

# Stochastic Games

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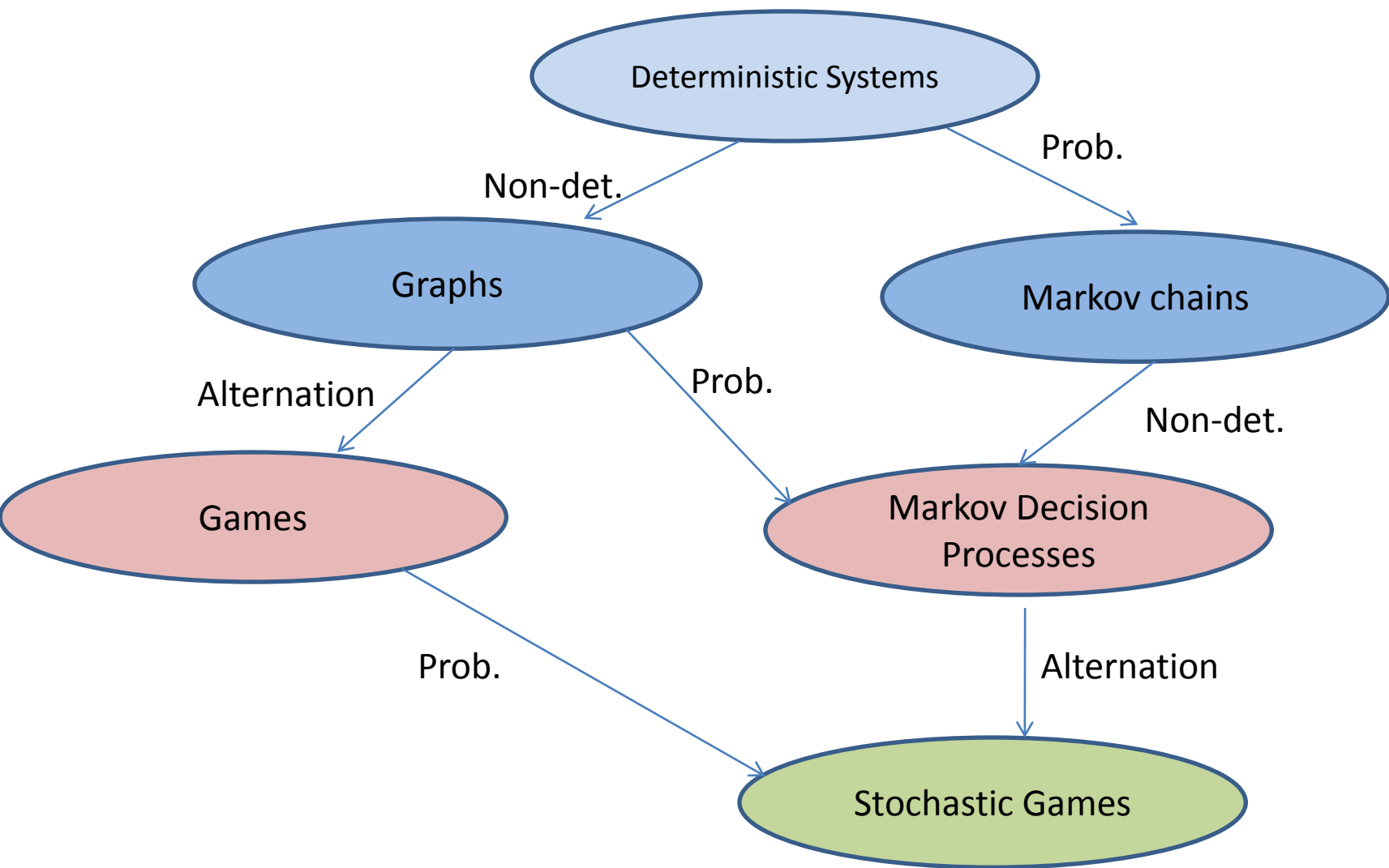
# Stochastic Games

- Two-player perfect-information games on graphs with randomness in transitions.
  
- Various sub-classes
  - Brief discussion of applications.
  - Solution techniques.

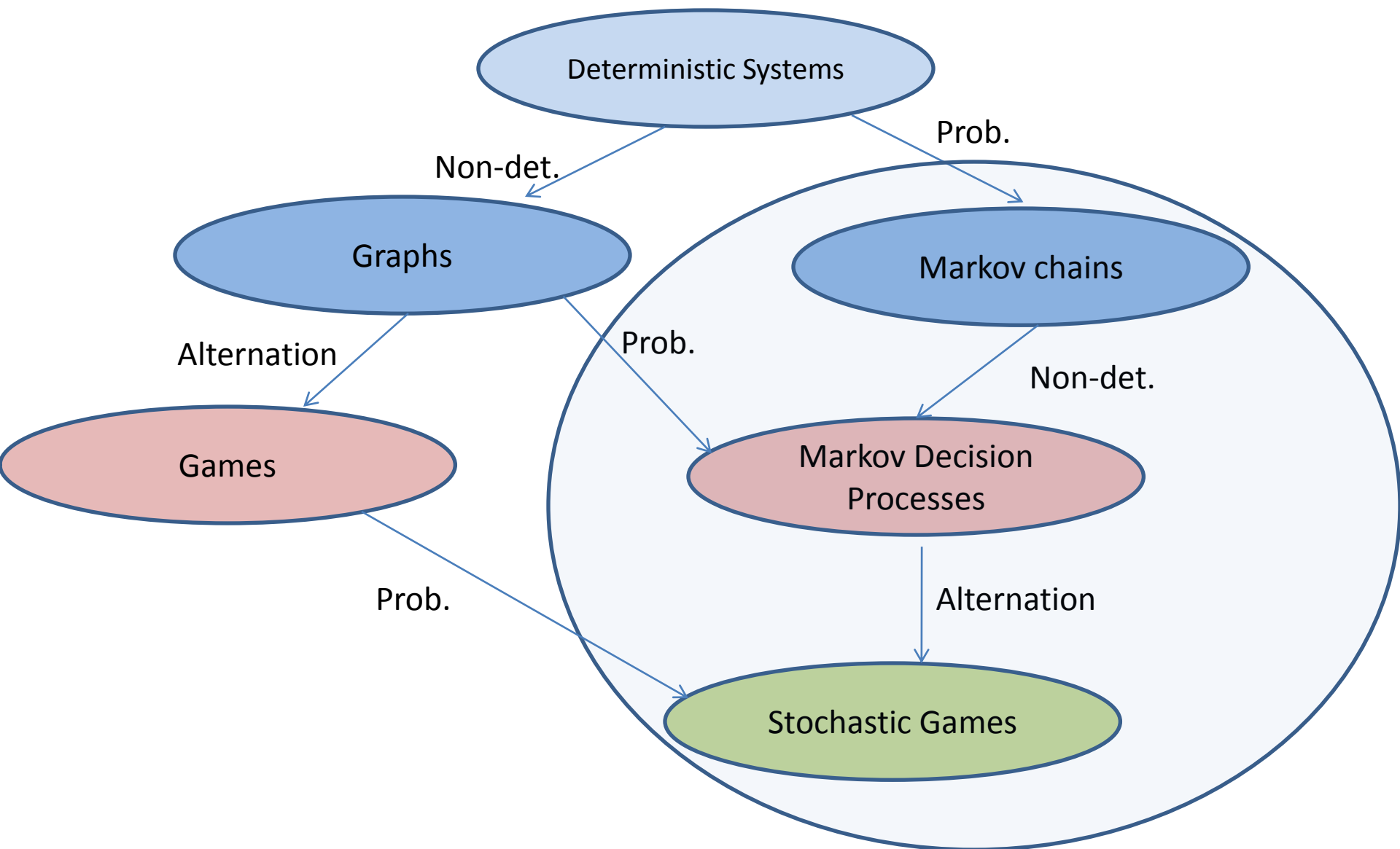
# System Analysis

- Formal analysis of systems to prove correctness with respect to properties.
- System to game graph
  - Vertices represent states.
  - Edges represent transitions.
  - Paths represent behavior.
  - Players represent various interacting agents.
- Mathematical framework for system analysis.

# Stochastic Games

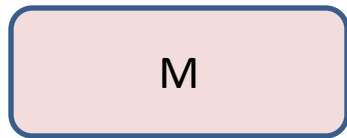


# Stochastic Games



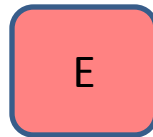
# Applications: Verification of Systems

- Verification of systems

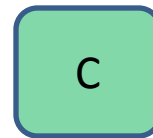


satisfies property

- Environment



- Controller (Synthesis)



# Applications: Verification of Systems

- Verification and synthesis of systems
  - System is fixed and the environment fixed: deterministic systems.
  - System is fixed, but not the environment: Demonic non-determinism.
  - Environment fixed but probabilistically (randomized scheduler): Markov chain.
  - Probabilistic environment and controller: Markov decision process.
  - Controller vs. environment: angelic vs. demonic non-determinism (alternation).

# Applications: Systems for Specification

- Synthesis of systems from specification
  - Input/Output signals.
  - Automata over I/O that specifies the desired set of behaviors.
  - Can the input player present input such that no matter how the output player plays the generated sequence of I/O signals is accepted by automata ?
  - Deterministic automata: Games.
  - Some input signals generate probabilistic transition: Stochastic games.



# Game Models Applications

- synthesis [Church, Ramadge/Wonham, Pnueli/Rosner]
  - model checking of open systems
  - receptiveness [Dill, Abadi/Lamport]
  - semantics of interaction [Abramsky]
  - non-emptiness of tree automata [Rabin, Gurevich/ Harrington]
  - behavioral type systems and interface automata [deAlfaro/ Henzinger]
  - model-based testing [Gurevich/Veanes et al.]
  - etc.
- 
- Mathematicians (logic and set theory), Stochastic game theorists, Economists, Computer Scientists, Biologists (evolutionary games).

# Properties

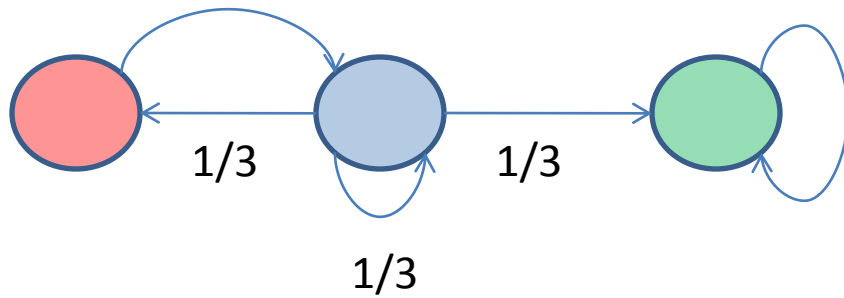
- Properties in verification
  - Reachability to target set.
  - Liveness (Buechi) or repeated reachability.
  - Fairness.
  - Parity objectives: all  $\omega$ -regular specifications.

# MARKOV CHAINS

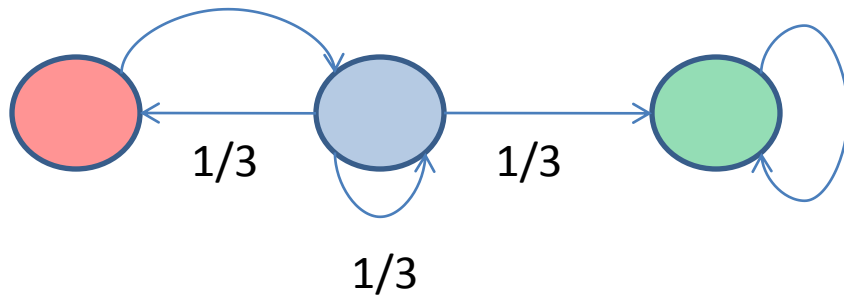
# Markov Chains

- Markov chain model:  $G = ((S, E), \delta)$
- Finite set  $S$  of states.
- Probabilistic transition function  $\delta$
- $E = \{ (s, t) \mid \delta(s)(t) > 0 \}$
- The graph  $(S, E)$  is useful.

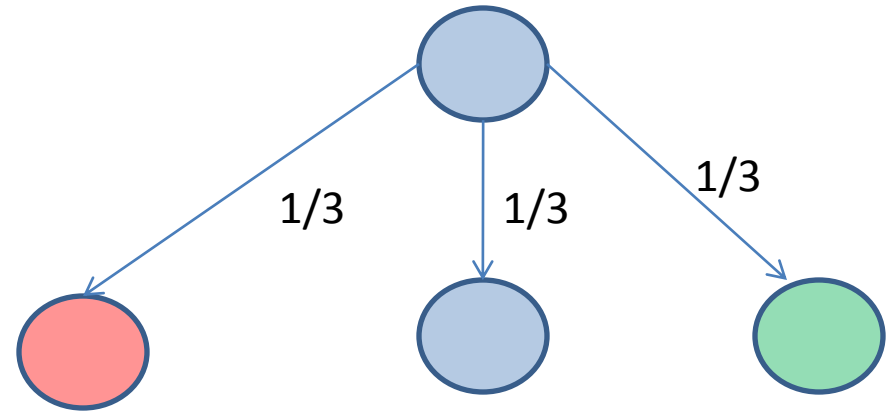
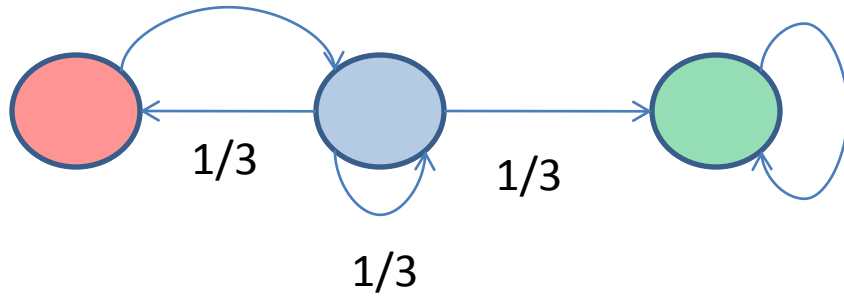
# Markov Chain: Example



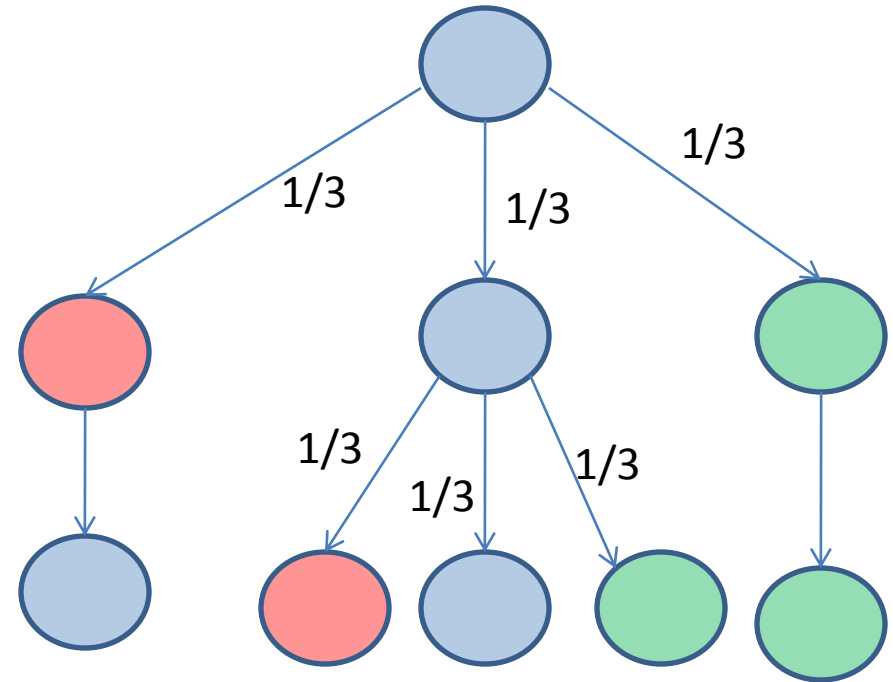
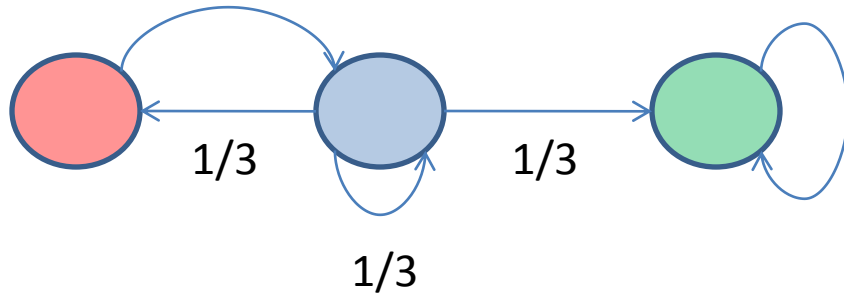
# Markov Chain: Example



# Markov Chain: Example



# Markov Chain: Example





# Markov Chain

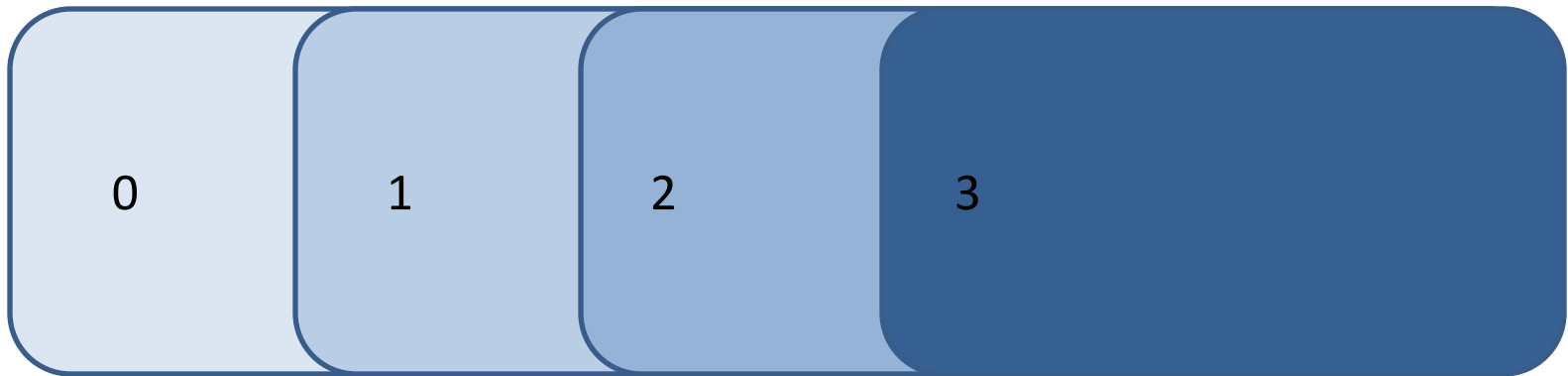
- Properties of interest
  - Target set T: probability to reach the target set.
  - Target set B: probability to visit B infinitely often.

# Objectives

- Objectives are subsets of infinite paths, i.e.,  $\psi \subseteq S^\omega$ .
- Reachability: set of paths that visit the target  $T$  at least once.
- Liveness (Buechi): set of paths that visit the target  $B$  infinitely often.
- Parity: given a priority function  $p: S \rightarrow \{0, 1, \dots, d\}$ , the objective is the set of infinite paths where the minimum priority visited infinitely often is even.

