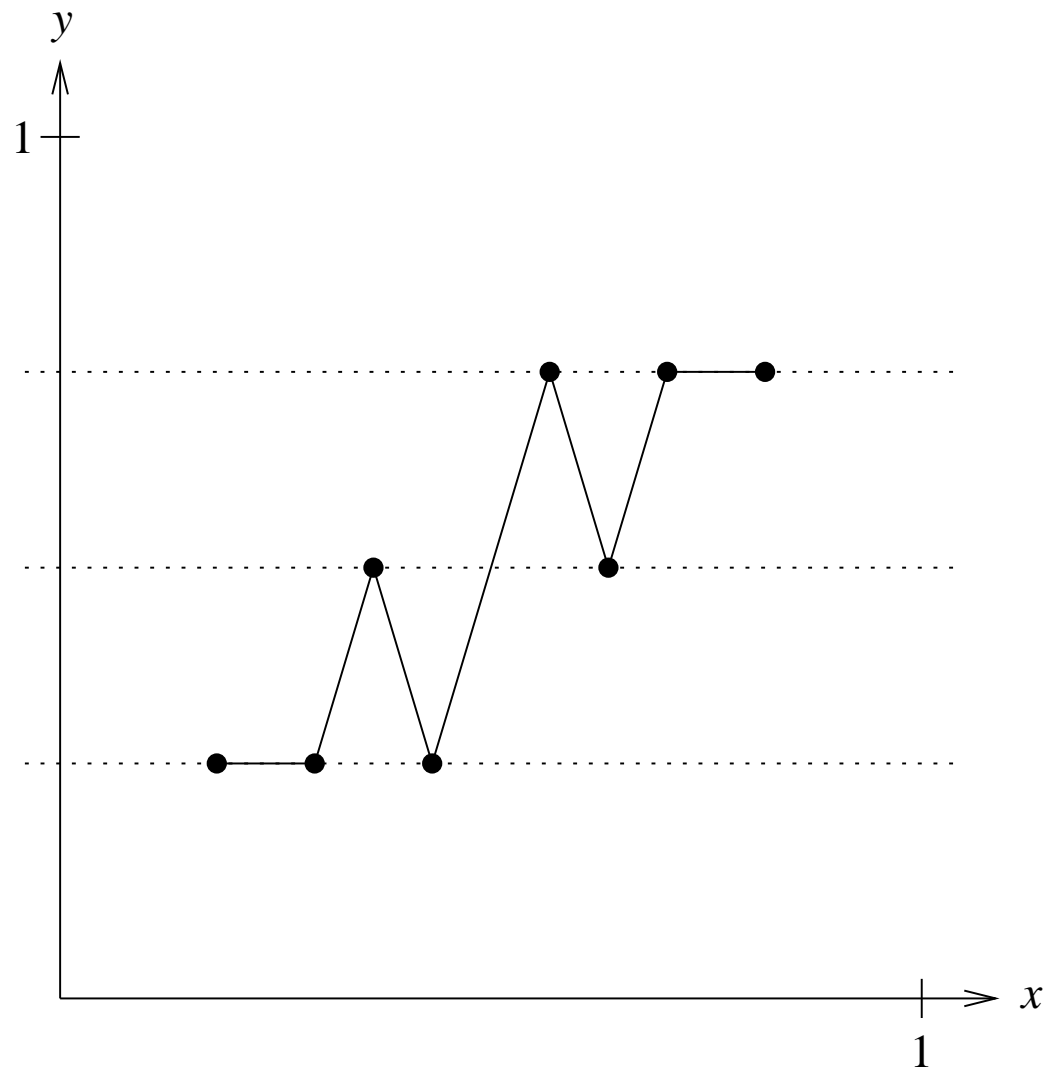
## Summary

- A single clock is surprisingly powerful ...
  - can capture simple timed functional specifications
  - can capture substantial fragments of MTL... yet still lives in a decidable world.
  
- Punctuality not *quite* as noxious as previously thought:
  - but it does take language inclusion from PSPACE to Non-Primitive Recursive!

