

Presburger Arithmetic And Verification of Infinite State Systems

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An Infinite State System

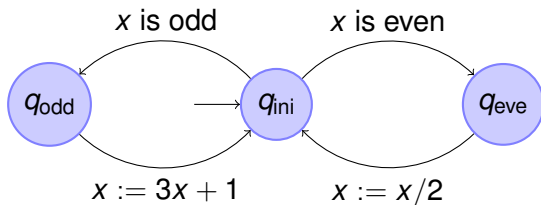


Figure: Syracuse

In this presentation, we consider counter systems:

- A finite set of counter variables.
- A finite control structure (a finite graph).
- Labelled with actions manipulating the variable contents.

Good model:

- C programs, expect system calls, heap manipulations, recursive calls, floating point arithmetic operations...
- C programs manipulating linked data structures [BBH⁺06].
- Abstraction of communicating processes [BCR01], [BMWK09].

The safety verification problem

Input : An initial and a final configuration.

Decide : if the final configuration is reachable from the initial one.

Some remarks:

- The problem is recursively-countable : we prove the reachability with a path.
- The problem is not recursive : we prove the non-reachability with an inductive invariant that contains the initial configuration but not the final configuration.

The big problem:

- Find out a “good” logic (expressive, decidable) to express invariants.
- Find out a way for computing an invariant in this logic.

Outline

- 1 Presburger Arithmetic
- 2 Formulas to Automata
- 3 Automata to Formulas
- 4 Presburger Counter Systems Reachability Problem
- 5 Conclusion

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Grammar

FO ($\mathbb{N}, +, 0, 1$)

Let X be a countable set of variables.

Definition (Presburger Formulas)

$t := 0 \mid 1 \mid x \mid t_1 + t_2$

$p := t_1 = t_2 \mid \top \mid \perp$

$\phi := p \mid \neg\phi \mid \phi_1 \vee \phi_2 \mid \phi_1 \wedge \phi_2 \mid \exists x \phi \mid \forall x \phi$

with $x \in X$

Examples:

- Even numbers : $\exists y x = y + y$
- Odd numbers : $\exists y x + 1 = y + y$

Term Variables

Definition

$\text{var}(t) \subseteq X$ is the set of variables of a term t .

$$\text{var}(0) = \emptyset$$

$$\text{var}(1) = \emptyset$$

$$\text{var}(x) = \{x\}$$

$$\text{var}(t_1 + t_2) = \text{var}(t_1) \cup \text{var}(t_2)$$

$$\text{var}(x + y) = \{x, y\}.$$

Free Variables

Definition

$\text{var}(\phi) \subseteq X$ is the set of variables of a Presburger formula ϕ .

$$\text{var}(t_1 = t_2) = \text{var}(t_1) \cup \text{var}(t_2)$$

$$\text{var}(\top) = \emptyset$$

$$\text{var}(\perp) = \emptyset$$

$$\text{var}(\neg\phi) = \text{var}(\phi)$$

$$\text{var}(\phi_1 \vee \phi_2) = \text{var}(\phi_1) \cup \text{var}(\phi_2)$$

$$\text{var}(\phi_1 \wedge \phi_2) = \text{var}(\phi_1) \cup \text{var}(\phi_2)$$

$$\text{var}(\exists x \phi) = \text{var}(\phi) \setminus \{x\}$$

$$\text{var}(\forall x \phi) = \text{var}(\phi) \setminus \{x\}$$

$$\text{var}(x = y + y) = \{x, y\}$$

$$\text{var}(x = x) = \{x\}$$

$$\text{var}(\exists y x = y + y) = \{x\}$$

Valuations

Definition

A valuation v is a total function $v : X \mapsto \mathbb{N}$.

$v(t)$ is the valuation of a term t .

$$v(0) = 0$$

$$v(1) = 1$$

$$v(t_1 + t_2) = v(t_1) + v(t_2)$$

For instance if $t = 1 + (x + (x + y))$ then:

$$v(t) = 1 + 2v(x) + v(y)$$

Models

$v \models \phi$ is defined by induction.