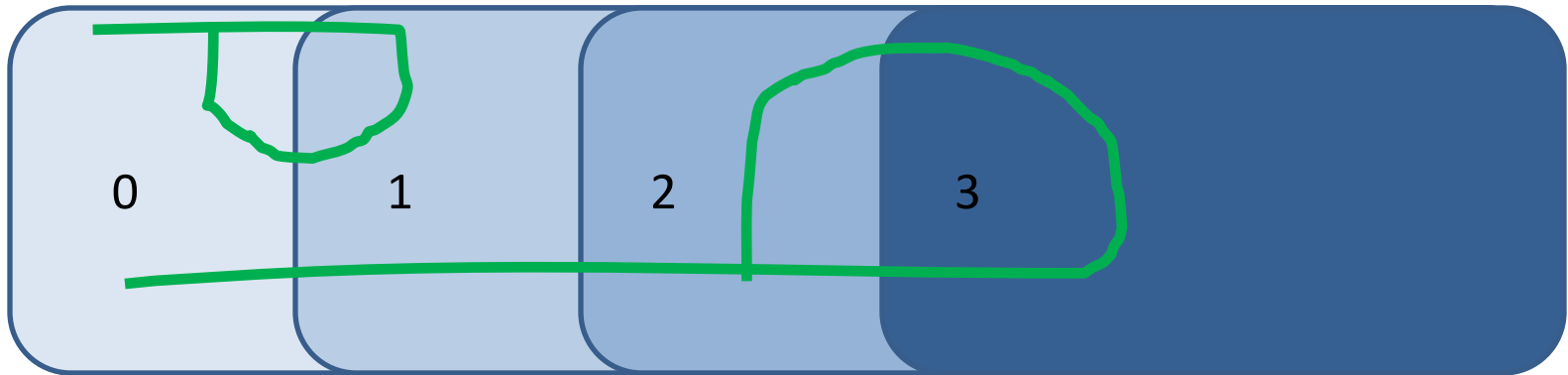
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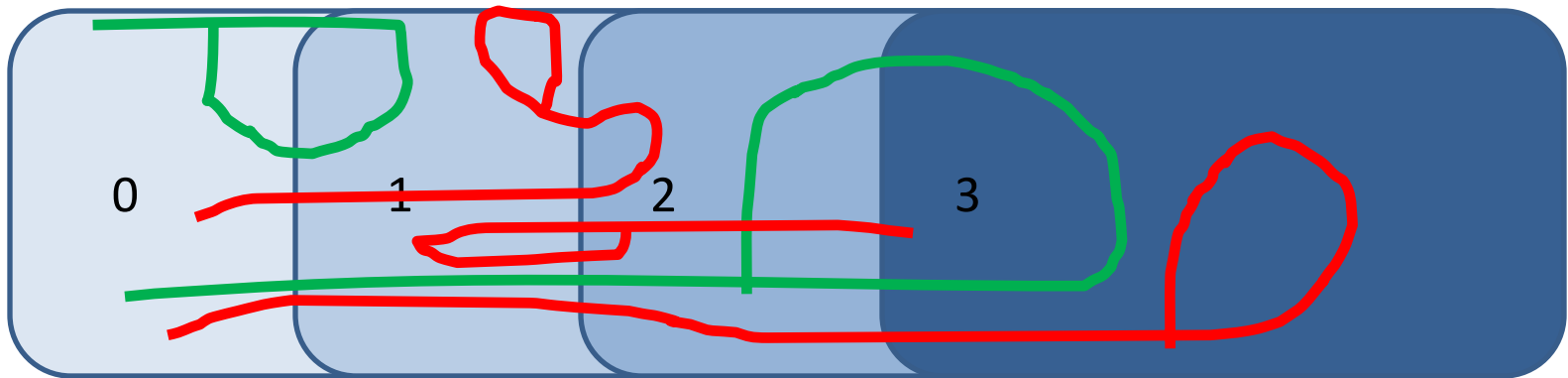
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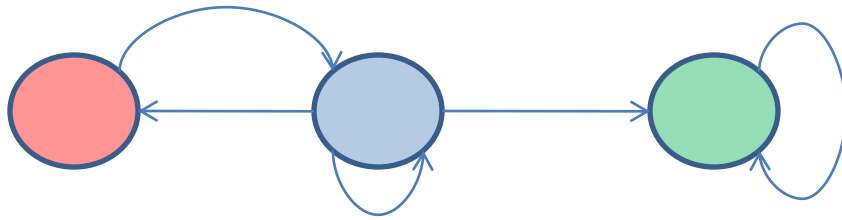


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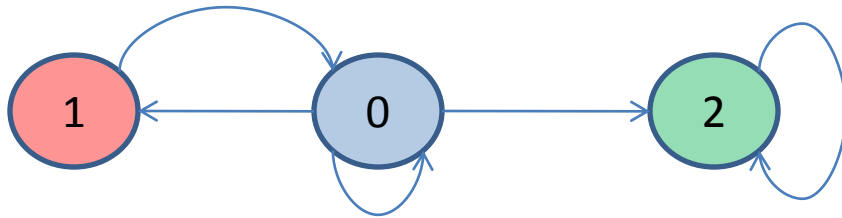


# Markov Chain: Example



- **Reachability:** starting state is blue.
  - Red: probability is less than 1.
  - Blue: probability is 1.
  - Green probability is 1.
- **Liveness:** infinitely often visit
  - Red: probability is 0.
  - Blue: probability is 0.
  - Green: probability is 1.

# Markov Chain: Example



## ■ Parity

- Blue infinitely often, or 1 finitely often.
- In general, if priorities are  $0, 1, \dots, 2d$ , then we require for some  $0 \leq i \leq d$ , that priority  $2i$  infinitely often, and all priorities less than  $2i$  is finitely often.

# Questions

- Qualitative question
  - The set where the property holds with probability 1.
  - Qualitative analysis.
- Quantitative question
  - What is the precise probability that the property holds.
  - Quantitative analysis.



# Qualitative Analysis of Markov Chains

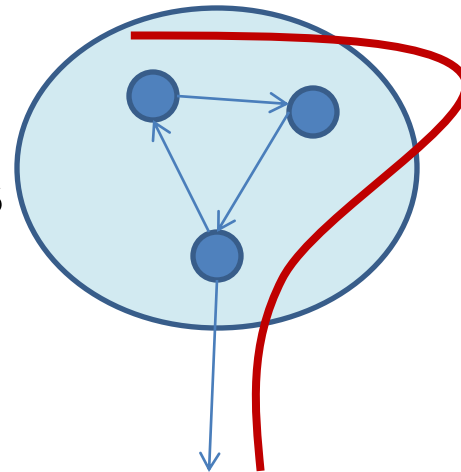
- Consider the graph of Markov chain.
- **Closed recurrent set:**
  - Bottom strongly connected component.
  - Closed: No probabilistic transition out.
  - Strongly connected.

# Qualitative Analysis of Markov Chains

- **Theorem:** Reach the set of closed recurrent set with probability 1.
- **Proof.**
  - Consider the DAG of the scc decomposition of the graph.
  - Consider a scc C of the graph that is not bottom.
  - Let  $\alpha$  be the minimum positive transition prob.
  - Leave C within n steps with prob at least  $\beta = \alpha^n$ .
  - Stay in C for at least k\*n steps is at most  $(1-\beta)^k$ .
  - As k goes to infinity this goes to 0.

# Qualitative Analysis of Markov Chains

- **Theorem:** Reach the set of closed recurrent set with probability 1.
- **Proof.**
  - Path goes out with  $\beta$ .
  - Never gets executed for k times is  $(1-\beta)^k$ . Now let k go to infinity.



# Qualitative Analysis of Markov Chains

- **Theorem:** Given a closed recurrent set  $C$ , for any starting state in  $C$ , all states is reached with prob 1, and hence all states visited infinitely often with prob 1.
- **Proof.** Very similar argument like before.

# Qualitative and Quantitative Analysis

- Previous two results are the basis.
- Example: Liveness objective.
  - Compute max scc decomposition.
  - Reach the bottom scc's with prob 1.
  - A bottom scc with a target is a good bottom scc, otherwise bad bottom scc.
  - Qualitative: if a path to a bad bottom scc, not with prob 1. Otherwise with prob 1.
  - Quantitative: reachability probability to good bottom scc.

# Quantitative Reachability Analysis

- Let us denote by  $C$  the set of bottom scc's (the quantitative values are 0 or 1). We now define a set of linear equalities. There is a variable  $x_s$  for every state  $s$ . The equalities are as follows:
  - $x_s = 0$  if  $s$  in  $C$  and bad bottom scc.
  - $x_s = 1$  if  $s$  in  $C$  and good bottom scc.
  - $x_s = \sum_{t \in S} x_t * \delta(s)(t)$ .
- Brief proof idea: The remaining Markov chain is transient. Matrix algebra  $\det(I-\delta) \neq 0$ .

# Markov Chain Summary

	Reachability	Liveness	Parity
Qualitative	Linear time	Linear time	Linear time
Quantitative	Linear equalities (Gaussian elimination)	Linear equalities	Linear equalities

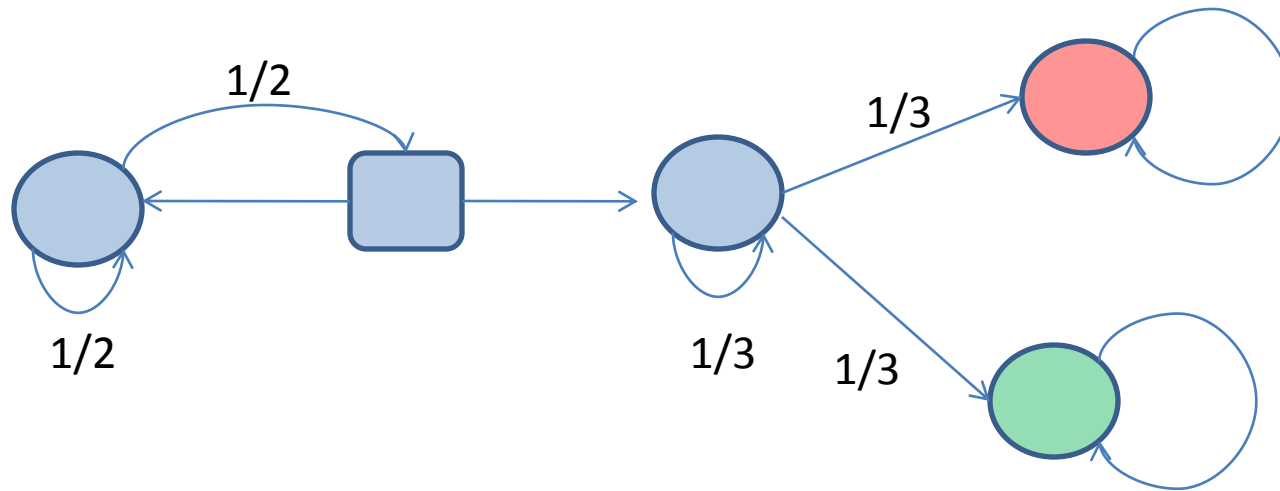
# MARKOV DECISION PROCESSES



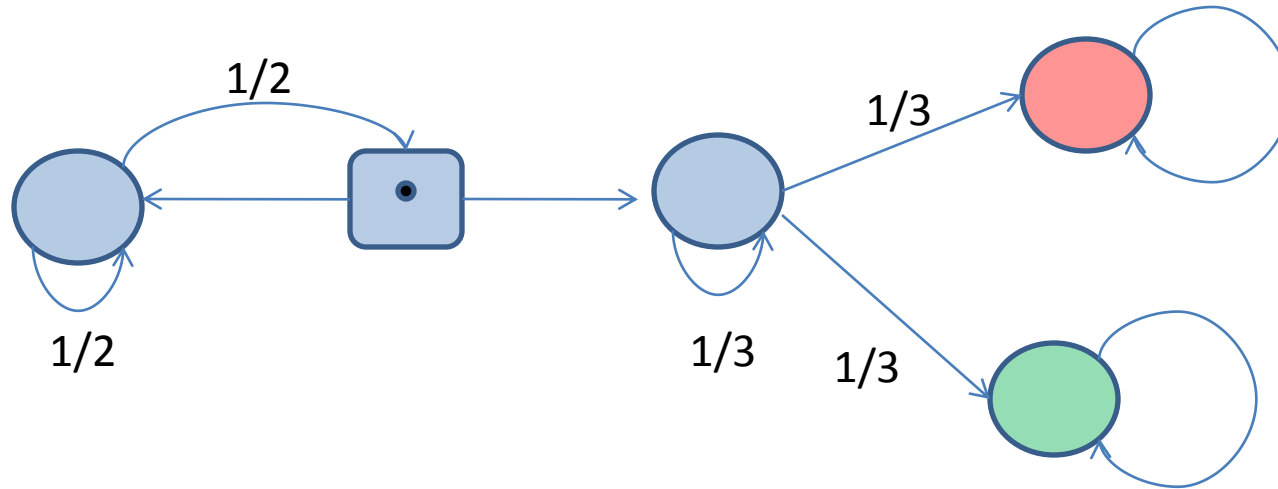
# Markov Decision Processes

- Markov decision processes (MDPs)
  - Non-determinism.
  - Probability.
  - Generalizes non-deterministic systems and Markov chains.
- An MDP  $G = ((S, E), (S_1, S_P), \delta)$ 
  - $\delta : S_P \rightarrow D(S)$ .
  - For  $s \in S_P$ , the edge  $(s, t) \in E$  iff  $\delta(s)(t) > 0$ .
  - $E(s)$  out-going edges from  $s$ , and assume  $E(s)$  non-empty for all  $s$ .

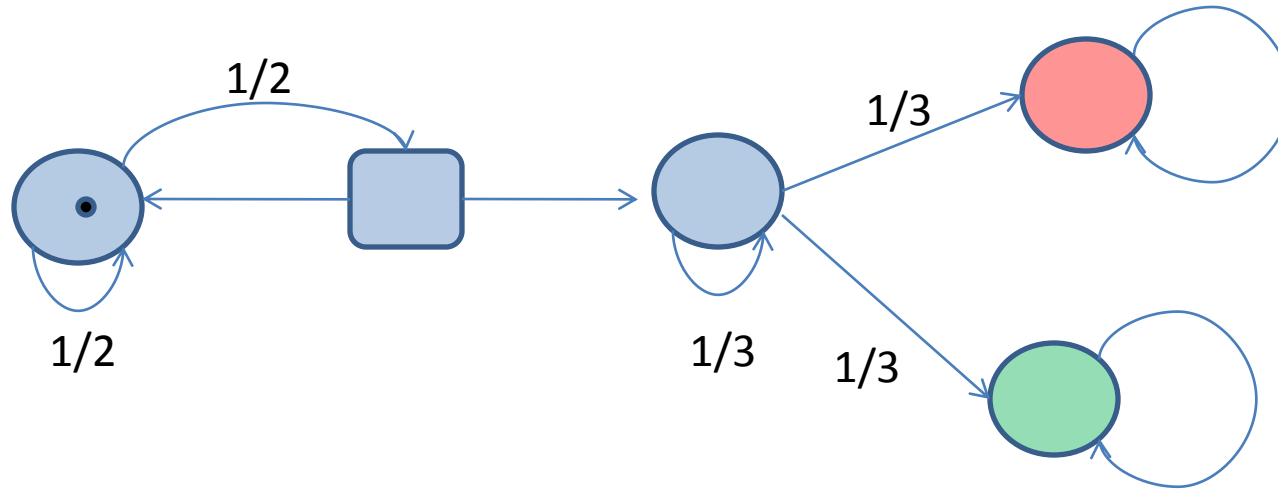
# MDP: Example



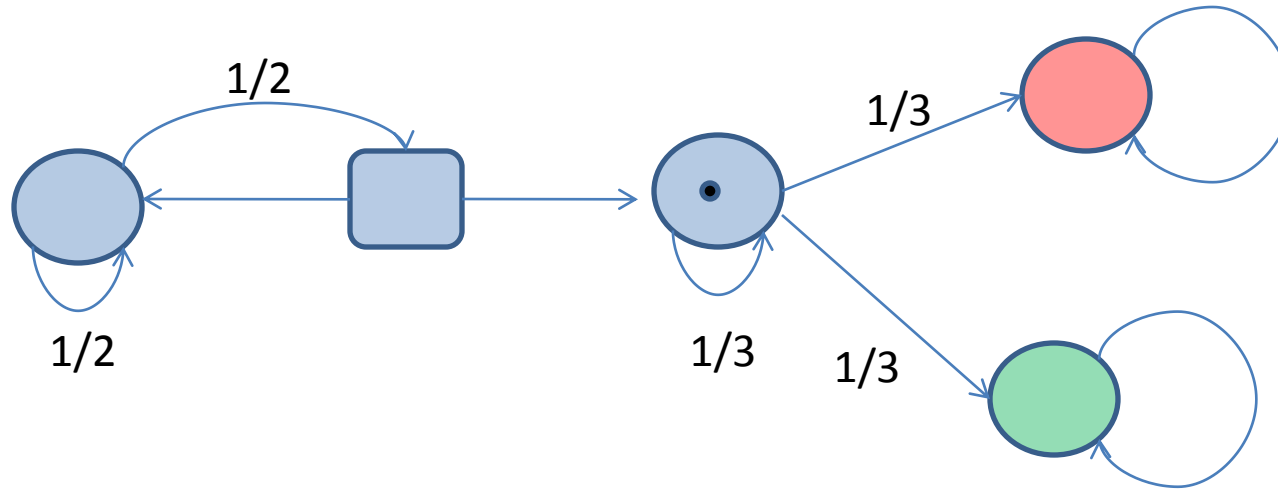
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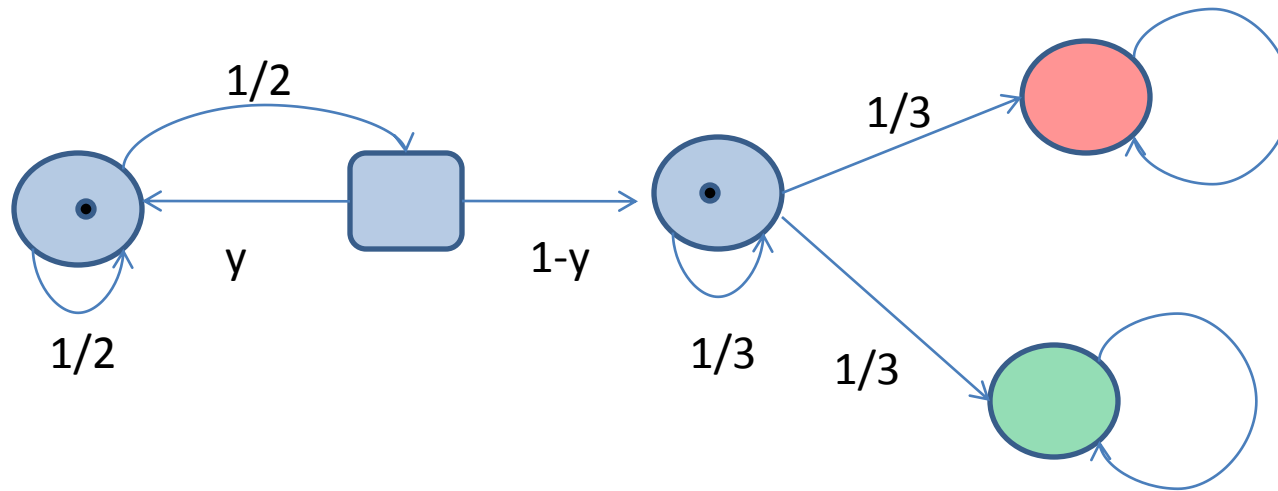
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# MDP

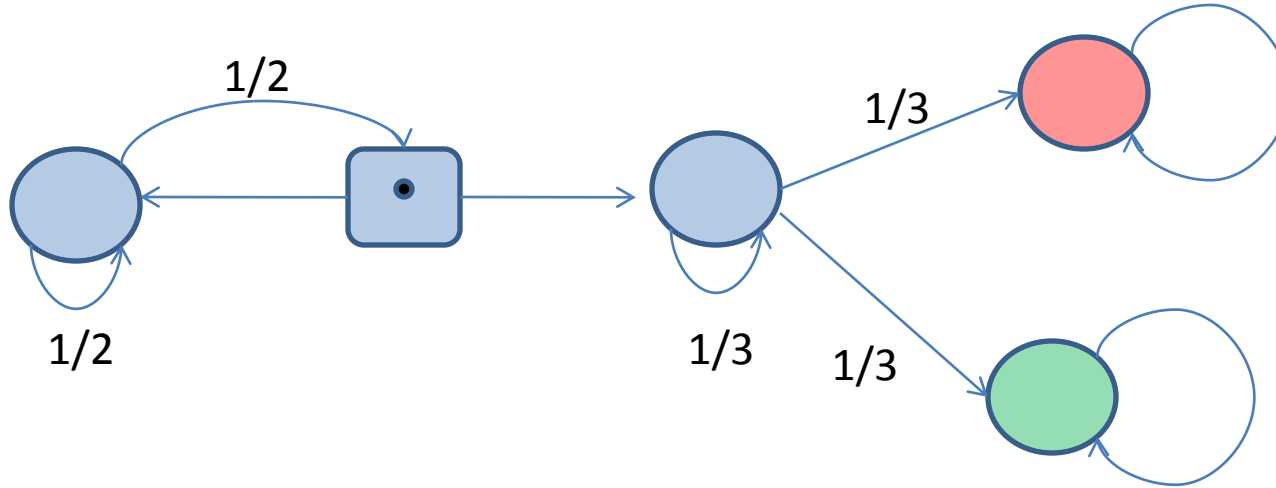
- Model
- Objectives
- How is non-determinism resolved: notion of strategies. At each stage can be resolved differently and also probabilistically.