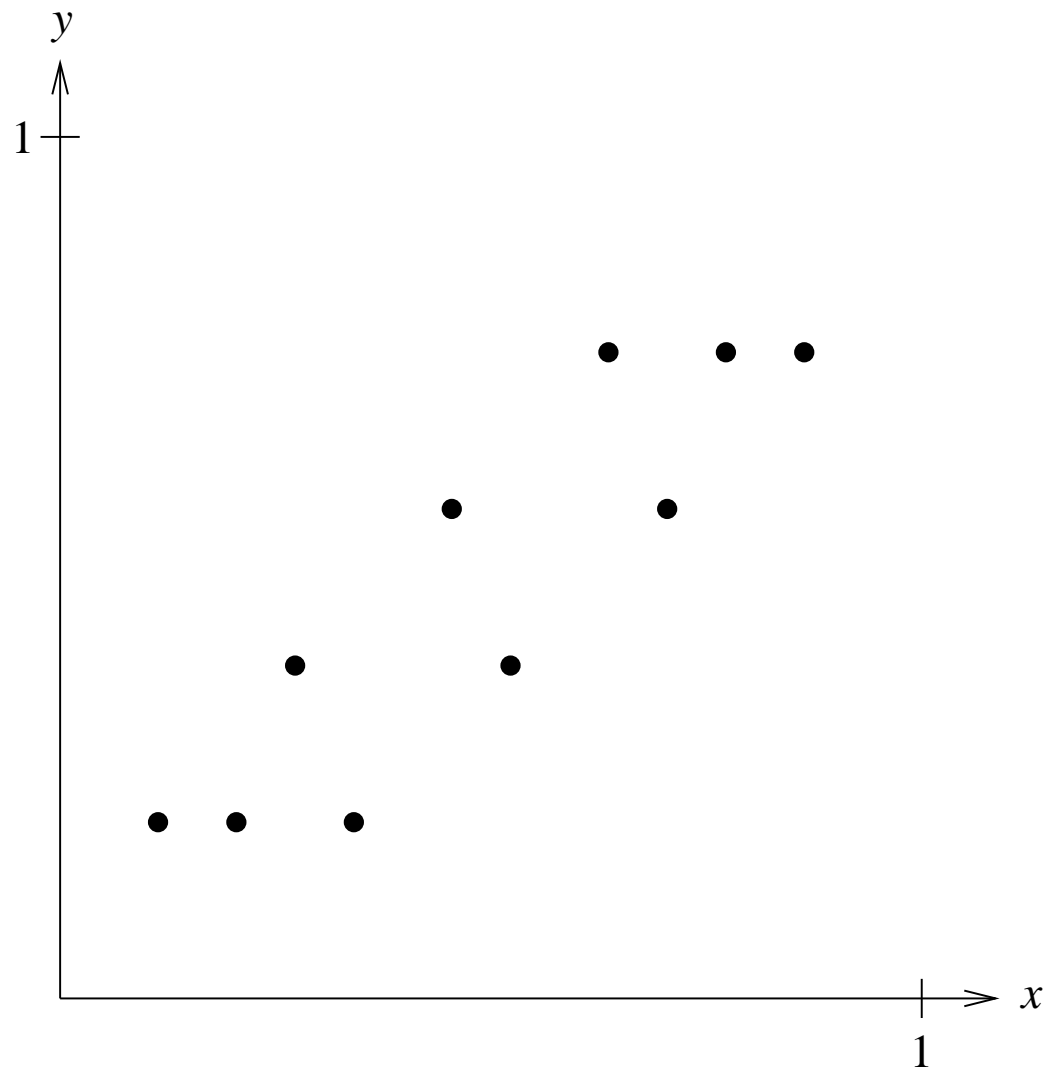
# Two Clocks: Configuration $G_3$



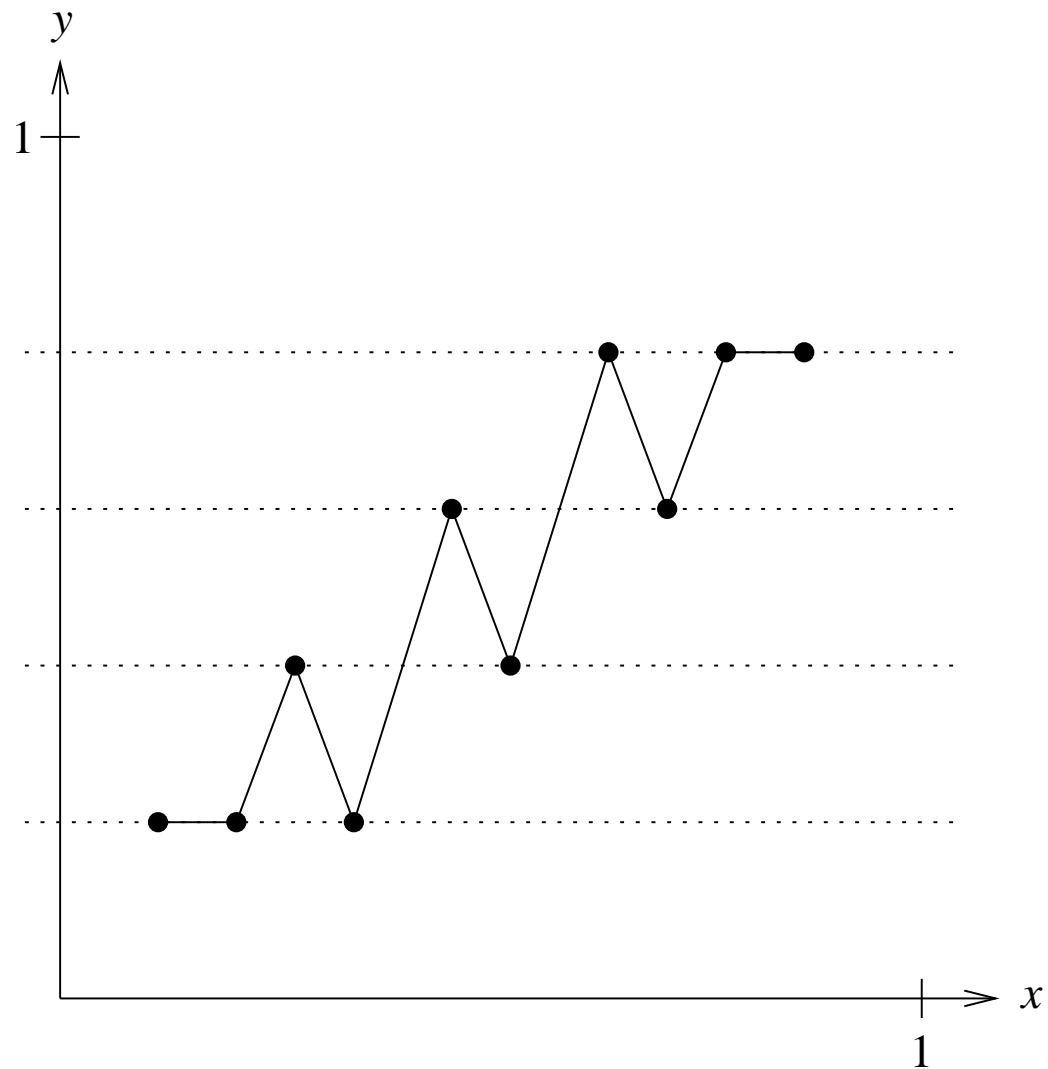
# Two Clocks: Configuration $G_3$



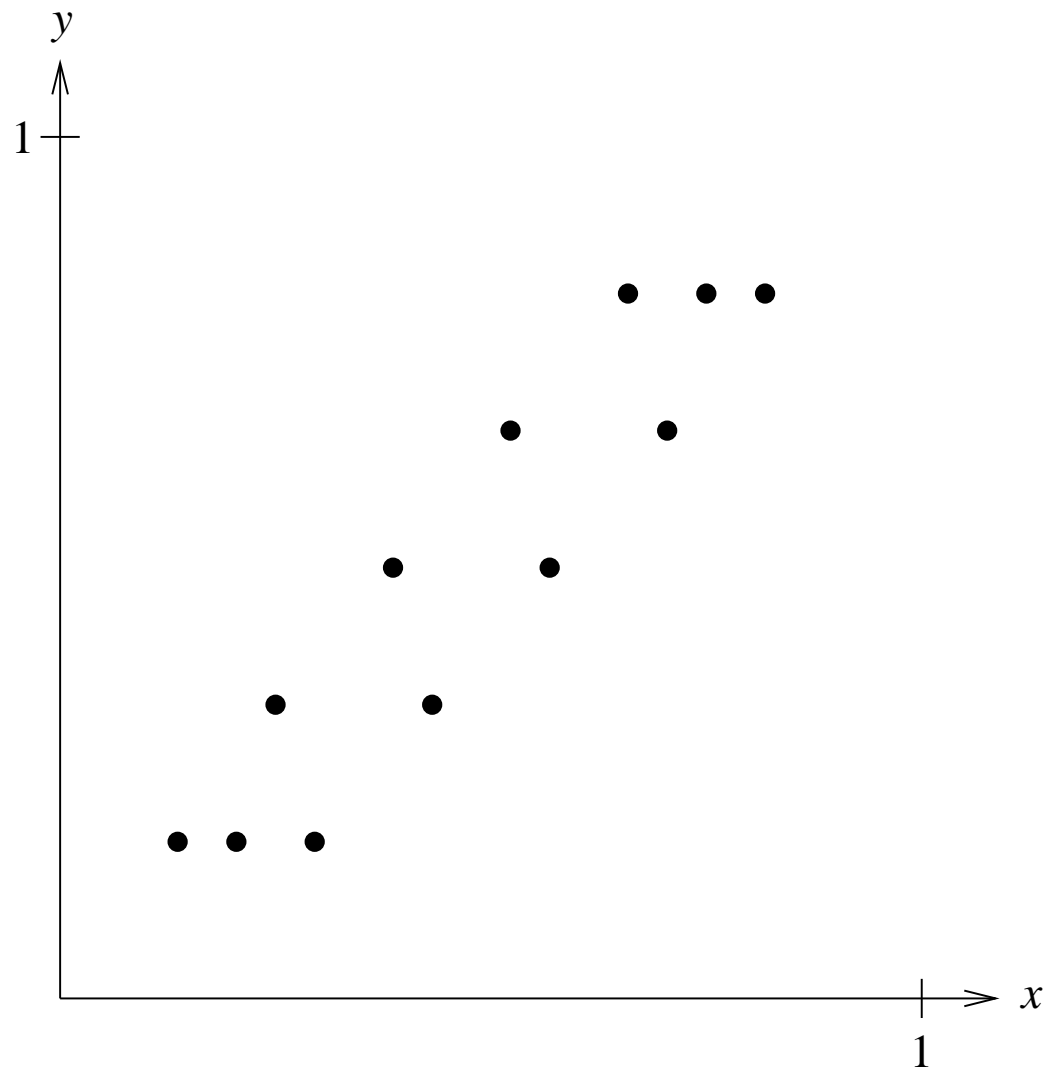
# Two Clocks: Configuration $G_4$



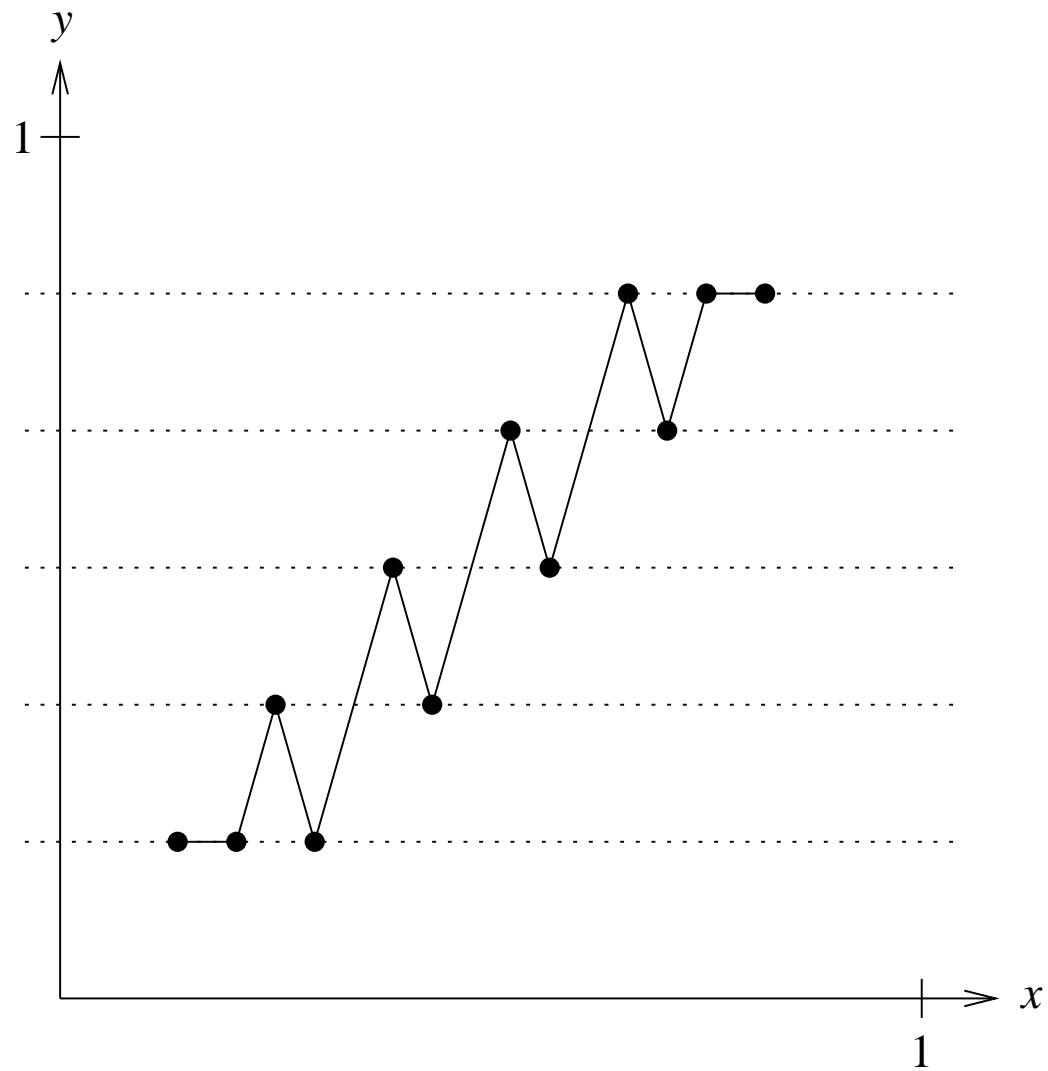
# Two Clocks: Configuration $G_4$



# Two Clocks: Configuration $G_5$



# Two Clocks: Configuration $G_5$





## Part II: Future Work

- Efficient implementation:
  - Symbolic algorithms — using better-quasi-orders?