$v \models t_1 = t_2$ iff $v(t_1) = v(t_2)$

$v \models \top$

$v \not\models \perp$

$v \models \neg\phi$ iff $v \not\models \phi$

$v \models \phi_1 \vee \phi_2$ iff $v \models \phi_1$ or $v \models \phi_2$

$v \models \phi_1 \wedge \phi_2$ iff $v \models \phi_1$ and $v \models \phi_2$

$v \models \exists x \phi$ iff $\exists n \in \mathbb{N}$ such that $v[x \mapsto n] \models \phi$

$v \models \forall x \phi$ iff $\forall n \in \mathbb{N}$ we have $v[x \mapsto n] \models \phi$

Presburger Sets

Let $\vec{x} = (x_1, \dots, x_d)$ be a vector of distinct variables.

Let $v(\vec{x}) = (v(x_1), \dots, v(x_d))$.

Definition

A set $S \subseteq \mathbb{N}^d$ is said to be denoted by $\phi(\vec{x})$ where ϕ is a Presburger formula with $\text{var}(\phi) \subseteq \{x_1, \dots, x_d\}$ if:

$$S = \{v(\vec{x}) \mid v \models \phi\}$$

In this case S is called a Presburger set.

Presburger Sets : Linear Constraints

$\{\vec{n} \in \mathbb{N}^2 \mid n_1 \leq n_2\}$ is denoted by $\phi(x_1, x_2)$ with:

$$\phi = \exists y \ x_1 + y = x_2$$

Let $\alpha_1, \dots, \alpha_d \in \mathbb{Z}$ and $\beta \in \mathbb{Z}$.

$\{\vec{n} \in \mathbb{N}^d \mid \alpha_1 n_1 + \dots + \alpha_d n_d \leq \beta\}$ is a Presburger set.

Presburger Sets : Divisibility Constraints

$z_1 \sim_m z_2$ if m divides $z_1 - z_2$.

$\{n \in \mathbb{N} \mid n \sim_m 0\}$ is denoted by $\phi(x)$ with:

$$\phi = \exists y \ x = y + y$$

Let $\alpha_1, \dots, \alpha_d \in \mathbb{Z}$, $\beta \in \mathbb{Z}$ and $m \in \mathbb{N}_{>0}$.

$\{\vec{n} \in \mathbb{N}^d \mid \alpha_1 n_1 + \dots + \alpha_d n_d \sim_m \beta\}$ is a Presburger set.

Quantifier Elimination

FO $(\mathbb{N}, +, 0, 1, \leq, (\sim_m)_{m \in \mathbb{N}_{>0}})$

$t := 0 \mid 1 \mid x \mid t_1 + t_2$

$p := t_1 = t_2 \mid t_1 \leq t_2 \mid t_1 \sim_m t_2 \mid \top \mid \perp$

$\phi := p \mid \neg\phi \mid \phi_1 \vee \phi_2 \mid \phi_1 \wedge \phi_2 \mid \exists x \phi \mid \forall x \phi$

Definition (Equivalence)

$\phi_1 \equiv \phi_2$ iff for every valuation v we have $v \models \phi_1$ iff $v \models \phi_2$.

Theorem ([Pre29])

Any Presburger formula is effectively equivalent to a quantifier-free formula in FO $(\mathbb{N}, +, 0, 1, \leq, (\sim_m)_{m \in \mathbb{N}_{>0}})$

Satisfiability Problem

Definition (Satisfiability)

ϕ *satisfiable* if $v \models \phi$ for at least one valuation v

Theorem ([Ber77])

The satisfiability problem for the Presburger arithmetic is complete for the class of problems decidable by alternating Turing machines working in 2-EXPTIME with at most n alternations.

The satisfiability problem is decidable in 2-EXPSPACE.

Semilinear Sets

Definition (Linear sets)

$\{\vec{v}_0 + n_1 \vec{v}_1 + \dots + n_k \vec{v}_k \mid n_1, \dots, n_k \in \mathbb{N}\}$
with $\vec{v}_0, \dots, \vec{v}_k \in \mathbb{N}^d$.

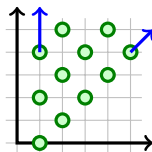


Figure: $\vec{v}_0 = (1, 0)$, $\vec{v}_1 = (1, 1)$, $\vec{v}_2 = (0, 2)$

Definition (Semilinear sets)

Finite union of linear sets.

Theorem ([GS66])

A set is Presburger iff it is semilinear.

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Presburger Formulas vs Automata

Presburger formulas (for denoting Presburger sets):

- Lack canonical representations.
- Simplification procedure difficult.

Deterministic automata (for recognizing regular languages):

- Unique minimal deterministic automaton.
- $n \log(n)$ minimization procedure.