# Strategies

- Strategies are recipe how to move tokens or how to extend plays. Formally, given a history of play (or finite sequence of states), it chooses a probability distribution over out-going edges.
  - $\sigma: S^* S_1 \rightarrow D(S)$ .



# MDP: Strategy Example

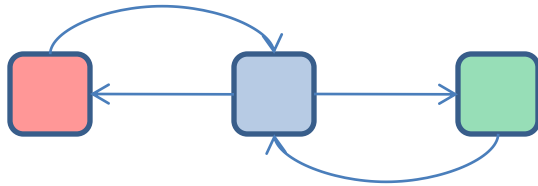


Token for  $k$ -th time: choose left with prob  $1/k$  and right  $(1-1/k)$ .

# Strategies

- Strategies are recipe how to move tokens or how to extend plays. Formally, given a history of play (or finite sequence of states), it chooses a probability distribution over out-going edges.
  - $\sigma: S^* S_1 \rightarrow D(S)$ .
- History dependent and randomized.
- History independent: depends only current state (memoryless or positional).
  - $\sigma: S_1 \rightarrow D(S)$
- Deterministic: no randomization (pure strategies).
  - $\sigma: S^* S_1 \rightarrow S$
- Deterministic and memoryless: no memory and no randomization (pure and memoryless and is the simplest class).
  - $\sigma: S_1 \rightarrow S$

# Example: Cheating Lovers



Visit green and red infinitely often.

Pure memoryless not good enough.

Strategy with memory: alternates.

Randomized memoryless: choose with uniform probability.

Certainty vs. probability 1.

# Values in MDPs

- Value at a state for an objective  $\psi$ 
  - $\text{Val}(\psi)(s) = \sup_{\sigma} \Pr_s^{\sigma}(\psi)$ .
- Qualitative analysis
  - Compute the set of almost-sure (prob 1) winning states (i.e., set of states with value 1).
- Quantitative analysis
  - Compute the value for all states.

# Qualitative and Quantitative Analysis

- Qualitative analysis
  - Liveness (Buechi) and reachability as a special case.
- Reduction of quantitative analysis to quantitative reachability.
- Quantitative reachability.

# Qualitative Analysis for Liveness

- An MDP  $G$ , with a target set  $B$ .
- Set of states such that there is a strategy to ensure that  $B$  is visited infinitely often with probability 1.
- We will show pure memoryless is enough.
- The generalization to parity (left as an exercise).

# Attractor

- Random Attractor for a set  $U$  of states.
- $U_0 = U$ .
- $$U_{i+1} = U_i \cup \{s \in S_1 \mid E(s) \subseteq U_i\}$$
$$\cup \{s \in S_p \mid E(s) \cap U_i \neq \emptyset\}.$$
- From  $U_{i+1}$  no matter what is the choice,  $U_i$  is reached with positive probability. By induction  $U$  is reached with positive probability.

# Attractor

- $\text{Attr}_p(U) = \bigcup_{i \geq 0} U_i$ .
- **Attractor lemma:** From  $\text{Attr}_p(U)$  no matter the strategy of the player (history dependent, randomized) the set  $U$  is reached with positive probability.
- Can be computed in  $O(m)$  time ( $m$  number of edges).
- Thus if  $U$  is not in the almost-sure winning set, then  $\text{Attr}_p(U)$  is also not in the almost-sure winning set.

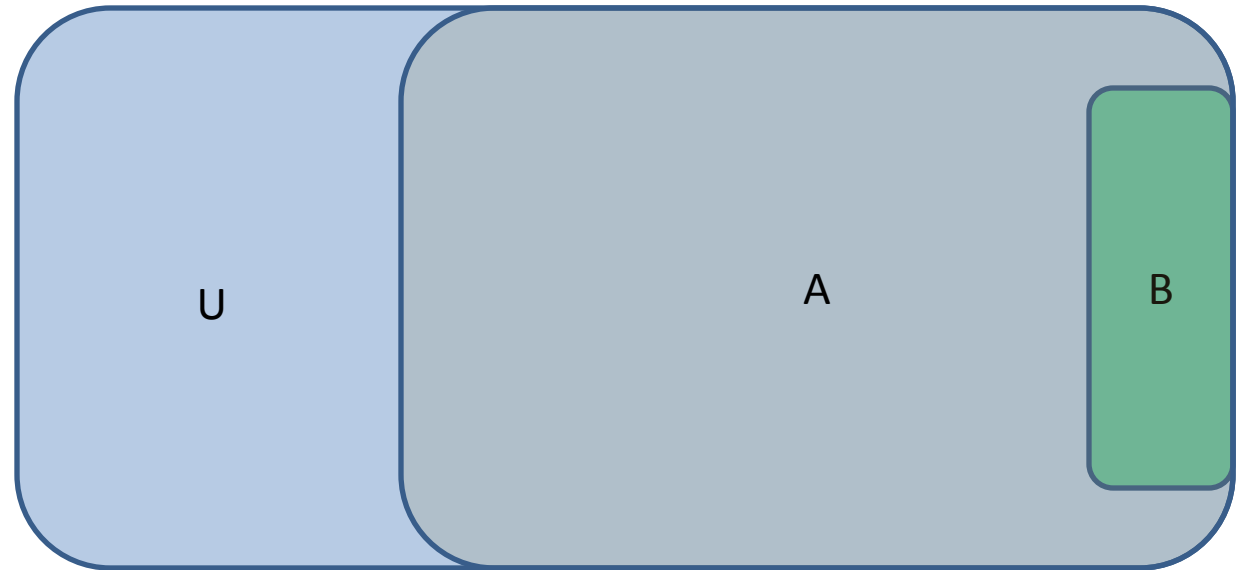


# Iterative Algorithm



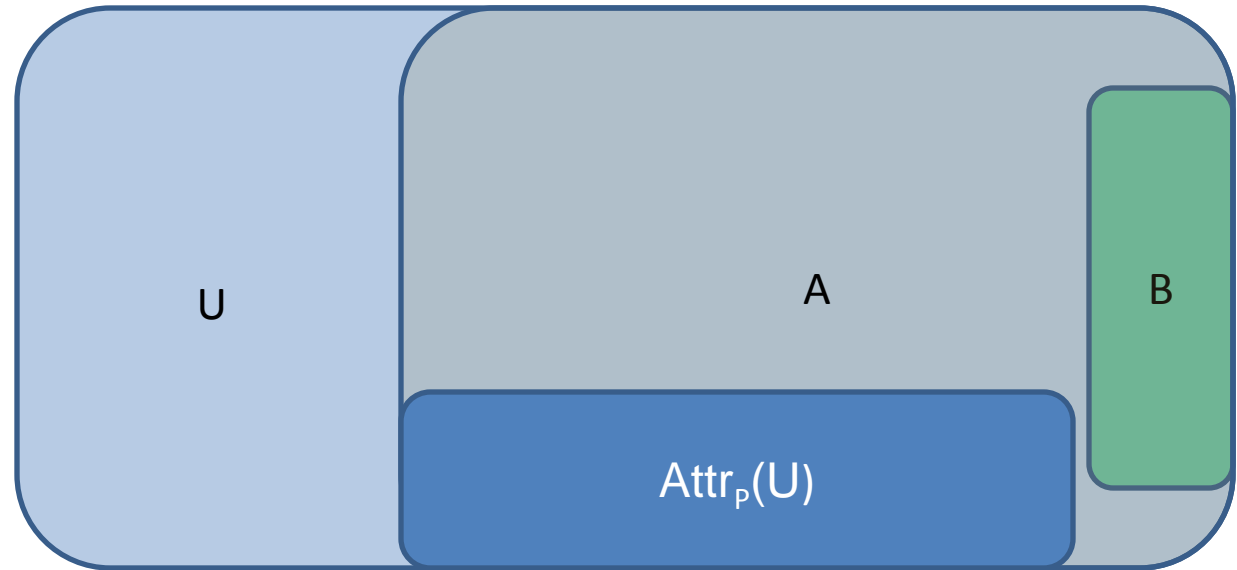
- Compute simple reachability to B (exist a path) in the graph of the MDP  $(S,E)$ . Let us call this set A.

# Iterative Algorithm



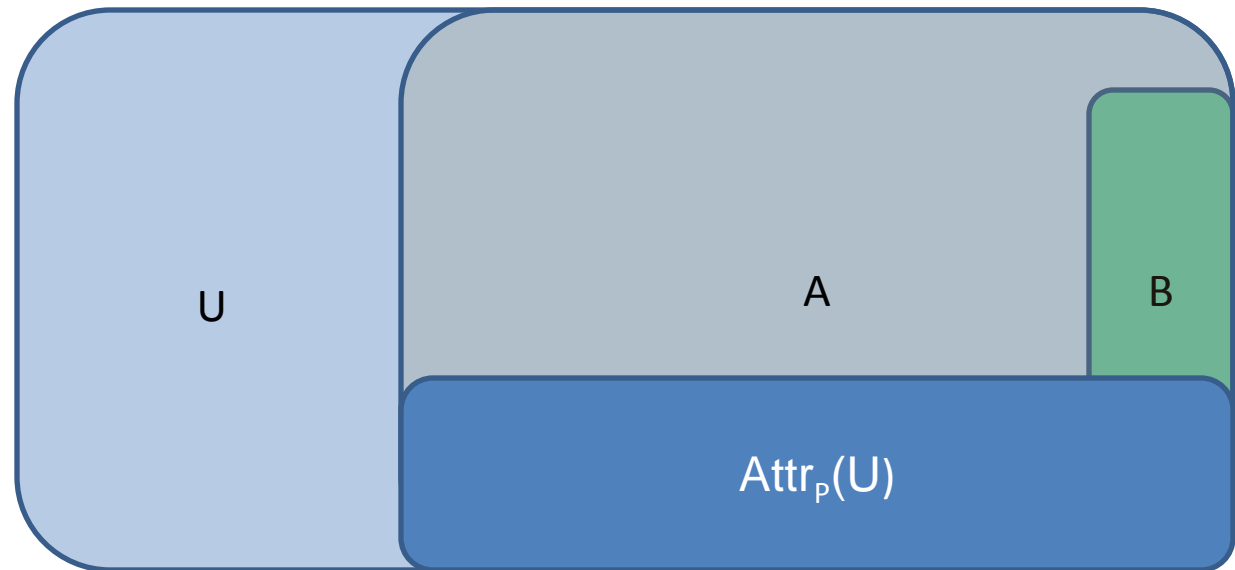
- Let  $U = S \setminus A$ . Then there is not even a path from U to B. Clearly, U is not in the almost-sure set.
- By attractor lemma can take  $\text{Attr}_p(U)$  out and iterate.

# Iterative Algorithm



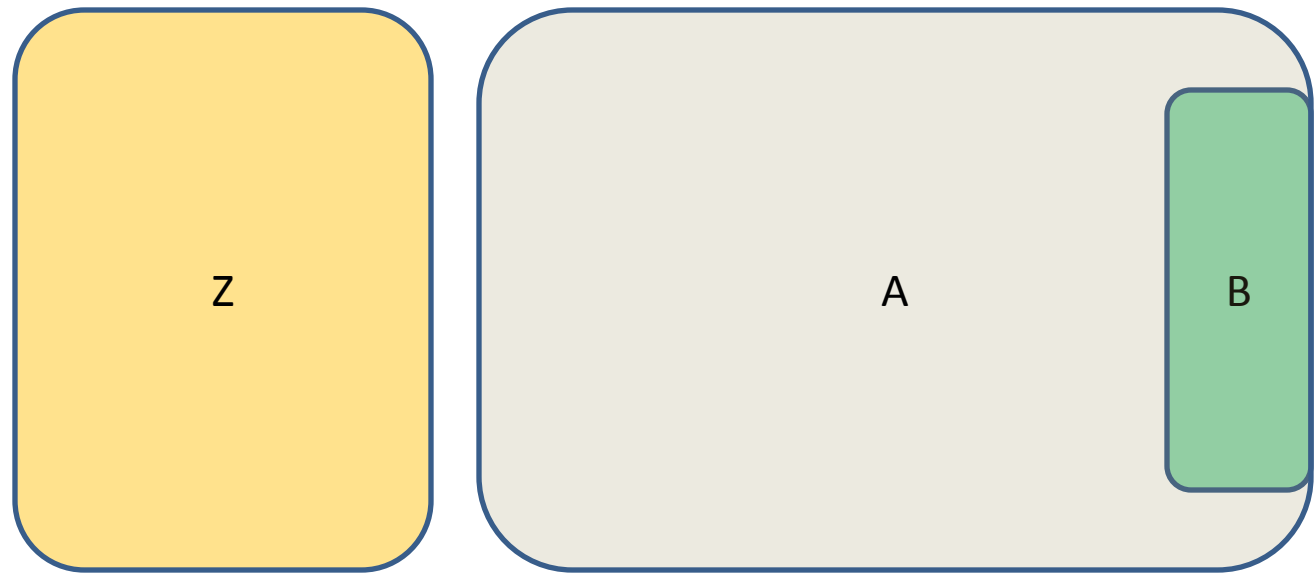
- $\text{Attr}_p(U)$  may or may not intersect with  $B$ .

# Iterative Algorithm



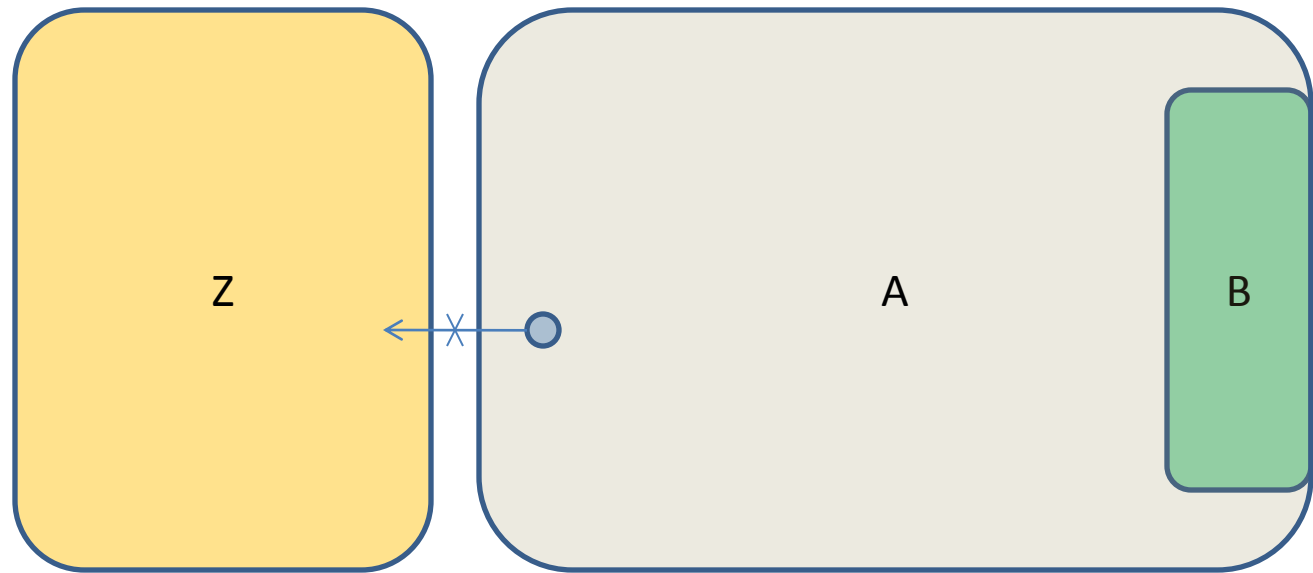
- Iterate on the remaining sub-graph.
- Every iteration what is removed is not part of almost-sure winning set.
- What happens when the iteration stops.

# Iterative Algorithm



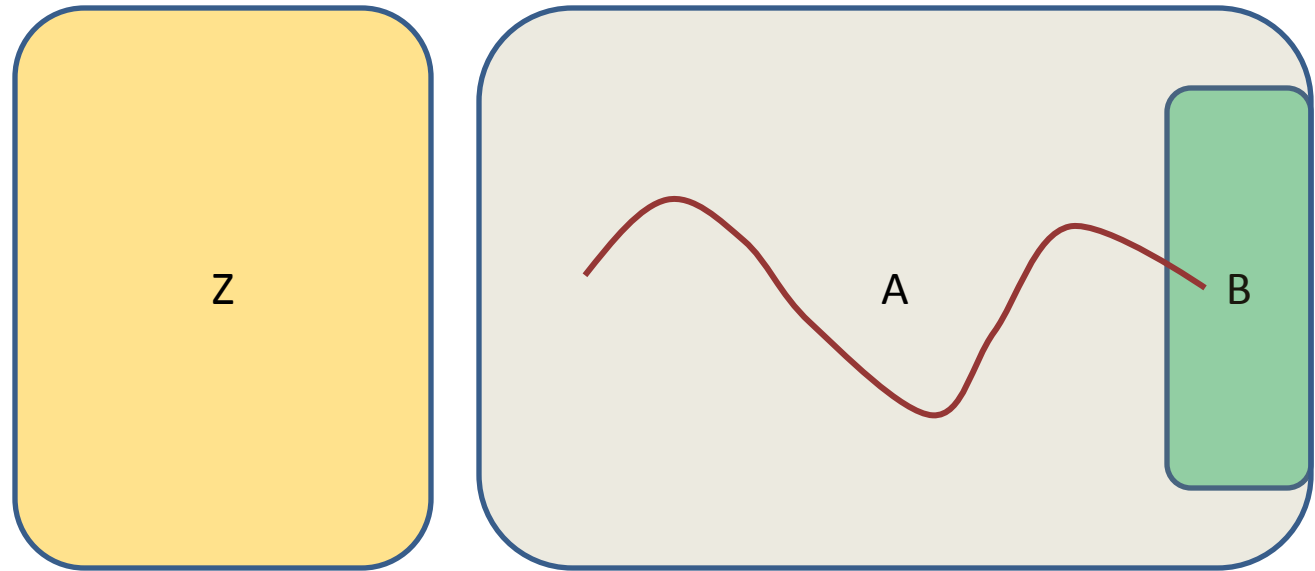
- The iteration stops. Let  $Z$  be the set of states removed overall iterations.
- Two key properties.