  - Good conservative abstractions.
  - Counterexample-guided framework.
- Language inclusion when discounting the future and/or bounding time.
- Connections with lossy and insertion channel systems:
  - Logical characterization of the expressive power of one-clock timed alternating automata.

# Part IV: Time-Bounded Verification

James Worrell

Oxford University Computing Laboratory

MOVEP, July 2010

# A Long Time Ago, circa 2003...

*How about bounding time?*



*Use logic you must!*

*Timed automata still cannot be complemented!*



*I have foreseen it: everything will remain undecidable.*



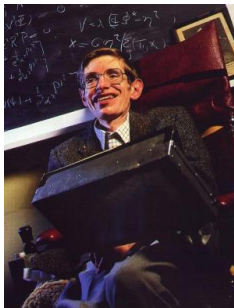
# Time-Bounded Language Inclusion

## TIME-BOUNDED LANGUAGE INCLUSION PROBLEM

**Instance:** Timed automata  $A$ ,  $B$ , and time bound  $T \in \mathbb{N}$

**Question:** Is  $L_T(A) \subseteq L_T(B)$  ?

- ▶ Inspired by Bounded Model Checking.
- ▶ Timed systems often have time bounds (e.g. timeouts), even if total number of actions is potentially unbounded.
- ▶ Universe's lifetime is believed to be bounded anyway...



# Timed Automata and Metric Logics

- ▶ Unfortunately, timed automata cannot be complemented even over bounded time. . .
- ▶ Key to solution is to **translate problem into logic**: Behaviours of timed automata can be captured in  $\text{MSO}(<, +1)$  (in fact, even in  $\exists\text{MTL}$  [Henzinger, Raskin, Schobbens 1998]).
- ▶ This reverses Vardi's 'automata-theoretic approach to verification' paradigm!