Binary Decomposition

Definition

A word $\sigma = a_1 \dots a_k$ with $a_j \in \{0, 1\}$ such that:

$$n = a_1 2^0 + \dots + a_k 2^{k-1}$$

Extension : basis

A *base of decomposition* $r \in \mathbb{N}_{>1}$

The *digit alphabet* $\Sigma_r = \{0, \dots, r-1\}$

Definition (Encodings for \mathbb{N} in basis r)

A word $\sigma = a_1 \dots a_k$ with $a_j \in \Sigma_r$ such that:

$$n = a_1 r^0 + \dots + a_k r^{k-1}$$

Extension : vectors

A dimension $d \in \mathbb{N}$.

The *digit-vector alphabet* $\Sigma_{r,d} = \Sigma_r^d$

Definition (Encodings for \mathbb{N}^d)

A word $\sigma = \vec{a}_1 \dots \vec{a}_k$ with $\vec{a}_j \in \Sigma_{r,d}$ such that:

$$n = \vec{a}_1 r^0 + \dots + \vec{a}_k r^{k-1}$$

Sets Recognizable in Base r

Definition

A set $S \subseteq \mathbb{N}^d$ is encoded by a language $L \subseteq \Sigma_{r,d}^*$ if S is the set of vectors $\vec{n} \in \mathbb{N}^d$ with at least one encoding $\sigma \in L$.

If L is regular, S is said to be recognizable in base r .

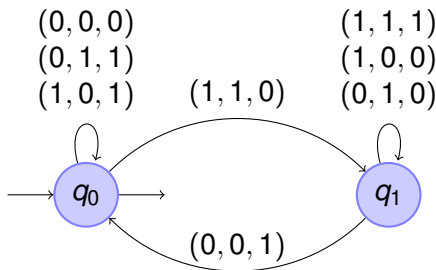


Figure: $\{\vec{n} \in \mathbb{N}^3 \mid n_1 + n_2 = n_3\}$

Saturated Languages

If S_1, S_2 are encoded by languages L_1, L_2

Then $S_1 \cup S_2$ is encoded by $L_1 \cup L_2$

But $S_1 \cap S_2$ is not encoded by $L_1 \cap L_2$

For instance $L_1 = \{0\}$ and $L_2 = \{0.0\}$.

Then $S_1 = S_2 = \{0\} = S_1 \cap S_2$

but $L_1 \cap L_2 = \emptyset$.

Definition (Saturated)

$L \subseteq \Sigma_{r,d}^*$ such that for every encodings σ_1, σ_2 of the same vector \vec{n} :

$$\sigma_1 \in L \iff \sigma_2 \in L$$

Lemma

Every set $S \subseteq \mathbb{N}^d$ is encoded by a **unique** saturated language

$L \subseteq \Sigma_{r,d}^*$.

Saturation Procedure

Lemma

if X is encoded by L then X is encoded by the saturated language:

$$\bigcup_{i \in \mathbb{N}} L \cdot (0^i)^{-1} \cdot 0^*$$

In particular this language is regular if L is regular.

Boolean Operations

Let S_1, S_2, S be encoded by the saturated languages L_1, L_2, L

$S_1 \cup S_2$ is encoded by the saturated language $L_1 \cup L_2$

$S_1 \cap S_2$ is encoded by the saturated language $L_1 \cap L_2$

$\mathbb{N}^d \setminus S$ is encoded by the saturated language $\Sigma_{r,d}^* \setminus L$

Lemma

The class of subsets of \mathbb{N}^d recognizable in base r is stable by union, intersection, and complement.

Projection

$$\begin{aligned}\pi_j &: \mathbb{N}^d \rightarrow \mathbb{N}^{d-1} \\ \vec{n} &\mapsto (n_1, \dots, n_{j-1}, n_{j+1}, \dots, n_d)\end{aligned}$$

Lemma

Let $X \subseteq \mathbb{N}^d$ encoded by $L \subseteq \Sigma_{r,d}^*$.

Then $\pi_j(X)$ is encoded by:

$$\{\pi_j(a_1) \cdots \pi_j(a_k) \mid a_1 \dots a_k \in L\}$$

In particular the language is regular if L is regular.

Presburger Automata

Theorem ([Cob69], [Kla04],[DGH10])

Every Presburger set is recognizable in base r .

Moreover, the set denoted by $\phi(\vec{x})$ can be encoded by a deterministic automaton in 3-EXPTIME.