# Iterative Algorithm



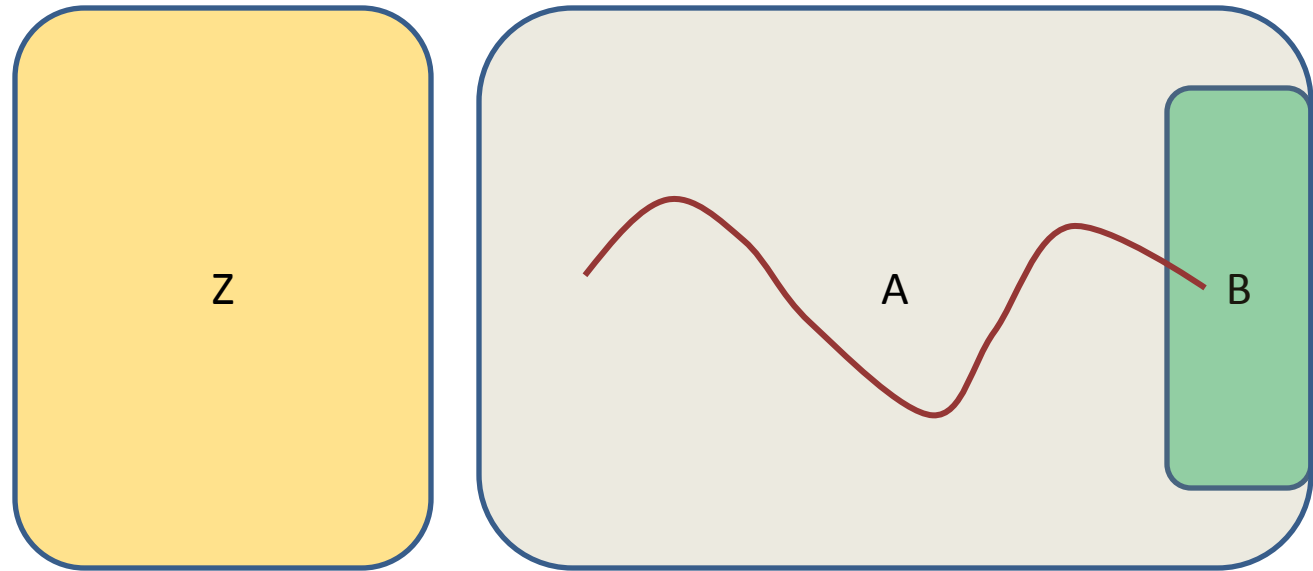
- The iteration stops. Let  $Z$  be the set of states removed overall iterations.
- Two key properties:
  - No probabilistic edge from outside to  $Z$ .

# Iterative Algorithm



- The iteration stops. Let  $Z$  be the set of states removed overall iterations.
- Two key properties:
  - No probabilistic edge from outside to  $Z$ .
  - From everywhere in  $A$  (the remaining graph) path to  $B$ .

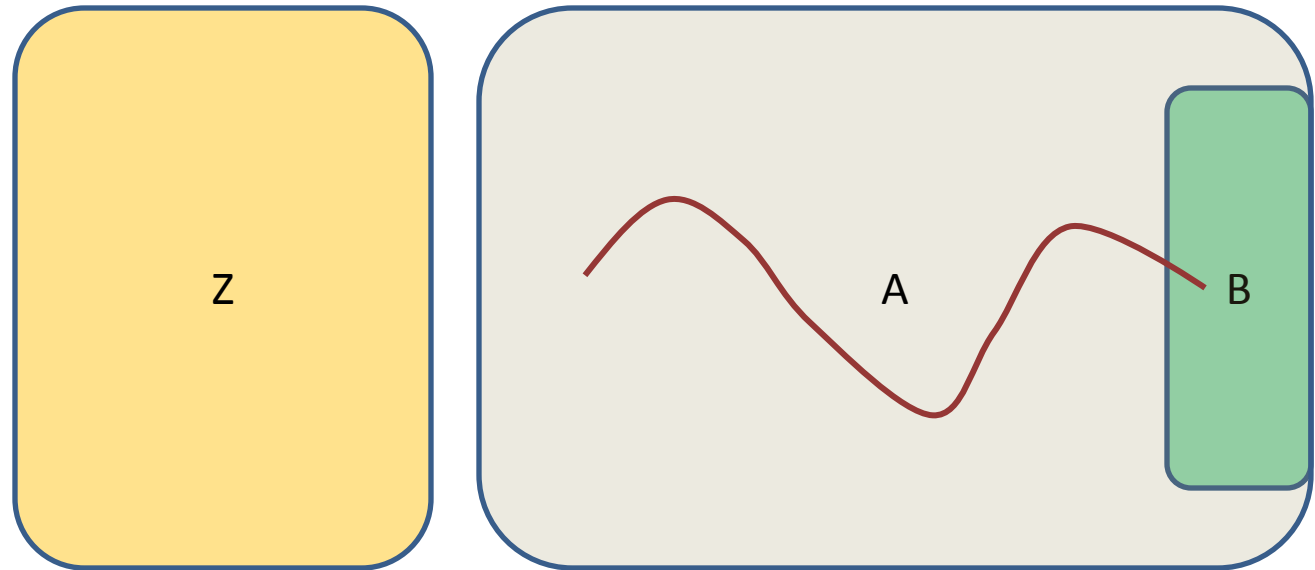
# Iterative Algorithm



- Two key properties:
  - No probabilistic edge from outside to Z.
  - From everywhere in A (the remaining graph) path to B.
- Fix a memoryless strategy as follows:
  - In  $A \setminus B$ : shorten distance to B. (Consider the BFS and choose edge).
  - In B: stay in A.

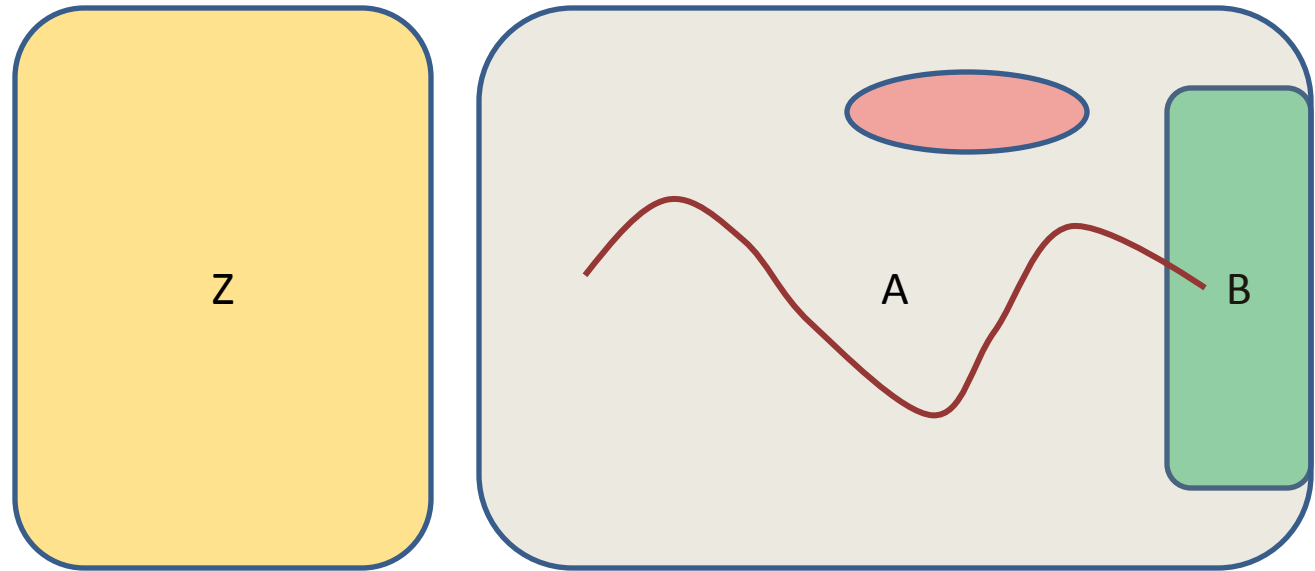


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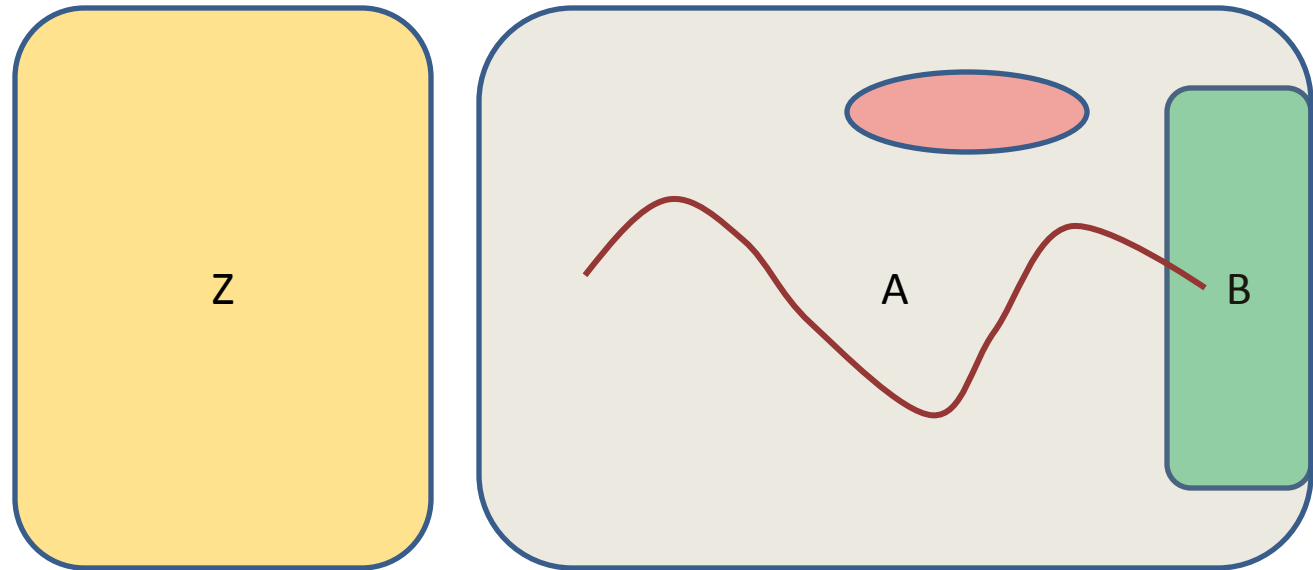
- Fix a memoryless strategy as follows:
  - In  $A \setminus B$ : shorten distance to  $B$ . (Consider the BFS and choose edge).
  - In  $B$ : stay in  $A$ .
- Argue all bottom scc's intersect with  $B$ . By Markov chain theorem done.

# Iterative Algorithm



- Argue all bottom scc's intersect with B. By Markov chain theorem done.
- Towards contradiction some bottom scc that does not intersect.
  - Consider the minimum BFS distance to B.

# Iterative Algorithm



- Argue all bottom scc's intersect with B. By Markov chain theorem done.
- Towards contradiction some bottom scc that does not intersect.
  - Consider the minimum BFS distance to B.
    - Case 1: if a state in  $S_p$ , all edges must be there and so must be the one with shorter distance.
    - Case 2: if a state in  $S_1$ , then the successor chosen has shorter distance.
    - In both cases we have a contradiction.

# Iterative Algorithm

- Time complexity is  $O(n m)$ .
- Pure memoryless almost-sure winning strategy.
- Exercise: extend it to parity with time complexity  $O(n m d)$ .
- We are now done with qualitative analysis. We will now argue how to reduce quantitative analysis to quantitative reachability.

# Quantitative Parity to Quantitative Reachability

- **End-components:** An end-component generalizes both scc and closed recurrent set. A set  $U$  is an end-component if the following properties hold:
  - $U$  is strongly connected.
  - $U$  is closed (no probabilistic edge out).
- Note that player 1 edges may leave the end-component.
- Why is end-component important: it allows us to reason about infinite behaviors.

# End Component Property

- **End-component property:** For an MDP and for all strategies, with probability 1 the set of states visited infinitely often is an end-component.
- Generalizes the scc for graphs and closed recurrent set for Markov chains.
- **Proof:**
  - Shape of the proof very similar to closed recurrent set.
  - We need to show that if a set  $U$  is not an end-component, then cannot be visited infinitely often with positive probability.
  - Assume towards contradiction that there is such a set  $U$ .

# End Component Property

- **End-component property:** For an MDP and for all strategies, with probability 1 the set of states visited infinitely often is an end-component.
- **Proof:**
  - We need to show that if a set  $U$  is not an end-component, then cannot be visited infinitely often with positive probability.
  - Assume towards contradiction that there is such a set  $U$ .
  - $U$  must be strongly connected.
  - Since  $U$  is not end-component, some probabilistic state  $s$  with an edge to  $t$  going out of  $U$  with probability  $\alpha$ .
  - Hence the probability that  $s$  is visited infinitely often, but the edge to  $t$  is taken finitely often is 0.
  - The result follows.

# Winning End-component

- An end-component  $U$  is winning if the minimum priority of  $U$  is even.
- From end-component property for any strategy the probability to satisfy parity is the probability to reach the winning end-components.
- In winning end-components pure memoryless almost-sure winning strategy exists.
  - Proof: Choose successor to shorten distance to the minimum even priority state.



# Quantitative Parity to Quantitative Reachability

- The probability to satisfy is the probability to reach winning end-components.
- In winning end-components pure memoryless almost-sure strategy.
- Winning end-components are included in the almost-sure winning set.
- Hence we need quantitative reachability to almost-sure winning set.
- We now need the quantitative reachability to complete the argument.

# Quantitative Reachability

- An MDP  $G$ , and a target set  $T$ .
- $\text{Val}(\text{Reach}(T))(s) = \sup_{\sigma} \Pr_s^{\sigma}(\text{Reach}(T))$ .
- $v(s)$  for abbreviation.
- Two properties:
  - Property 1: For  $s \in S_p$  we have  $v(s) = \sum_{t \in S} v(t) * \delta(s)(t)$ .
  - Property 2: For  $s \in S_1$  we have  $v(s) = \max \{ v(t) \mid t \in E(s) \}$ .

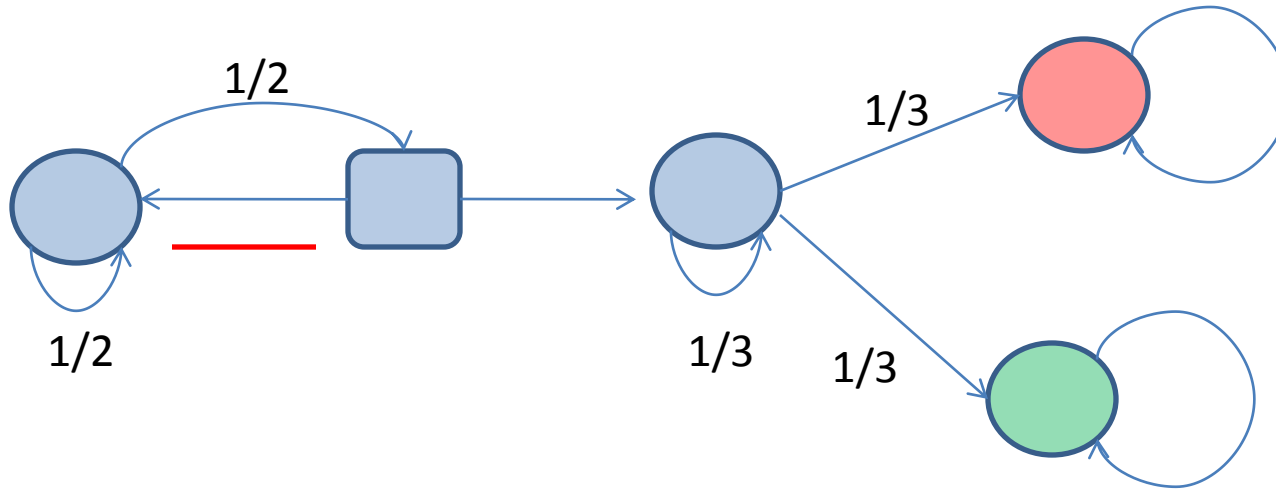
# Proof of Property 2

- Inequality 1:  $v(s) \geq \max\{v(t) \mid t \in E(s)\}$ 
  - Fix  $\epsilon > 0$ .
  - Let  $t^*$  be the arg max.
  - From  $s$  choose  $t^*$ , and then an  $\epsilon$  optimal strategy from  $t^*$  to ensure value at least  $v(t^*) - \epsilon$ .
  - As  $\epsilon > 0$  is arbitrary, the result follows.
  
- Inequality 2.  $v(s) \leq \max\{v(t) \mid t \in E(s)\}$ 
  - We have
    - $v(s) \leq \sup_{\mu} \sum_{t \in S} v(t)^* \mu(t) \leq \max\{v(t) \mid t \in E(s)\}$ ,  
where  $\mu \in D(E(s))$ .

# A Simple Attempt

- For a state  $s$  choose a successor that achieves the maximum.
- However this simple construction is not sufficient.

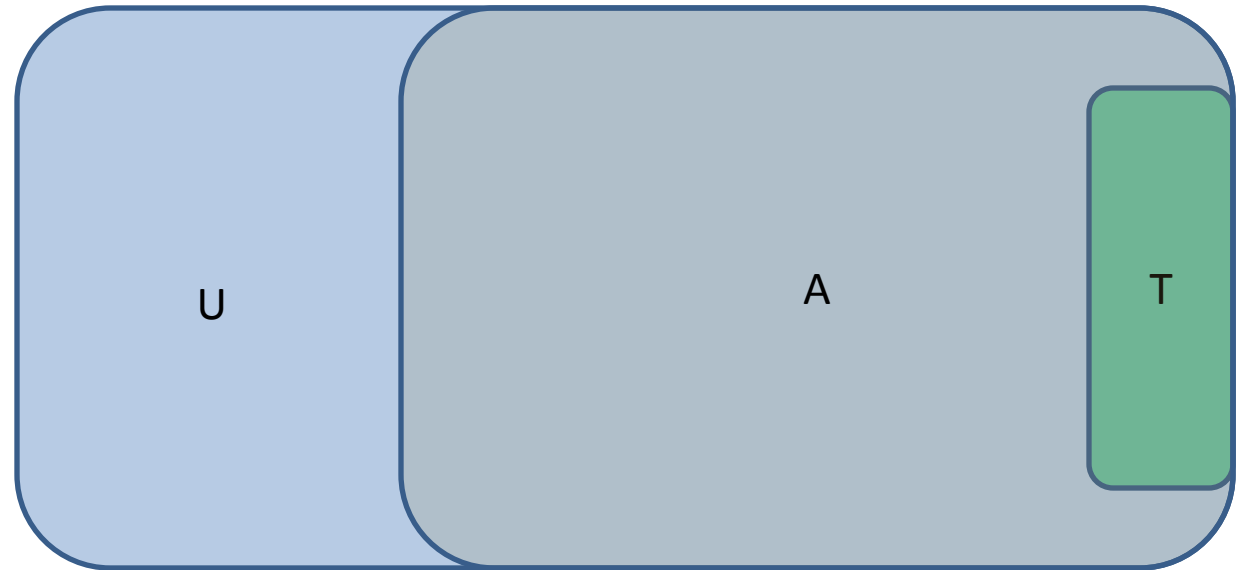
# MDP: Simple Fails



In all blue states the value is  $\frac{1}{2}$ .

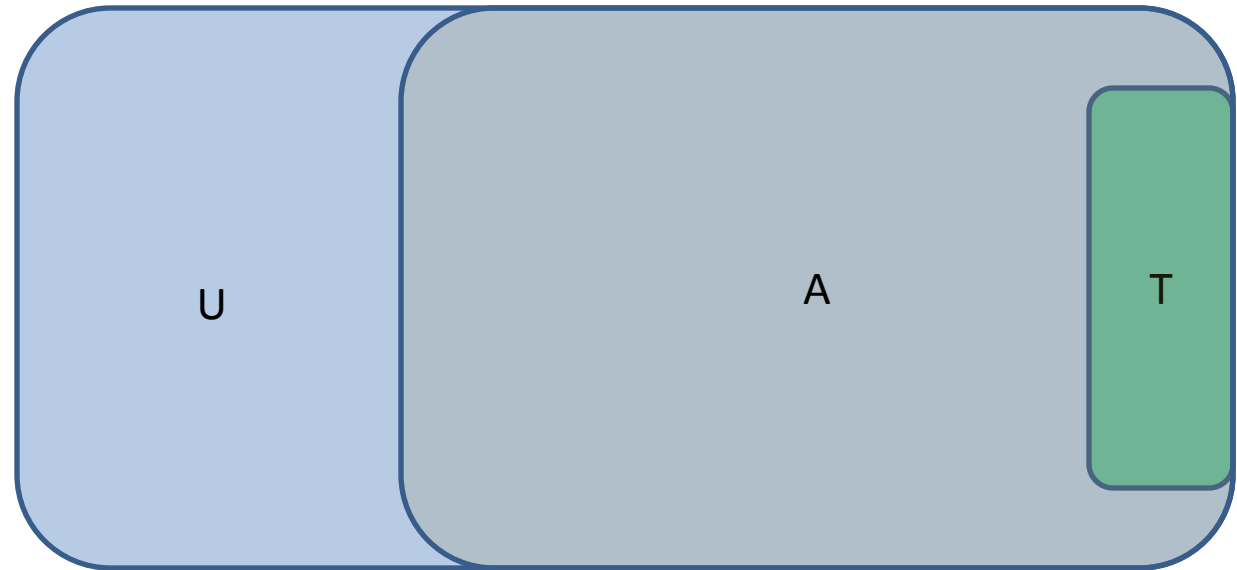
However the choice of red edge is bad.