# Monadic Second-Order Logic

More problems:

Theorem (Shelah 1975)

*$MSO(<)$  is undecidable over  $[0, 1)$ .*



By contrast,

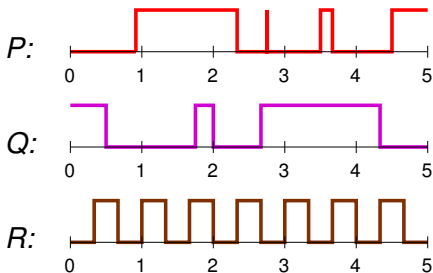
Theorem

- ▶  *$MSO(<)$  is decidable over  $\mathbb{N}$  [Büchi 1960]*
- ▶  *$MSO(<)$  is decidable over  $\mathbb{Q}$ , via [Rabin 1969]*

# Finite Variability

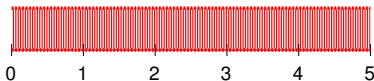
Timed behaviours are modelled as **flows** (or **signals**):

$$f : [0, T) \rightarrow 2^{\text{MP}}$$



Predicates must have **finite variability**:

Disallow e.g.  $\mathbb{Q}$ :



Then:

**Theorem (Rabinovich 2002)**

*MSO( $<$ ) satisfiability over finitely-variable flows is decidable.*

# The Time-Bounded Theory of Verification

## Theorem

*For any fixed bounded time domain  $[0, T)$ , the satisfiability and model-checking problems for  $MSO(<, +1)$ ,  $FO(<, +1)$ , and  $MTL$  are all decidable, with the following complexities:*

<i><math>MSO(&lt;, +1)</math></i>	<i>NON-ELEMENTARY</i>
<i><math>FO(&lt;, +1)</math></i>	<i>NON-ELEMENTARY</i>
<i><math>MTL</math></i>	<i>EXPSPACE-complete</i>

## Theorem

*$MTL$  and  $FO(<, +1)$  are equally expressive over any fixed bounded time domain  $[0, T)$ .*

## Theorem

*Given timed automata  $A, B$ , and time bound  $T \in \mathbb{N}$ , the language inclusion problem  $L_T(A) \subseteq L_T(B)$  is decidable and  $2EXPSPACE$ -complete.*



# Time-Bounded Language Inclusion

- ▶ Let timed automata  $A$ ,  $B$ , and time bound  $T$  be given.
- ▶ Define formula  $\varphi_A^{\text{acc}}(\mathbf{W}, \mathbf{P})$  in  $\text{MSO}(<, +1)$  such that:

$A$  accepts timed word  $w \iff \varphi_A^{\text{acc}}(\mathbf{W}, \mathbf{P})$  holds

where

- ▶  $\mathbf{W}$  encodes  $w$
- ▶  $\mathbf{P}$  encodes a corresponding run of  $A$ .
- ▶ Define likewise  $\varphi_B^{\text{acc}}(\mathbf{W}, \mathbf{Q})$  for timed automaton  $B$ .
- ▶ Then  $L_T(A) \subseteq L_T(B)$  iff:

$$\forall \mathbf{W} \forall \mathbf{P} (\varphi_A^{\text{acc}}(\mathbf{W}, \mathbf{P}) \rightarrow \exists \mathbf{Q} \varphi_B^{\text{acc}}(\mathbf{W}, \mathbf{Q}))$$

holds over time domain  $[0, T)$ .

- ▶ This can be decided in 2EXPSpace.

# MSO( $<, +1$ ) Time-Bounded Satisfiability

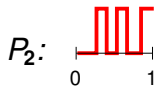
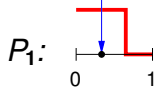
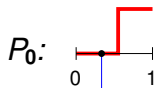
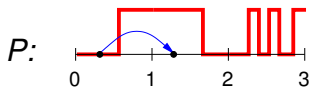
Key idea: **eliminate the metric by 'vertical stacking'**.