Efficient algorithms for:

- linear constraints.
- divisibility constraints.

can be found in [WB95].

What Are The Recognizable Sets ?

$r^* = \{r^n \mid n \in \mathbb{N}\}$ is encoded by $L = 0^*.1$.

Thus any set in $\text{FO}(\mathbb{N}, +, 0, 1, r^*)$ is recognizable in base r .

Valuation Function

Definition

The valuation function $V_r : \mathbb{N} \mapsto r^*$ is defined over any $n \in \mathbb{N}_{>0}$ by:
 $V_r(n)$ is the greatest integer in r^* that divides n

$\{(n, V_r(n)) \mid n \in \mathbb{N} \setminus \{0\}\}$ is encoded by:

$$L = (0, 0)^* \cdot \bigcup_{b \neq 0} (b, 1) \cdot \Sigma_{r,2}^*$$

Characterization

Theorem ([BHMV94])

A set is recognizable in base r if and only if it is definable in $\text{FO}(\mathbb{N}, +, 0, 1, V_r)$.

Moreover, the set denoted by $\phi(\vec{x})$ can be encoded by a deterministic automaton in time:

$2^{2^{\dots^{2^n}}}$ a tower of height n .

Sets Recognizable in Multiple Basis

Observe that if $S \subseteq \mathbb{N}^d$ is recognizable in basis r then it is recognizable in basis r^n for every $n \in \mathbb{N}_{>0}$.

Definition (Multiplicatively dependant)

$r_1, r_2 \in \mathbb{N}_{>1}$ are multiplicatively dependant if there exists $n_1, n_2 \in \mathbb{N}_{>0}$ such that $r_1^{n_1} = r_2^{n_2}$

Lemma

Let $r_1, r_2 \in \mathbb{N}_{>1}$ be multiplicatively dependant basis of decomposition. A set is recognizable in base r_1 iff it is recognizable in base r_2 .

Theorem ([Cob69],[Sem77])

Let $r_1, r_2 \in \mathbb{N}_{>1}$ be multiplicatively independant basis of decomposition. A set is recognizable in basis r_1 and r_2 iff it is Presburger.

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Why ?

- Understand the complexity gap.
- Extract geometrical properties.
- Used the automata minimization procedure as a formula simplification and normalization procedure.

Ultimately Periodic Sets

Definition

A set $S \subseteq \mathbb{N}$ is ultimately periodic if

$$\exists k \exists m \geq 1 \wedge (\forall n \geq k \Rightarrow (n \in S \Leftrightarrow n + m \in S))$$

is equivalent to \top .

A set $S \subseteq \mathbb{N}$ is Presburger iff it is ultimately periodic (based on quantifier elimination).

Muchnik Criterion

Theorem ([Muc03])

Let $d \in \mathbb{N}$ and let P_d be an uninterpreted symbol of dimension d .

We can effectively compute a formula ψ_d in $\text{FO}(\mathbb{N}, +, 0, 1, P_d)$ such that the formula ψ_d is equivalent to \top when P_d is interpreted as a set $S \subseteq \mathbb{N}^d$ iff S is Presburger.

Related Works

Presburger Synthesis:

- An EXPTIME algorithm for Boolean combinations of linear equalities [Ler03].
- An EXPTIME algorithm for conjunctions of inequalities [Lat04].
- An 2-EXPTIME algorithm for sets $B + P^*$ where B, P finite [Lug04].
- A PTIME algorithm for the full Presburger arithmetic [Ler05].

Affine Spaces

Definition (Affine spaces)

A non-empty subset A of \mathbb{Q}^d satisfying a conjunction of linear equalities. Its direction \vec{A} is the subset of \mathbb{Q}^n satisfying the *homogeneous* conjunction.

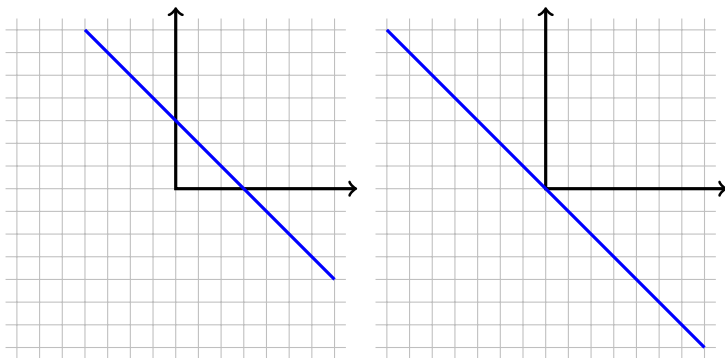


Figure: An affine space and its direction

Semi-Affine spaces

Definition (Semi-affine spaces[Ler04])

A finite union $S = \bigcup_{i=1}^k A_i$ of non-empty affine spaces A_i .