# Quantitative Reachability



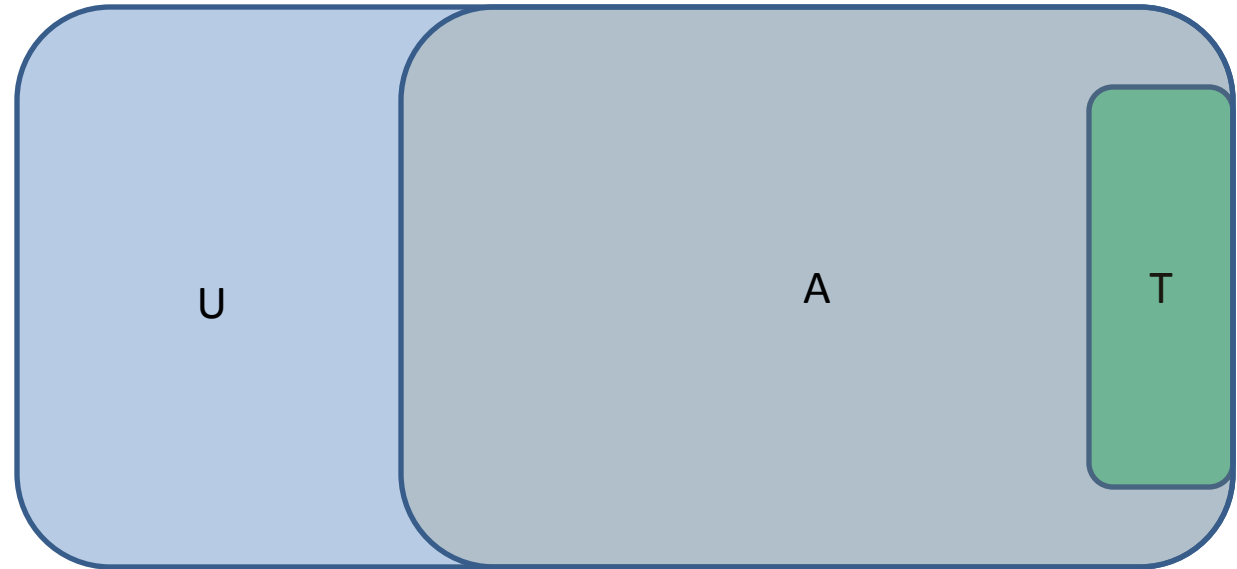
- Original MDP is connected.
- Compute simple reachability to T.
- From U, there is no path so value is 0.
- From A, the value is positive everywhere as there is a path.

# Quantitative Reachability



- From U, there is no path so value is 0.
- From A, the value is positive everywhere as there is a path.
- Retain only the edges that attains the max in A (remove all the other). Make U and T absorbing.
- Easy to show that there is still path to T from A.
- Choose the edge that shortens distance to T.

# Quantitative Reachability



- Retain only the edges that attains the max in A (remove all the other). Make U and T absorbing.
- Easy to show that there is still path to T from A.
- Choose the edge that shortens distance to T.
- Markov chain where all closed recurrent states are U or T.
- The values  $v(s)$  satisfies the Markov chain equality. Hence the memoryless strategy achieves  $v(s)$ .



# Quantitative Reachability

- An MDP  $G$ , and a target set  $T$ .
- $\text{Val}(\text{Reach}(T))(s) = \sup_{\sigma} \text{Pr}_s^{\sigma}(\text{Reach}(T))$ .
- Existence of pure memoryless optimal strategies.
- Algorithm: Linear programming. Variable  $x_s$  for all states  $s$ .
  - $x_s = 0$   $s \in U$
  - $x_s = 1$   $s \in T$
  - $x_s = \sum_{t \in S} x_t * \delta(s)(t)$   $s \in S_p$
  - $x_s = \max_{t \in E(s)} x_t$   $s \in S_1$ .

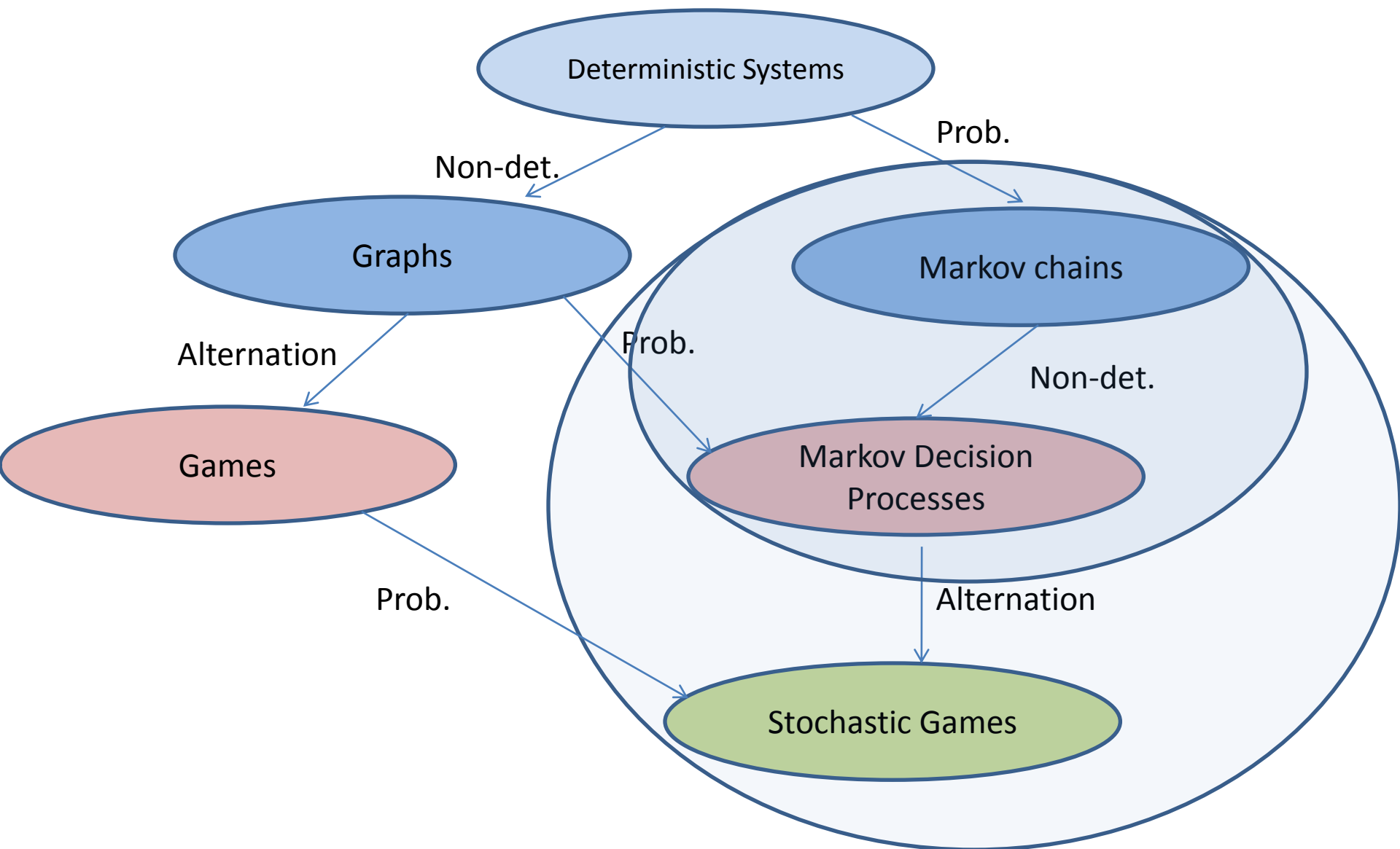
# Quantitative Reachability

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  - $x_s = \max_{t \in E(s)} x_t$   $s \in S_1$ .
- The above optimization to linear program
  - Objective function:  $\min \sum_{t \in S} x_t$
  - $x_s \geq x_t$   $s \in S_1, t \in E(s)$ .

# MDP Summary

	Reachability	Liveness	Parity
Qualitative	$O(n \cdot m)$	$O(n \cdot m)$	$O(n \cdot m \cdot d)$
Quantitative	Linear programming	Linear programming	Linear programming

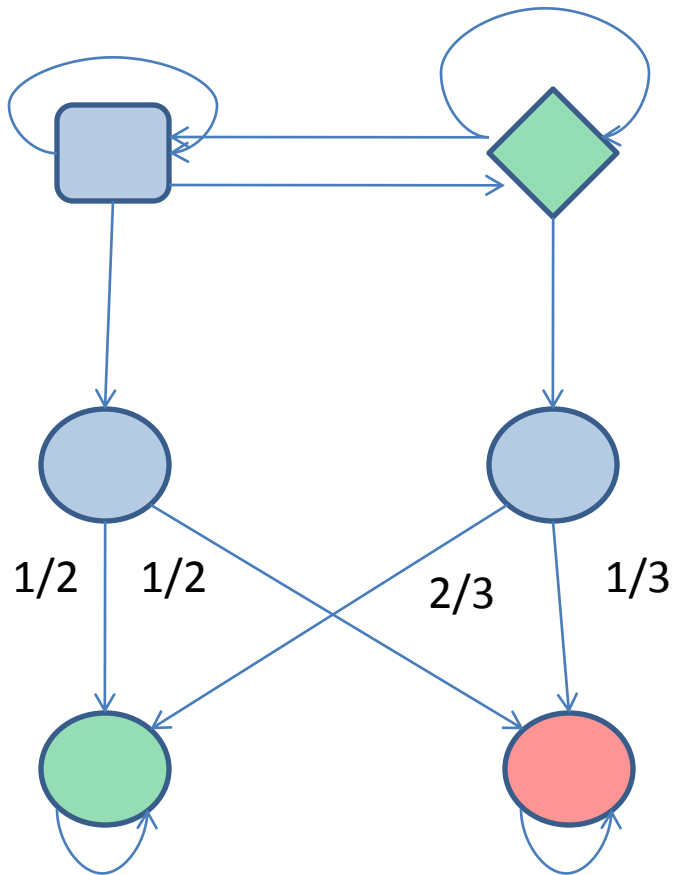
# Stochastic Games



# Stochastic Games

- Stochastic games
  - Non-determinism: angelic vs. demonic non-determinism (alternation).
  - Probability.
  - Generalizes non-deterministic systems and Markov chains, alternating games, MDPs.
- An MDP  $G = ((S, E), (S_1, S_2, S_P), \delta)$ 
  - $\delta : S_P \rightarrow D(S)$ .
  - For  $s \in S_P$ , the edge  $(s, t) \in E$  iff  $\delta(s)(t) > 0$ .
  - $E(s)$  out-going edges from  $s$ , and assume  $E(s)$  non-empty for all  $s$ .

# Stochastic Game



Example of stochastic game.

Objective for player 1 is to visit green infinitely often

# Strategies

- Strategies are recipe how to move tokens or how to extend plays. Formally, given a history of play (or finite sequence of states), it chooses a probability distribution over out-going edges.
  - $\sigma: S^* S_1 \rightarrow D(S)$ .
  - $\pi: S^* S_2 \rightarrow D(S)$ .

# Strategies

- Strategies are recipe how to move tokens or how to extend plays. Formally, given a history of play (or finite sequence of states), it chooses a probability distribution over out-going edges.
  - $\sigma: S^* S_1 \rightarrow D(S)$ .
- History dependent and randomized.
- History independent: depends only current state (memoryless or positional).
  - $\sigma: S_1 \rightarrow D(S)$
- Deterministic: no randomization (pure strategies).
  - $\sigma: S^* S_1 \rightarrow S$
- Deterministic and memoryless: no memory and no randomization (pure and memoryless and is the simplest class).
  - $\sigma: S_1 \rightarrow S$
- Same notations for player 2 strategies  $\pi$ .

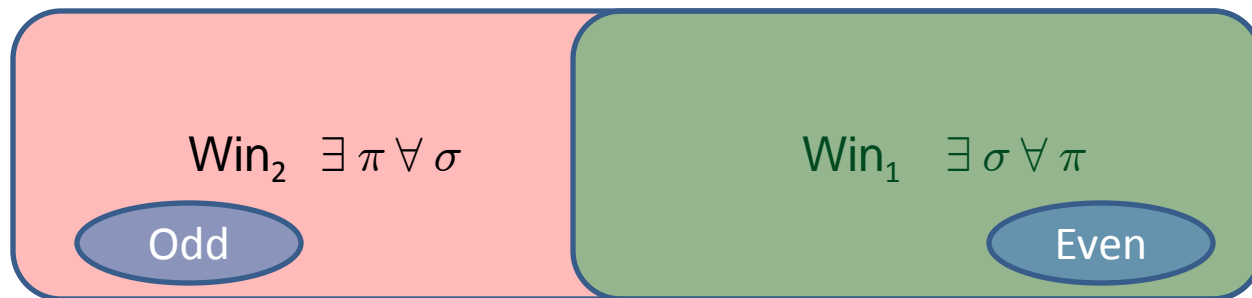


# Values in Stochastic Games

- Value at a state for an objective  $\psi$ 
  - $\text{Val}(\psi)(s) = \sup_{\sigma} \inf_{\pi} \Pr_s^{\sigma, \pi}(\psi)$ .
- Qualitative analysis
  - Compute the set of almost-sure (prob 1) winning states (i.e., set of states with value 1).
- Quantitative analysis
  - Compute the value for all states.
- Determinacy: the order of sup inf can be exchanged.

# Non-Stochastic Games

- There are no probabilistic states.
- Non-stochastic games with parity objectives
  - Values only 0 or 1.
  - Pure memoryless winning strategies exist.
  - Once a pure memoryless strategy is fixed all cycles winning.

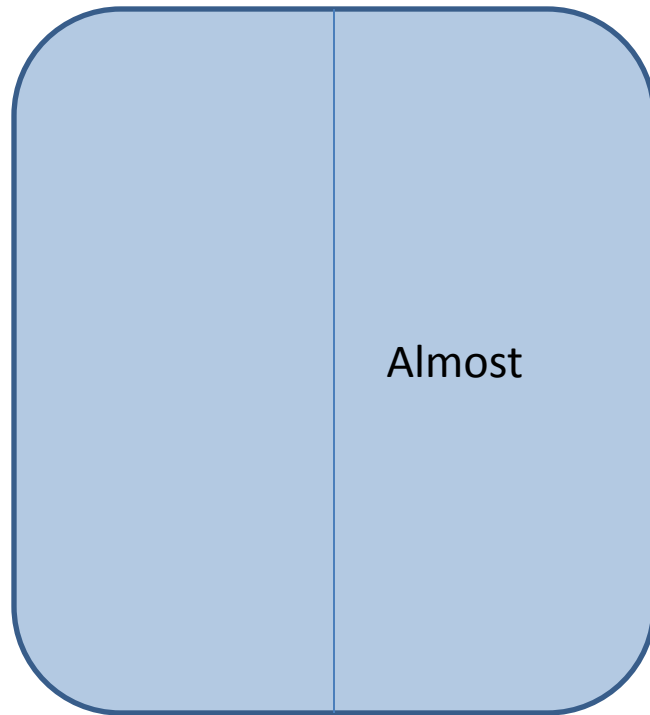


# Qualitative and Quantitative Analysis

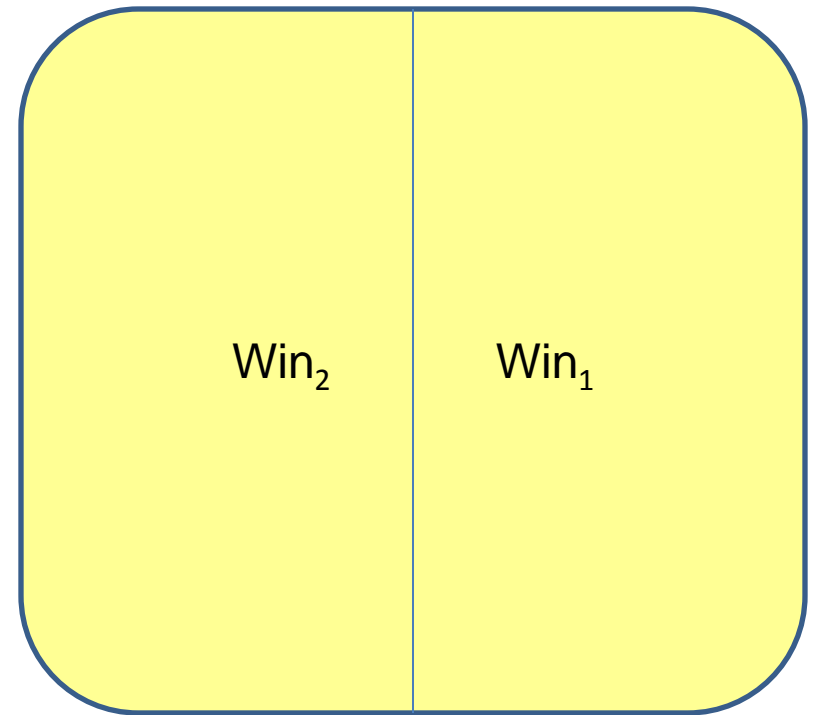
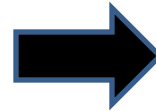
- Qualitative analysis
  - Reduction to games without probability.
  - Use existence of pure memoryless strategies in games with probability for parity objectives.
  - Show it for Liveness and can be extended to parity.
- Quantitative analysis
  - Combine notion of qualitative and local optimality for quantitative optimality.