- ▶ Let  $\varphi$  be an MSO( $<, +1$ ) formula and let  $T \in \mathbb{N}$ .
- ▶ Construct an MSO( $<$ ) formula  $\bar{\varphi}$  such that:

$\varphi$  is satisfiable over  $[0, T)$   $\iff$   $\bar{\varphi}$  is satisfiable over  $[0, 1)$

- ▶ Conclude by invoking decidability of MSO( $<$ ).

# From MSO( $\langle, +1$ ) to MSO( $\langle$ )



## Replace every:

▶  $\forall x \psi(x)$  **by**  $\forall x (\psi(x) \wedge \psi(x+1) \wedge \psi(x+2))$

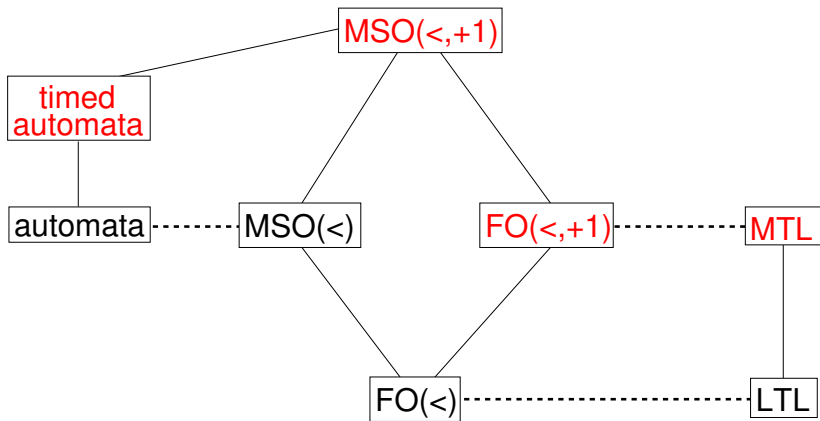
▶  $x + k_1 < y + k_2$  **by**  $\begin{cases} x < y & \text{if } k_1 = k_2 \\ \text{true} & \text{if } k_1 < k_2 \\ \text{false} & \text{if } k_1 > k_2 \end{cases}$

▶  $P(x+k)$  **by**  $P_k(x)$

▶  $\forall P \psi$  **by**  $\forall P_0 \forall P_1 \forall P_2 \psi$

Then  $\varphi$  is satisfiable over  $[0, T)$   $\iff \bar{\varphi}$  is satisfiable over  $[0, 1)$ .

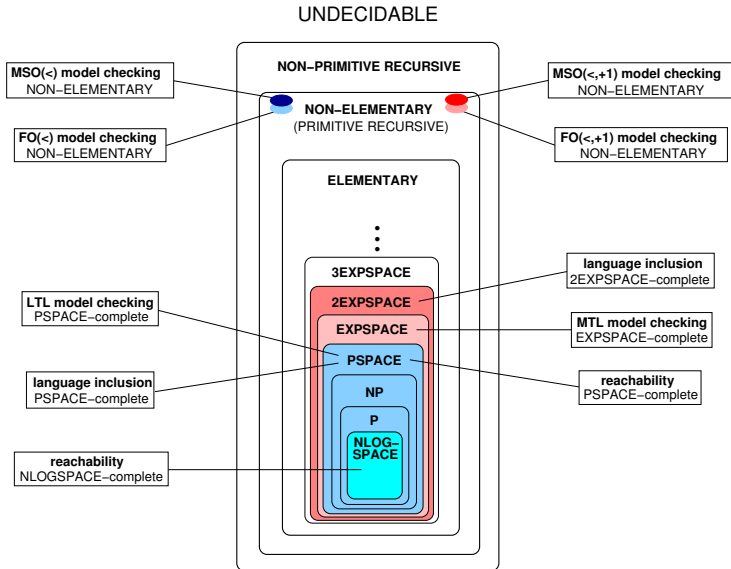
# The Time-Bounded Theory: Expressiveness



# The Time-Bounded Theory: Complexity

## Classical Theory

## Time-Bounded Theory



## Part IV: Conclusion

- ▶ For specifying and verifying real-time systems, the time-bounded theory is much better behaved than the real-time theory.
- ▶ Original motivation for this work was the time-bounded language inclusion problem for timed automata. We used logic as a tool to solve this problem.

**Thank you for your attention!**