Its direction $\vec{S} = \bigcup_{i=1}^k \vec{A}_i$.

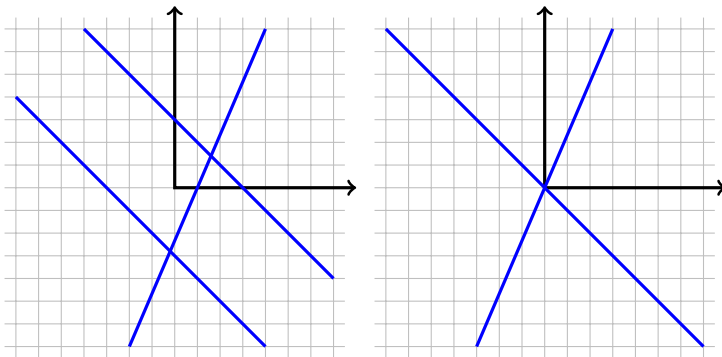


Figure: A semi-affine space and its direction

Semi-Affine Encapsulation

Definition ([Ler04])

For any set $R \subseteq \mathbb{Q}^d$ there exists a minimal for \subseteq semi-affine space that contains R called the **semi-affine encapsulation** of R .

Theorem ([Ler05])

Directions of semi-affine encapsulations of subsets of \mathbb{N}^d recognized by automata are computable in PTIME.

Boundaries

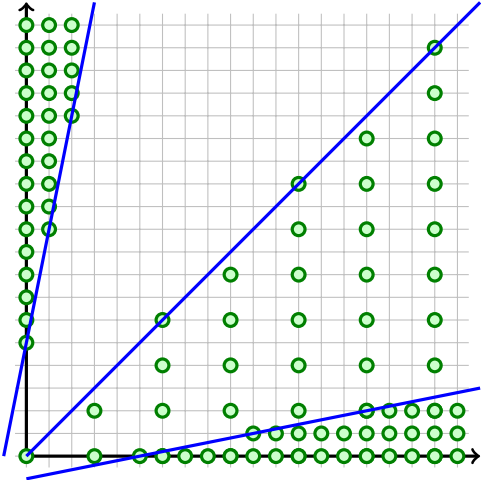
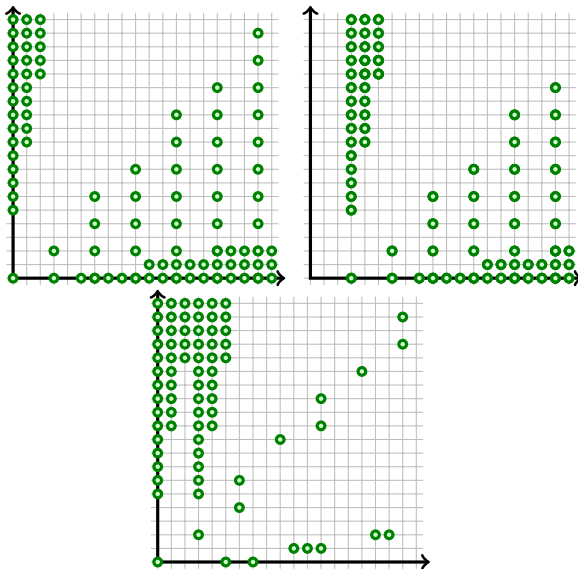
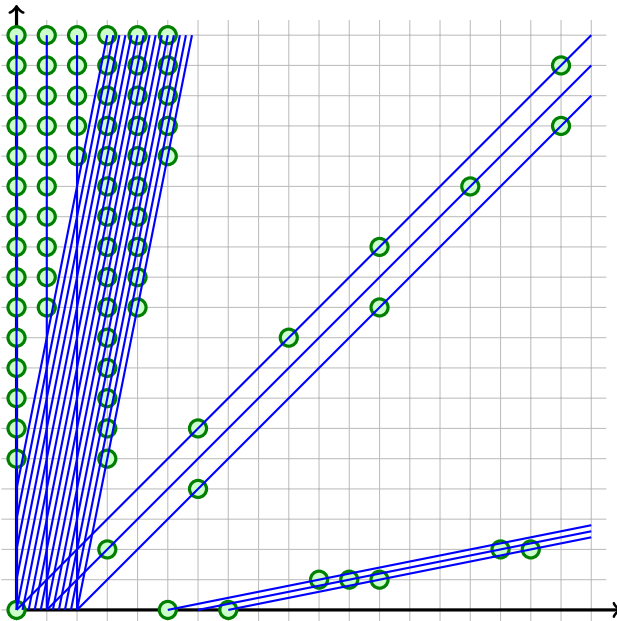