# Qualitative Analysis

- Reduction



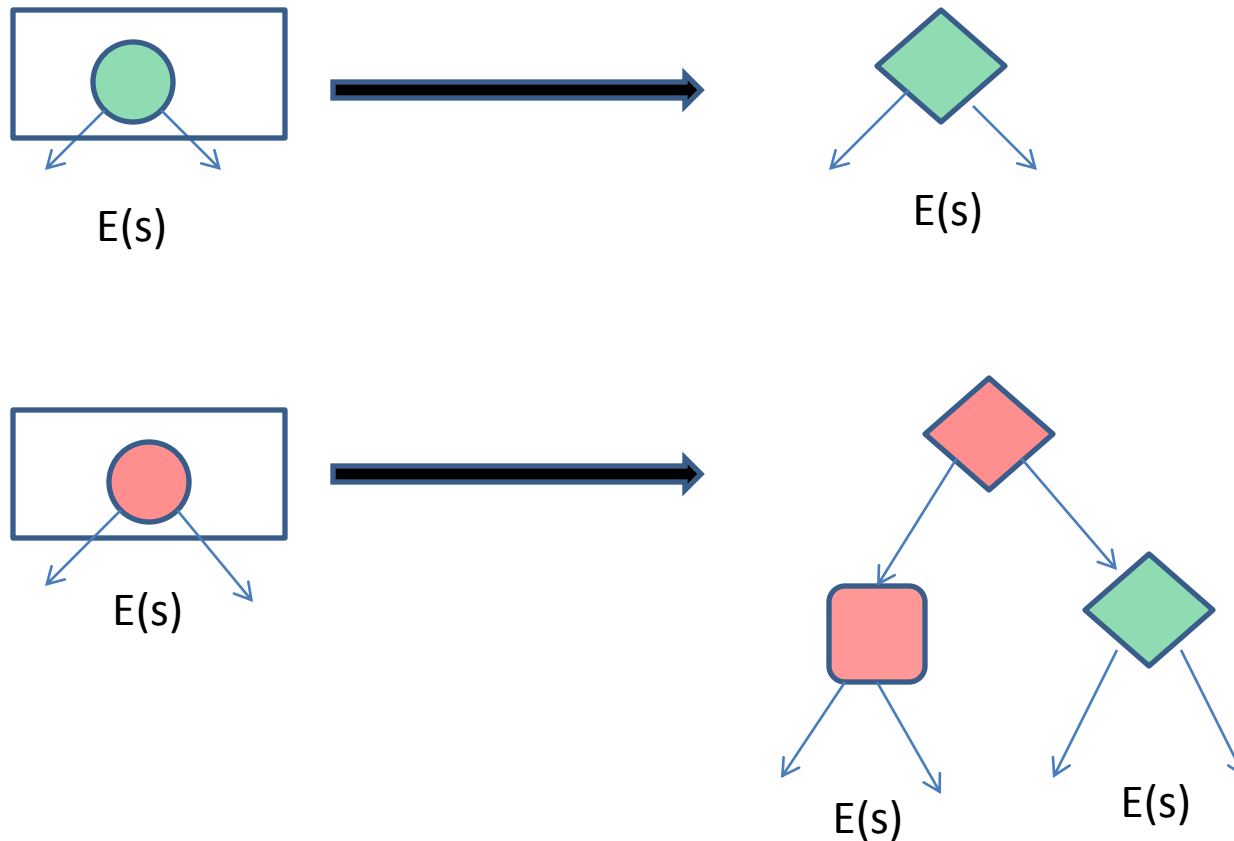
Stochastic Game



Non stochastic game

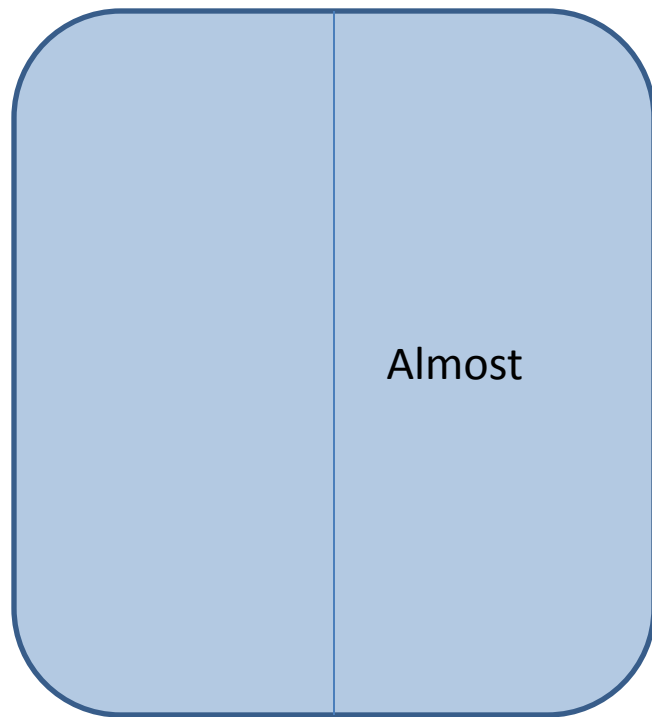
# Reduction

- Replace every probabilistic state by two-player gadget. Illustrate it for Liveness.

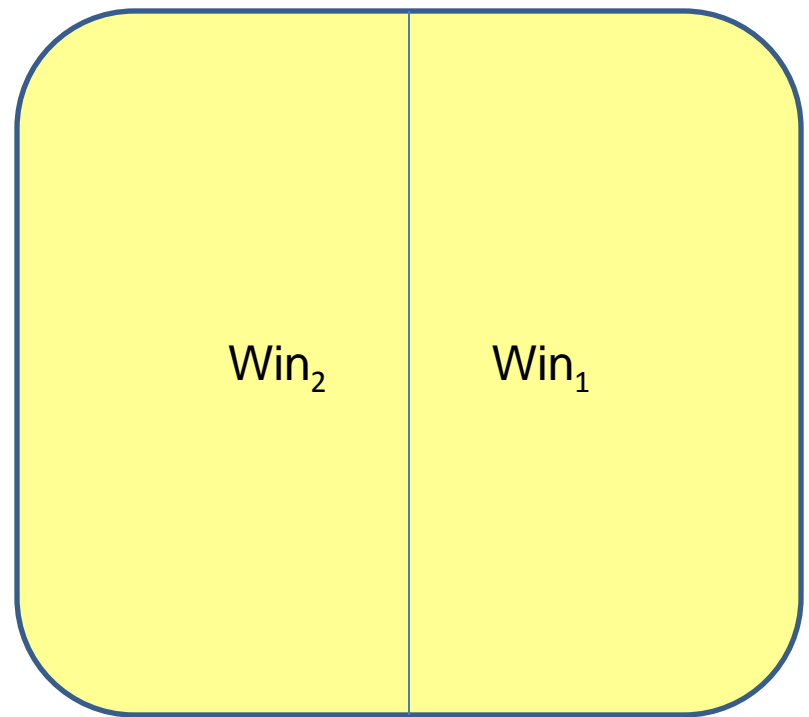
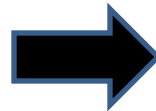


# Qualitative Analysis

- Reduction: the end-components are winning.



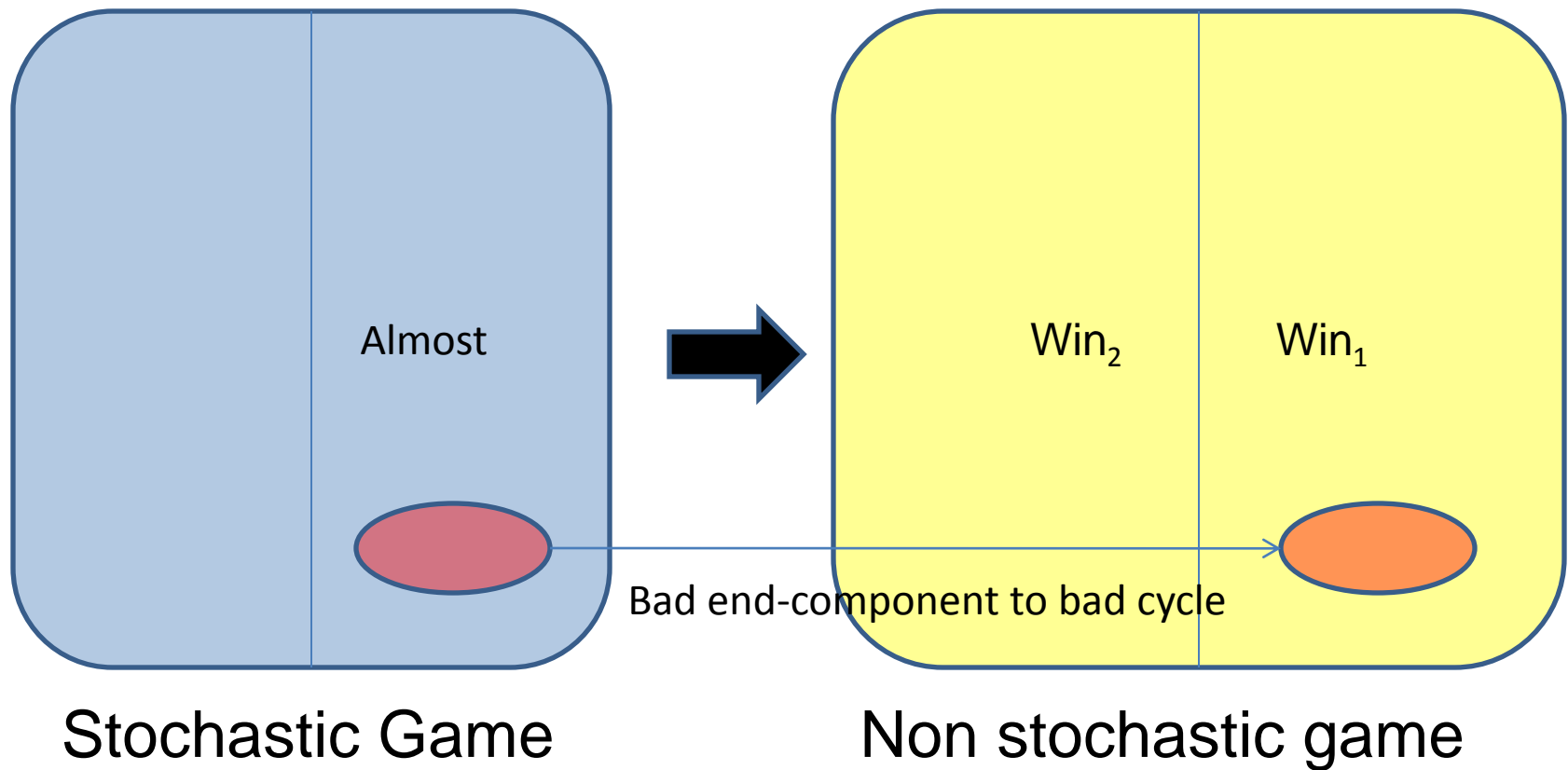
Stochastic Game



Non stochastic game

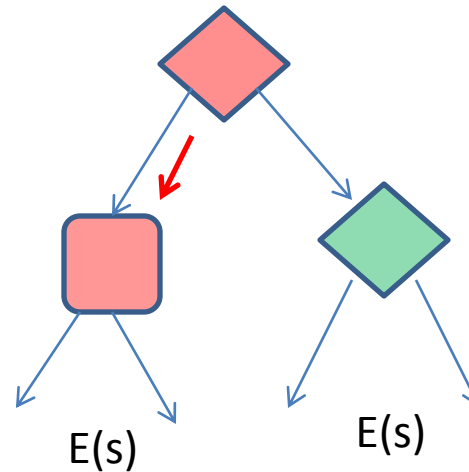
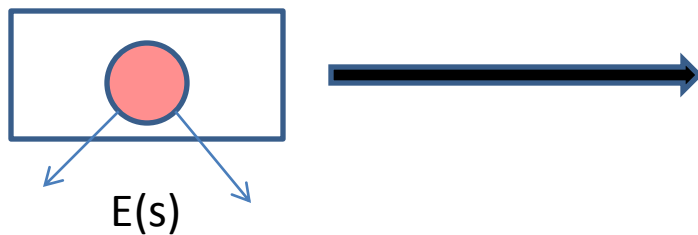
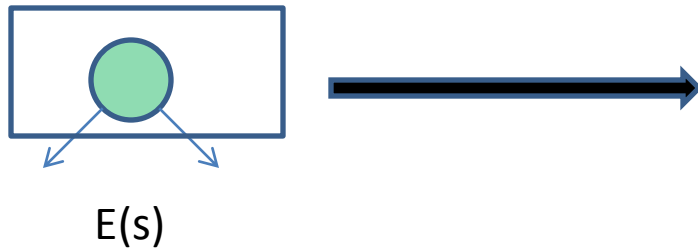
# Qualitative Analysis

- Reduction: the end-components are winning.



# Reduction

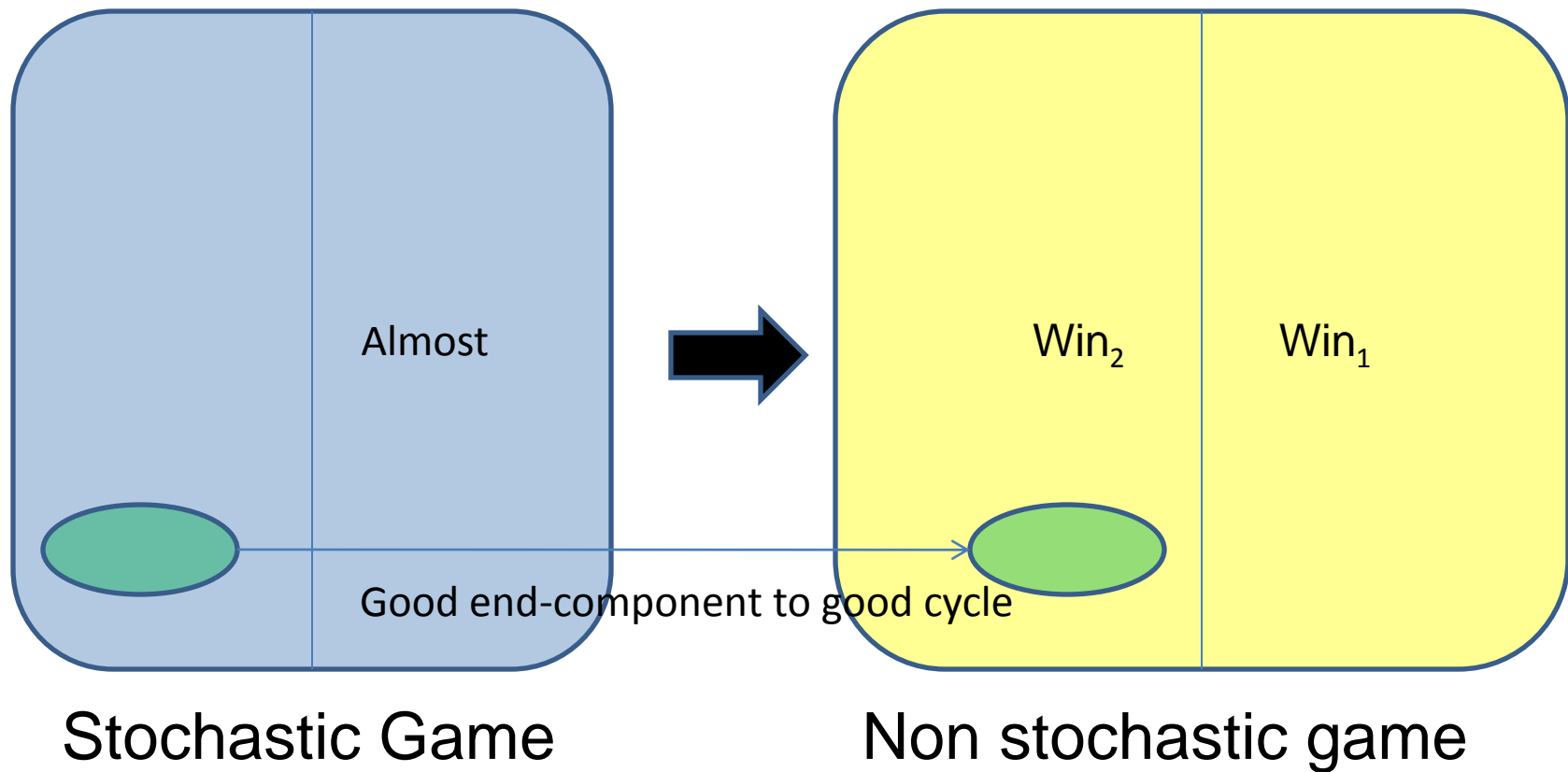
- Choice in the gadget





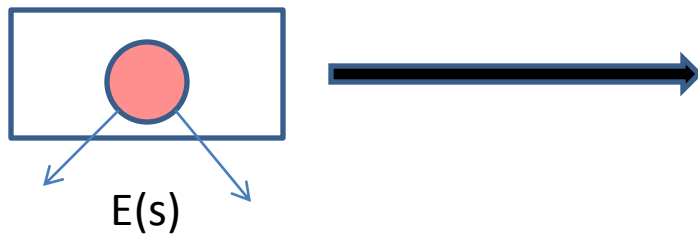
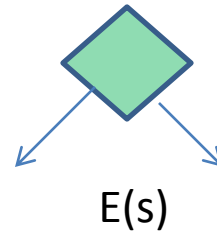
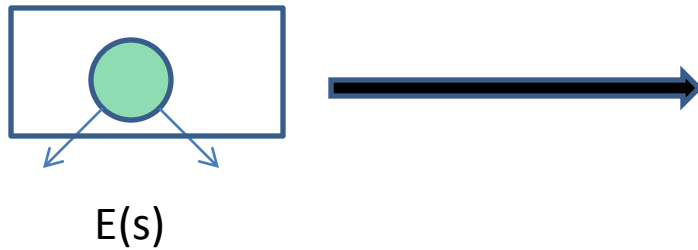
# Qualitative Analysis

- Reduction: the end-components are winning.

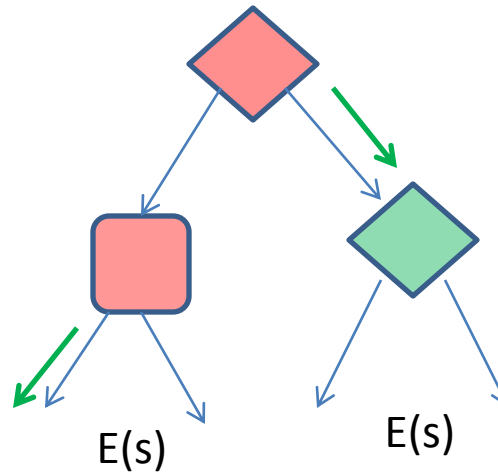


# Reduction

- Choice in the gadget

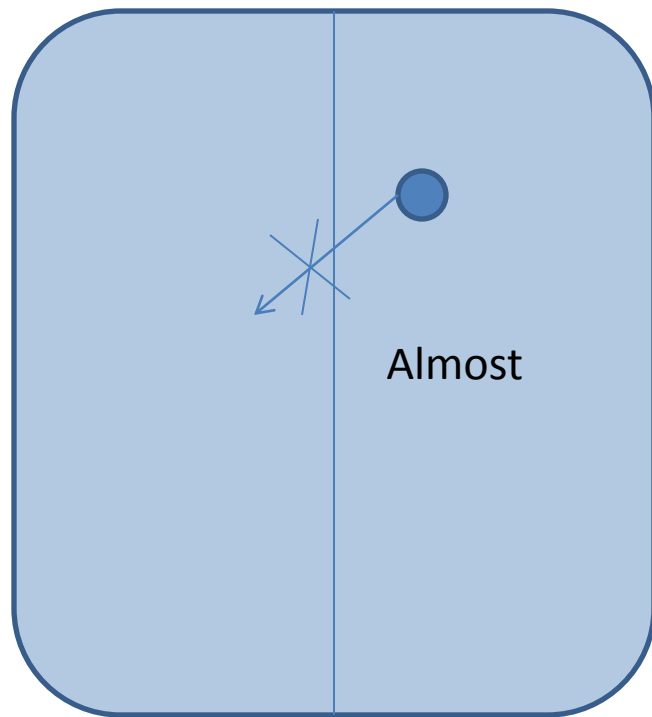


Shorten distance to green

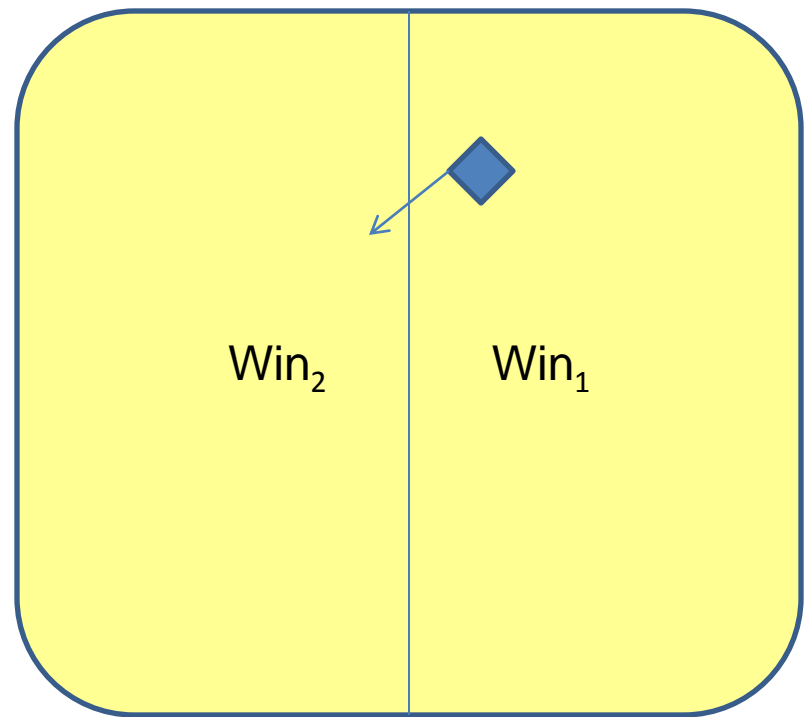
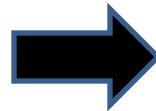


# Qualitative Analysis

- Reduction: the end-components are winning.



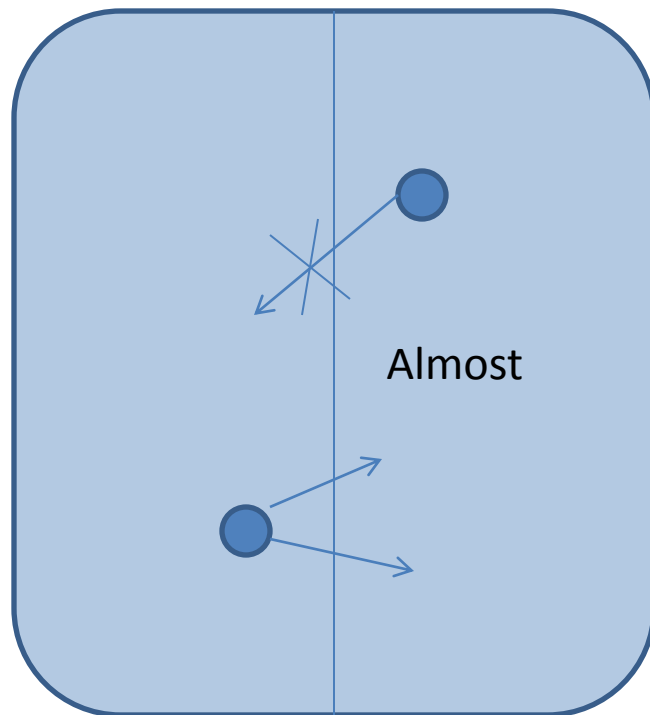
Stochastic Game



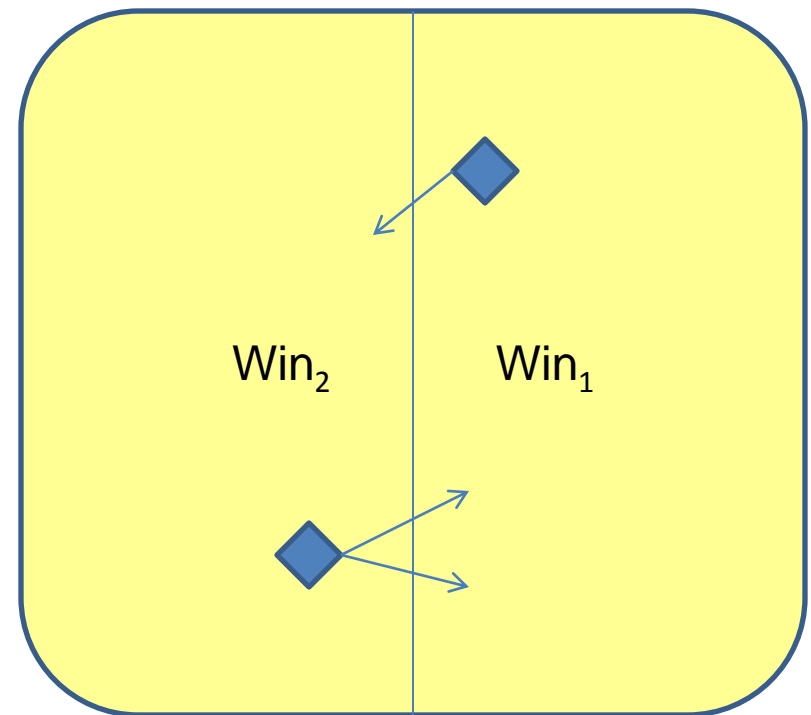
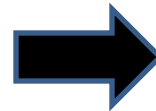
Non stochastic game

# Qualitative Analysis

- Reduction: the end-components are winning.



Stochastic Game



Non stochastic game

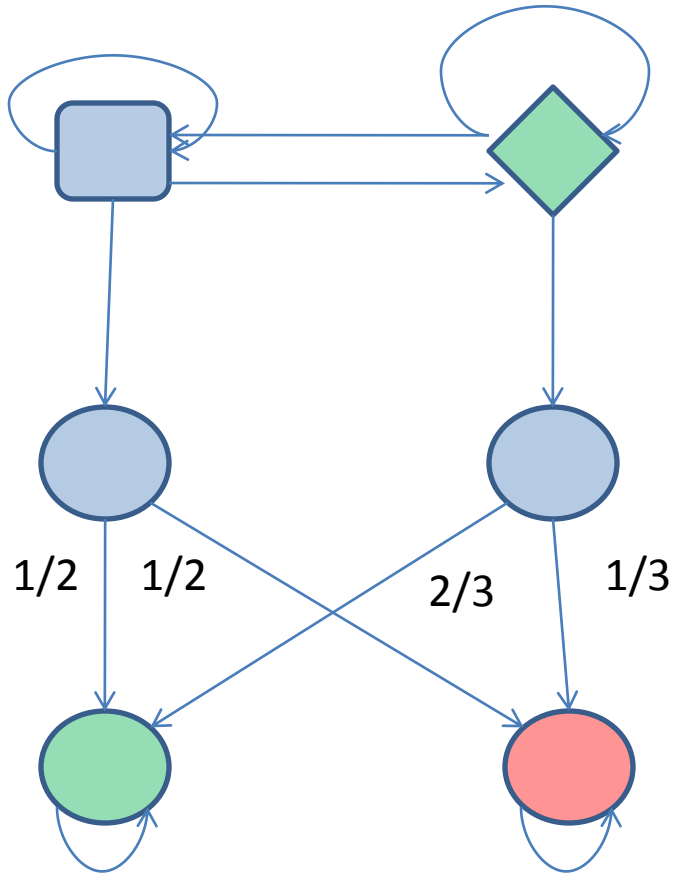
# Reduction

- Gadget based reduction can be extended to parity.
- Qualitative analysis
  - Pure memoryless almost-sure strategies exists.
  - Linear time reduction to non-stochastic games.
  - Same complexity:  $NP \cap coNP$ .
  - All algorithms can be used.

# Quantitative Analysis

- Unlike MDPs, we cannot do the following:
  - Compute almost-sure winning states.
  - Compute quantitative reachability to almost-sure winning states.
  - We illustrate with an example.

# Stochastic Game



Example of stochastic game.

Objective for player 1 is to visit green infinitely often

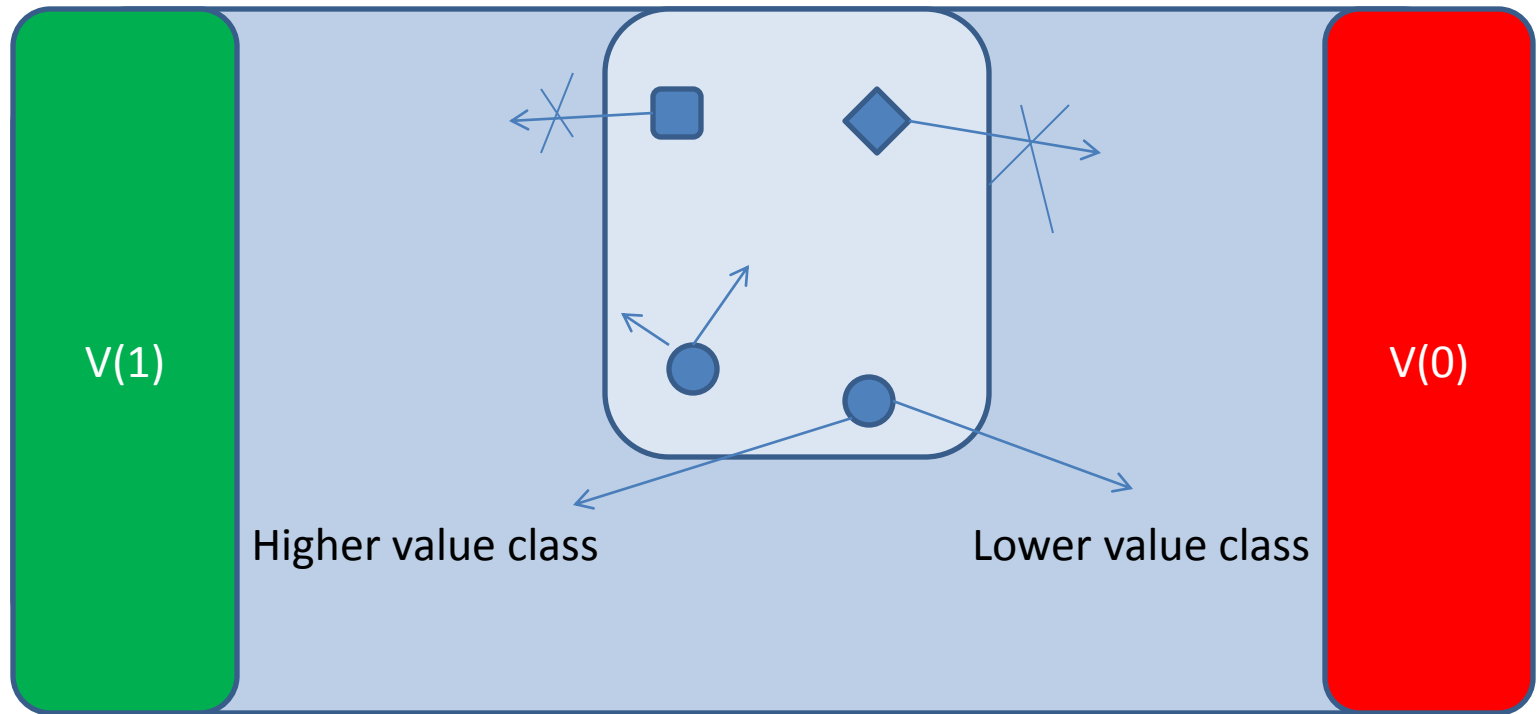
Cannot ensure to reach green absorbing with prob  $2/3$ .

# Quantitative Analysis

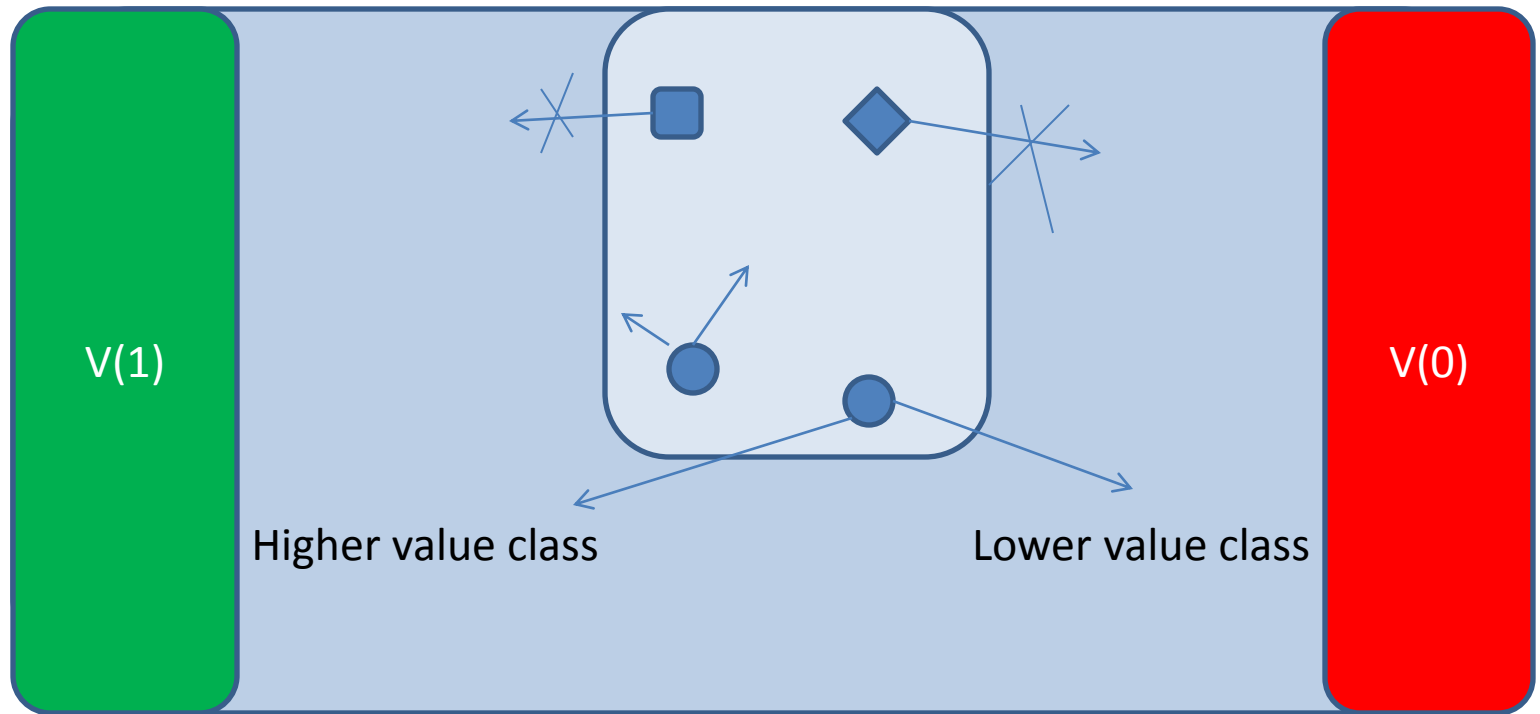
- Quantitative optimality
  - Local optimality
  - Qualitative optimality
- Value class: the set of states with same value.  
 $V(r)$  is the set of states with value  $r$ .



# Value Class Property



# Value Class: Boundary Probabilistic States



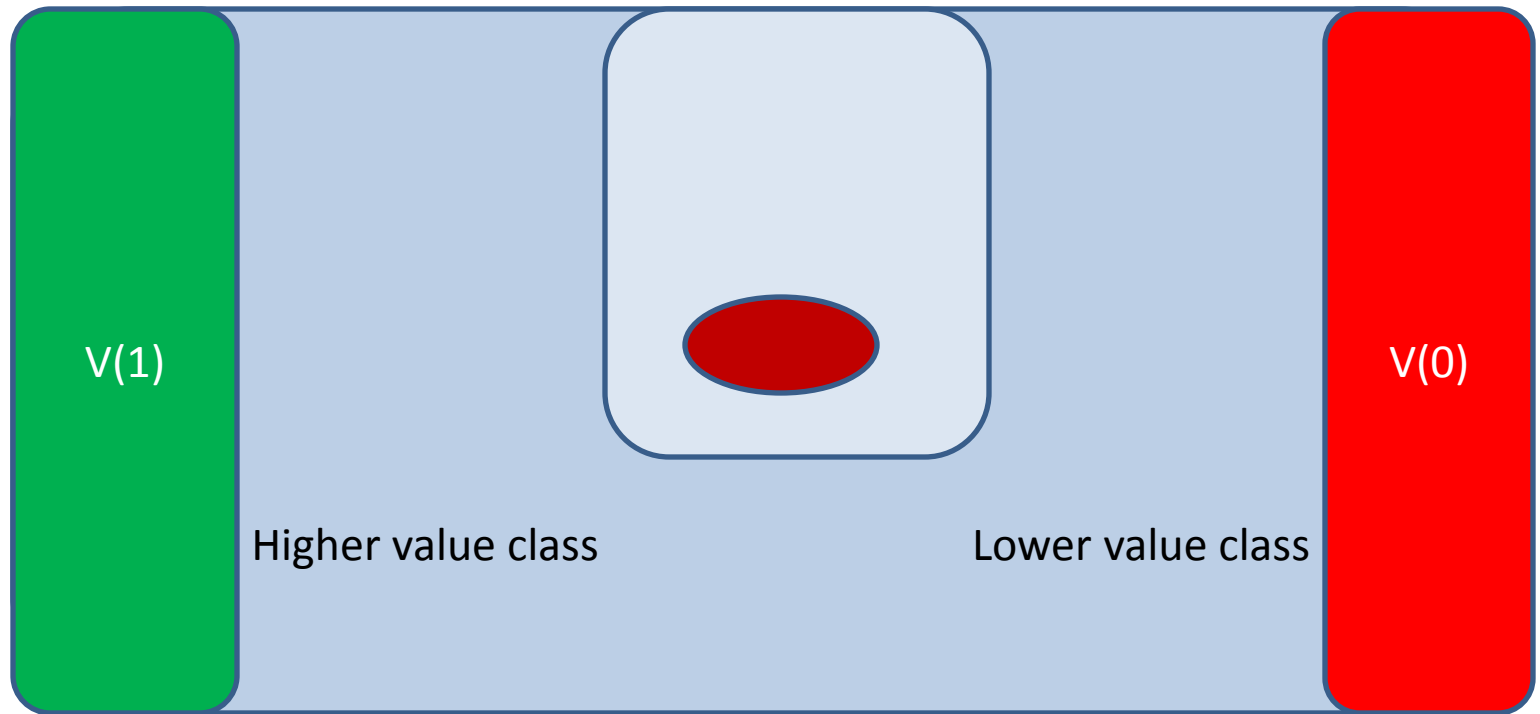
# Value Class Reduction

- Remove edges going out to lower value class (local optimality).
- Change boundary probabilistic states to winning states for player 1.
- Claim: In this sub-game player 1 wins almost-surely everywhere.

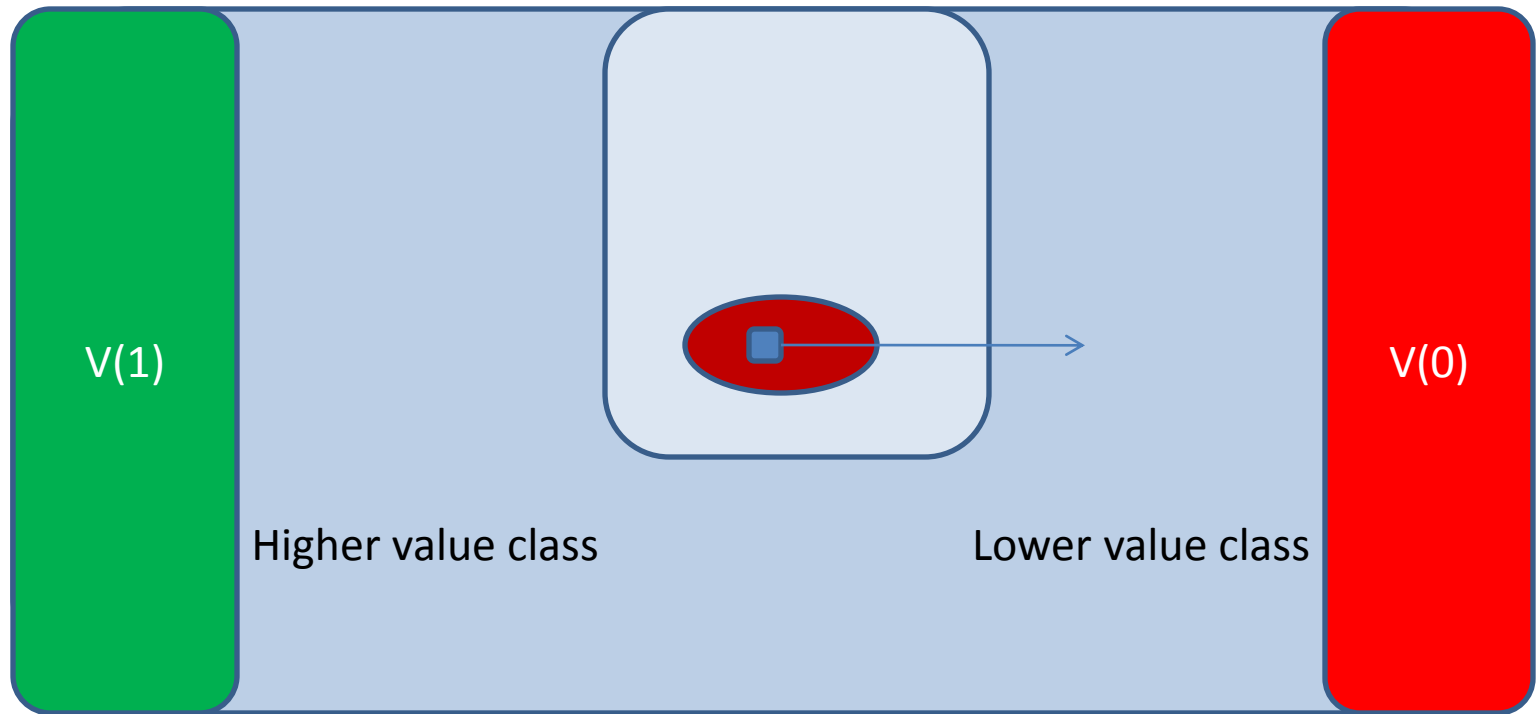
# Sub-game Qualitative Optimality

- Claim: Player 1 wins almost-surely.
- Proof: Suppose not.
  - Then player 2 wins with positive probability somewhere.
  - Player 2 wins almost-surely somewhere.
  - Player 1 if stays in the value class loses with probability 1 or else jumps to a lower value class.
  - Contradiction.