Figure: A Presburger set

Key Idea





Theorem ([Ler05])

We can decide in PTIME if an automaton recognizes a Presburger set S . Moreover, in this case, we can compute in PTIME a Presburger formula $\phi(\vec{x})$ that denotes S .

This algorithm is implemented in TAPAS [LP09].

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Presburger Relations

Let $(x_1, x'_1, \dots, x_d, x'_d)$ be a sequence of distinct variables.

$$\vec{x} = (x_1, \dots, x_d)$$

$$\vec{x}' = (x'_1, \dots, x'_d)$$

Definition

A relation $R \subseteq \mathbb{N}^d \times \mathbb{N}^d$ is said to be denoted by $\phi(\vec{x}, \vec{x}')$ where ϕ is a Presburger formula with $\text{var}(\phi) \subseteq \{x_1, x'_1, \dots, x_d, x'_d\}$ if:

$$R = \{(v(\vec{x}), v(\vec{x}')) \mid v \models \phi\}$$

In this case R is called a Presburger relation.

Presburger Counter Systems

Definition

A Presburger counter system is a tuple (Q, d, Δ) where:

- Q is a finite set of *control states*.
- Δ is a finite set of triples (q, ϕ, q') where $q, q' \in Q$ and ϕ is a Presburger formula satisfying $\text{var}(\phi) \subseteq \{x_1, x'_1, \dots, x_d, x'_d\}$.

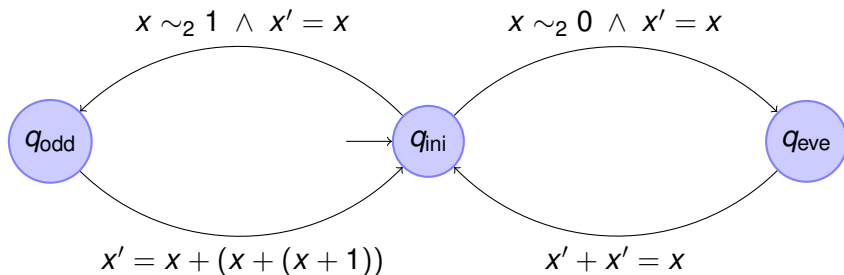


Figure: A Presburger counter system.

Semantics

A configuration c is a couple $(q, \vec{n}) \in Q \times \mathbb{N}^d$.

The semantics is given by $(q, \vec{n}) \xrightarrow{\phi} (q', \vec{n}')$ if $(q, \phi, q') \in \Delta$ and $(\vec{n}, \vec{n}') \in R_\phi$ where R_ϕ is the Presburger relation denoted by $\phi(\vec{x}, \vec{x}')$.

The Reachability Problem

We introduce $\xrightarrow{*}$ defined by $c \xrightarrow{*} c'$ if there exists:

$$c = c_0 \xrightarrow{\phi_1} c_1 \cdots \xrightarrow{\phi_k} c_k = c'$$

In this case c' is said to be *reachable* from c

With the Minsky machines:

Lemma

The reachability problem is undecidable for the class of Presburger Counter Systems.

Inductive Invariant

Definition

A set $C \subseteq Q \times \mathbb{N}^d$ is called an inductive invariant if for every $c \xrightarrow{\phi} c'$ with $c \in C$, we have $c' \in C$.

Definition

A set $C \subseteq Q \times \mathbb{N}^d$ is said Presburger if $C = \bigcup_{q \in Q} N_q$ where $N_q \subseteq \mathbb{N}^d$ is Presburger for every q .

Symbolic Computation

Semi-algorithm deciding the reachability problem $c_\bullet \xrightarrow{*} c_l$.

Initially $k = 0$ and $C_0 = \{c_\bullet\}$.