# Value Class: Boundary Probabilistic States



# Value Class: Boundary Probabilistic States



# Value Class Property

- In value classes if we assume boundary probabilistic vertices winning for player 1 then player 1 wins almost surely.
- Conditional almost-sure winning strategies.
- **Stitching lemma**: Compose them to get a optimal strategy.

# Stitching Lemma

- Proof idea:
  - If the game stays in some value class player 1 wins with probability 1.
  - Else it leaves the value class through the boundary probabilistic vertex or goes to a higher value class.
  - Invoke sub-martingale Theorem or use results from MDPs.



# Quantitative Analysis

- Pure memoryless optimal strategies exist.
- Complexity bound
  - $NP \cap coNP$ .
- Algorithms: Strategy improvement algorithms, uses qualitative algorithms and local optimality.

# Stochastic Games Summary

	Reachability	Liveness	Parity
Qualitative	$O(n \cdot m)$	$O(n \cdot m)$	$NP \cap coNP$  Linear reduction to non-stochastic parity
Quantitative	$NP \cap coNP$	$NP \cap coNP$	$NP \cap coNP$

# Summary and Messages

- Markov chains
  - Qualitative: Linear time algorithm through closed recurrent states (bottom scc's).
  - Quantitative analysis: Linear equalities, Gaussian elimination.
- MDPs
  - Qualitative: Iterative algorithm.
  - Quantitative: Reduction to quantitative reachability using end-components.
  - Quantitative reachability: Linear programming.
- Stochastic games
  - Qualitative: Reduction to non-stochastic games.
  - Quantitative: Qualitative and local optimality.

# Extensions

- Perfect-information    turn-based    finite    state  
stochastic games
  - Infinite state games: pushdown games, timed games.
  - Concurrent games: simultaneous interaction.
  - Imperfect-information games.

# CONCURRENT GAMES

# Games on Graphs

Games on graphs:

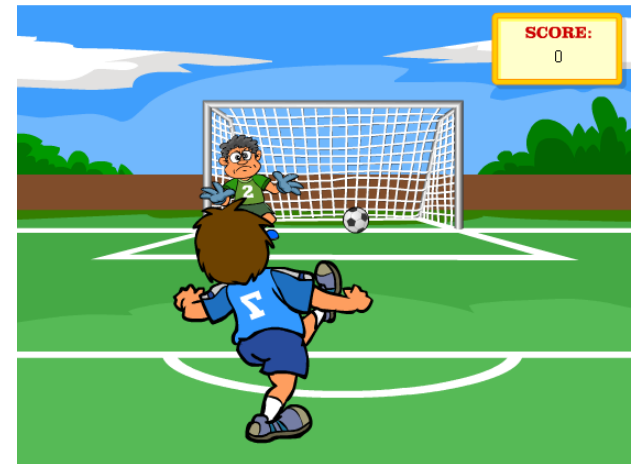
1. Turn-based:

- Chess.
- Tic-tac-toe.



2. Concurrent:

- Penalty Shoot-out.
- Rock-paper-scissor.

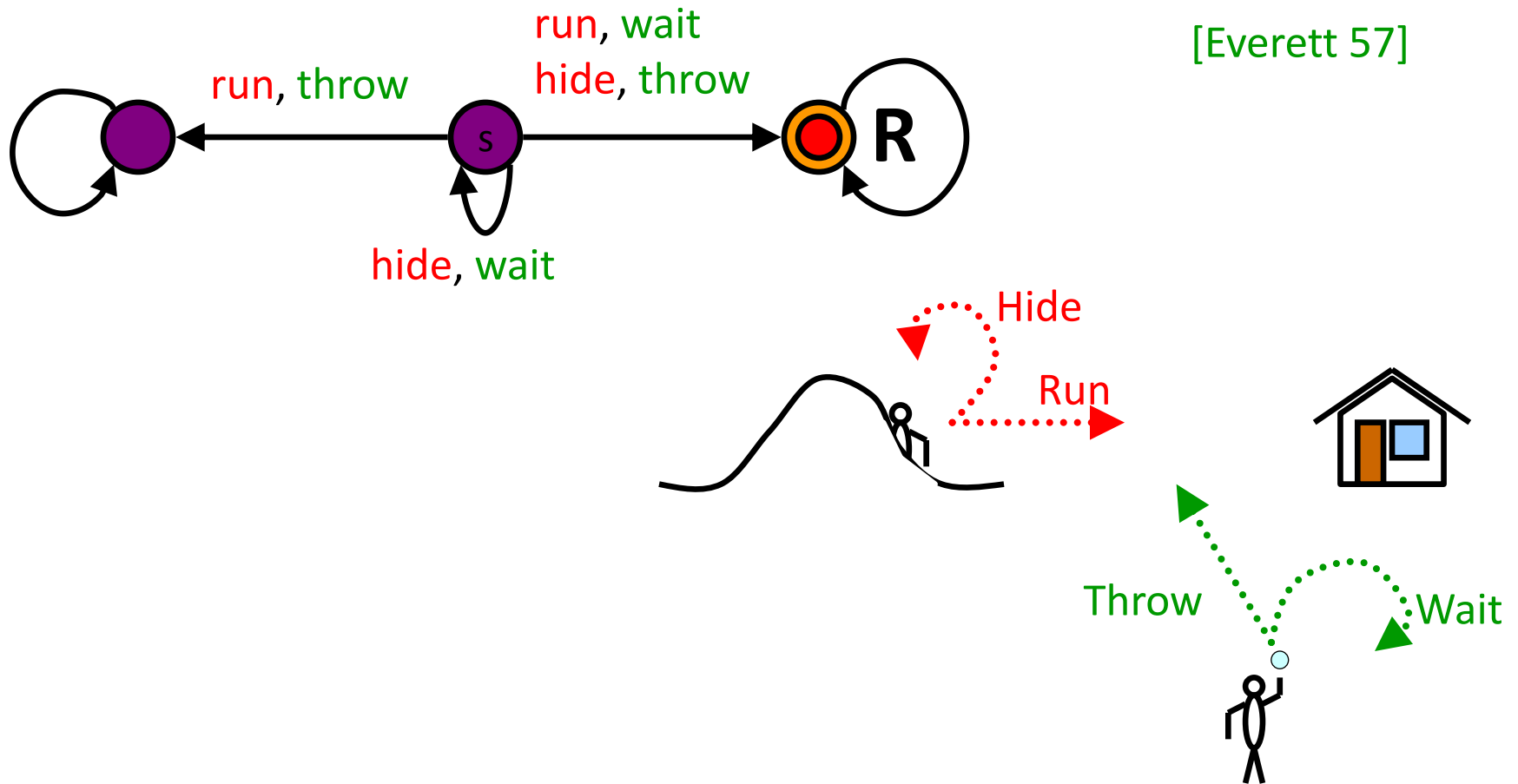


# Concurrent Game Graphs

A concurrent game graph is a tuple  $G = (S, M, \Gamma_1, \Gamma_2, \delta)$

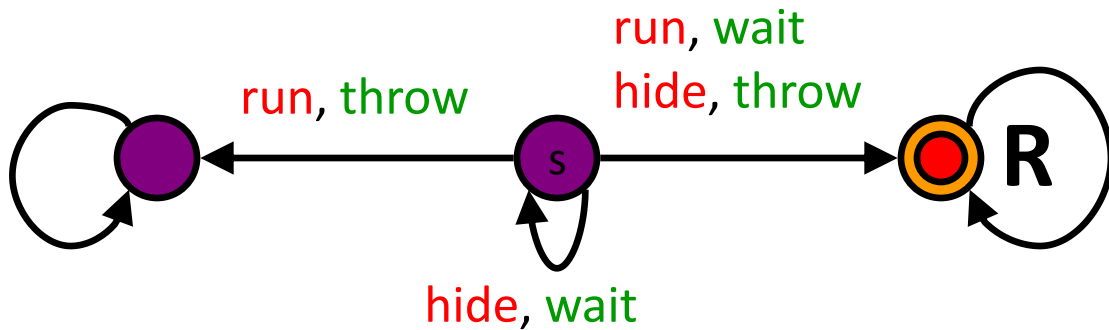
- $S$  is a finite set of states.
- $M$  is a finite set of moves or actions.
- $\Gamma_i: S \rightarrow 2^M \setminus \emptyset$  is an action assignment function that assigns the non-empty set  $\Gamma_i(s)$  of actions to player  $i$  at  $s$ , where  $i \in \{1, 2\}$ .
- $\delta: S \times M \times M \rightarrow \text{Dist}(S)$ , is a probabilistic transition function that given a state and actions of both players gives a probability distribution of the next state.

# An Example (Deterministic Transition)



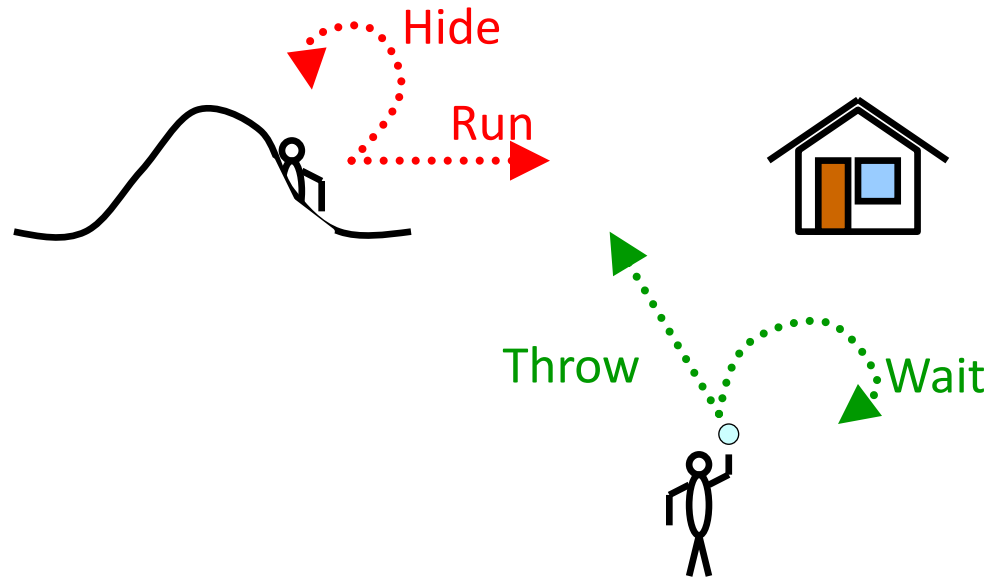


# Concurrent reachability games



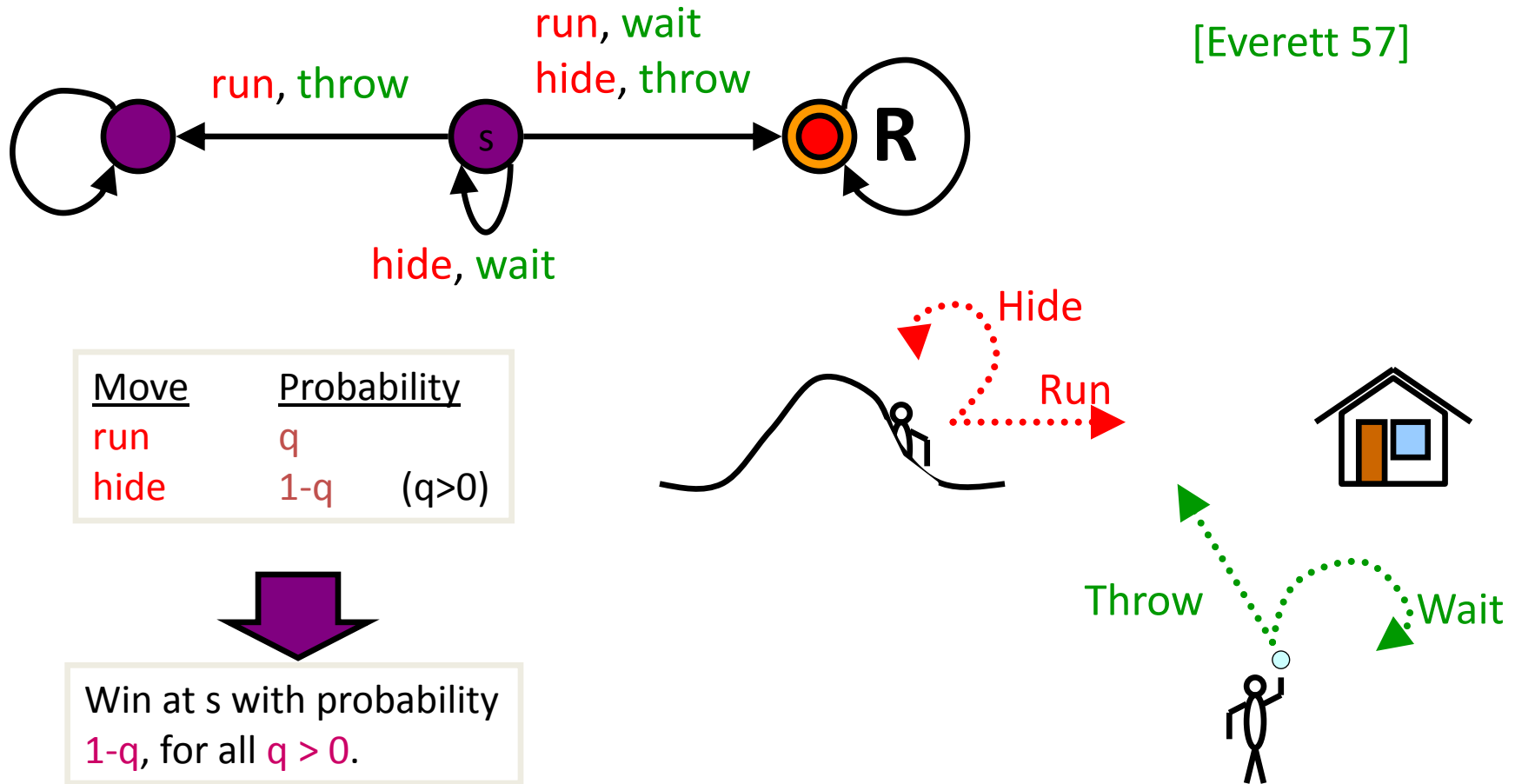
[Everett 57]

Move	Probability
run	$q$
hide	$1-q$ ( $q > 0$ )



Win at  $s$  with probability  $1-q$ , for all  $q > 0$ .

# Concurrent reachability games



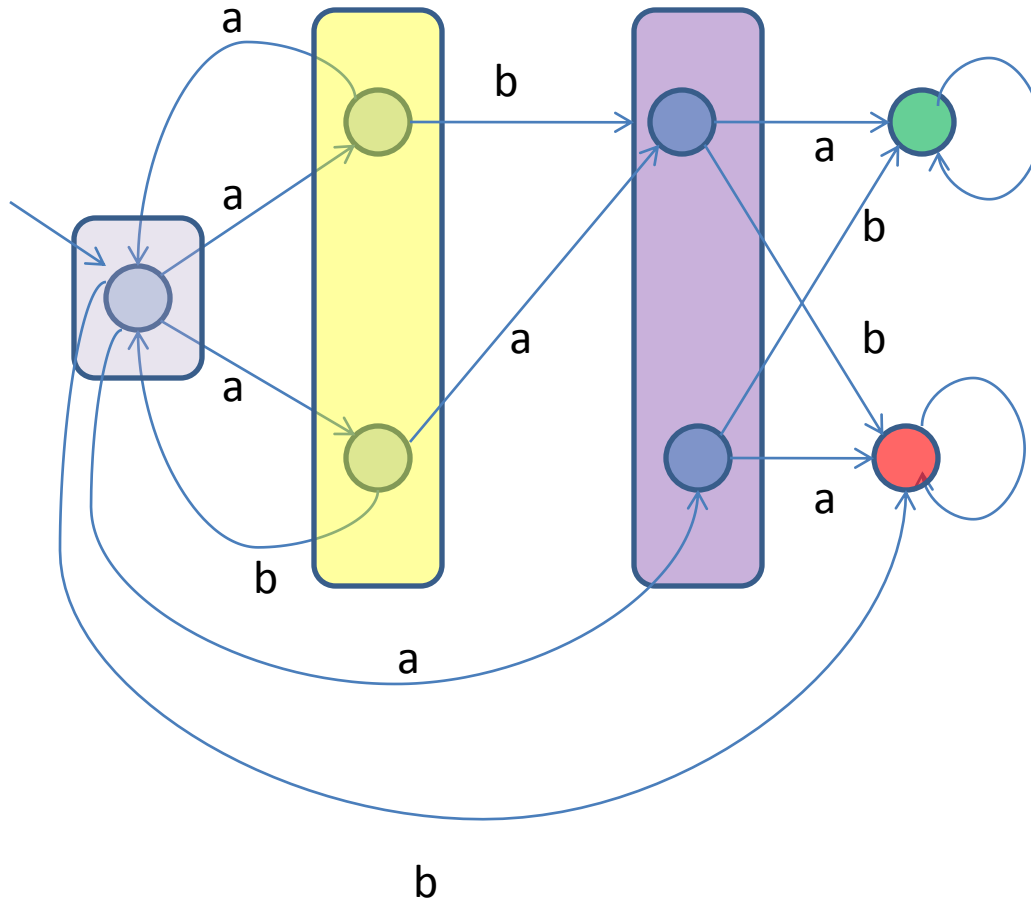
Player 1 cannot achieve  $v(s) = 1$ , only  $v(s) = 1-q$  for all  $q > 0$ .

# Concurrent Games

- Strategies
  - Require randomization.
  - May not be optimal.
  - Only  $\epsilon$ -optimal, for  $\epsilon > 0$ .
  - For liveness requires infinite memory.
- Values can be irrational for concurrent deterministic reachability games.
- Qualitative and quantitative analysis still decidable
  - Qualitative analysis is  $NP \cap coNP$ .
  - Quantitative analysis is PSPACE.

# PARTIAL-INFORMATION GAMES

# Partial-information Games



In starting play a.

In yellow play a and b at random.

In purple:

- if last was yellow then a
- if last was starting, then b.

Requires both randomization and memory

# Partial-information Games

- Strategies
  - Require randomization.
  - May not be optimal.
  - Only  $\epsilon$ -optimal, for  $\epsilon > 0$ .
  - For liveness requires infinite memory.
  - More complicated than concurrent games.
- Quantitative analysis
  - Undecidable.
- Qualitative analysis
  - Reachability, Liveness: EXPTIME-complete.
  - Parity: Undecidable.

# Conclusion

- Perfect-information stochastic games
  - Applications: verification and synthesis of stochastic reactive systems.
  - Markov chains, MDPs and stochastic games with parity objectives.
- Glimpses of the world of games beyond.

# References

- Applications and connections:
  - Church 62, Pnueli-Rosner 89, Ramadge-Wonham 87, Courcoubetis-Yannakakis 95, Thomas Handbook 97, and many more.
- Markov chains:
  - Book of Kemeny
- Markov Decision Processes:
  - Book of Filar Vrieze.
  - Probabilistic verification: Courcoubetis-Yannakakis.
  - PhD Thesis of deAlfaro.
- Stochastic games
  - Condon 92, 93.
  - PhD Thesis of Chatterjee



The end

Thank you !



Questions ?