We repeat forever the following loop:

If $c_l \in C_k$ return “reachable”.

Compute:

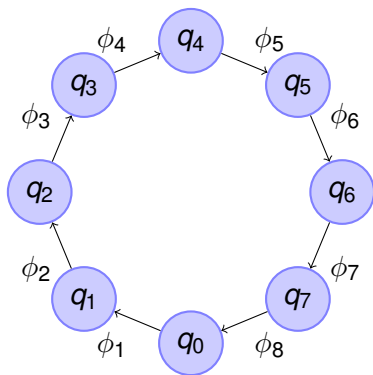
$$C_{k+1} = C_k \cup \{c_{k+1} \mid \text{there exists } c_k \xrightarrow{\phi} c_{k+1} \text{ with } c_k \in C_k\}$$

If $C_{k+1} \subseteq C_k$ return “unreachable”.

Otherwise increment k .

Acceleration Techniques

The iterative effect of cycles.



$R_1 \cdots R_8$ is a Presburger relation denoted by $\phi(\vec{x}, \vec{x}')$.

In general even if R is a Presburger relation, R^* is not a Presburger binary relation.

We cannot even decide if it is definable in the Presburger arithmetic.

Some Results

- Let $f : \mathbb{Z}^d \mapsto \mathbb{Z}^d$ be a total linear function $f(\vec{x}) = M\vec{x} + \vec{v}$. Then f^* is definable in $\text{FO}(\mathbb{Z}, +, 0, 1, \leq)$ if and only if M^* is finite [Boi03].
- Let $f : \mathbb{Z}^d \mapsto \mathbb{Z}^d$ be a linear function partially defined over a Presburger set. Then f^* is definable in $\text{FO}(\mathbb{Z}, +, 0, 1, \leq)$ if M^* is finite [FL02].
- Let ϕ be a conjunction of difference constraints $z_i - z_j \leq c$ with $z_i \in \{x_i, x'_i\}$ and $z_j \in \{x_j, x'_j\}$. Then ϕ^* is effectively definable in $\text{FO}(\mathbb{Z}, +, 0, 1, \leq)$ [CJ98].
- Let ϕ be a conjunction of octagonal constraints $z_i - z_j \leq c$ or $z_i + z_j \leq c$ with $z_i \in \{x_i, x'_i\}$ and $z_j \in \{x_j, x'_j\}$. Then ϕ^* is effectively definable in $\text{FO}(\mathbb{Z}, +, 0, 1, \leq)$ [BGI09].

Sometimes Approximation Is Mandatory

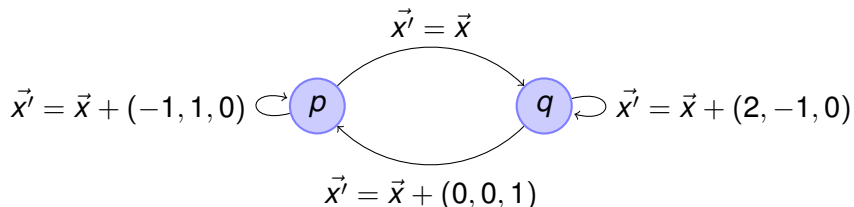


Figure: A Vector Addition System With States [HP76]

Reachability set from $(p, (1, 0, 0))$

$$\{p\} \times \{\vec{n} \in \mathbb{N}^3 \mid n_1 + n_2 \leq 2^{n_3}\} \\ \cup \{q\} \times \{\vec{n} \in \mathbb{N}^3 \mid n_1 + 2n_2 \leq 2^{n_3+1}\}$$

Vector Addition Systems With States

Definition

A Vector Addition System with States (VASS) is a Presburger counter systems with formulas ϕ of the form $\vec{x}' = \vec{x} + \vec{v}$ with $\vec{v} \in \mathbb{Z}^d$.

Theorem ([Ler09])

If c_1 is not reachable from c_\bullet , then there exists a Presburger Inductive Invariant that contains c_\bullet but not c_1 .

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Conclusion



We have seen:

- Some links between automata and Presburger arithmetic.
- Applications of the Presburger arithmetic on the verification of counter systems.

Many open problems:

- Find a decision procedure for the Presburger arithmetic combining efficiently formulas and automata.
- Improve acceleration techniques to be “complete” for the VASS reachability problem.
- Find interesting classes of Presburger formulas that can be iterated.
- And many other problems based on results not presented here.

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