

Uniformization in Automata Theory

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RWTH Aachen

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A3 – Logic and Computation

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- 1 Introduction
- 2 Uniformization of Automatic Relations
- 3 Synthesis of Nonterminating Programs

Outline

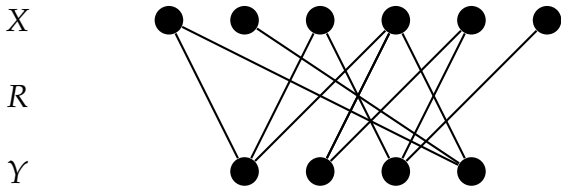
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Uniformization

Given a relation $R \subseteq X \times Y$, a uniformization of R is a function

$$f_R : X \rightarrow Y$$

whose graph is a subset of R .

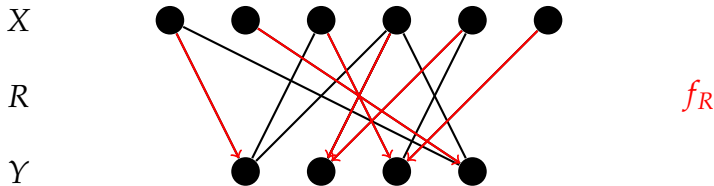


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Uniformization in Descriptive Set Theory

Axiom of Choice: For each relation R there is some uniformization f_R

Descriptive Set Theory: Study of definable objects. Relate the complexity of R and the complexity of a uniformization f_R :

- For a class \mathcal{C} of relations and a class \mathcal{F} of functions, does each R in \mathcal{C} have a uniformization in \mathcal{F} ?

Uniformization in Automata Theory

Idea: effective uniformization

Classes \mathcal{C} , \mathcal{F} defined by automata (or equivalent logical formalism)

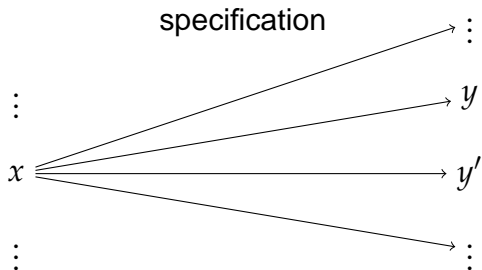
Questions:

- Does each $R \in \mathcal{C}$ have a uniformization in \mathcal{F} ?
- Given $R \in \mathcal{C}$ decide if it has a uniformization in \mathcal{F} and effectively construct one if possible.

From Specification to Implementation

input

output

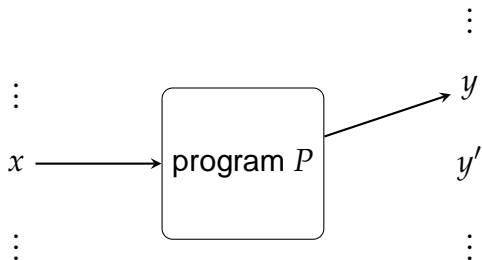


Effective uniformization can be seen as a form of automatic program synthesis from specifications.

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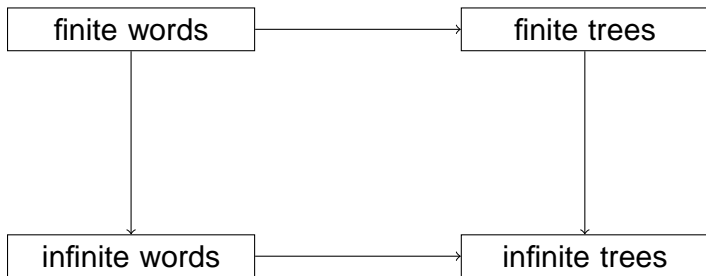
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Automatic Relations over Different Structures



Automatic Relations over Finite Words

Example: Alphabet $\{0, 1\}$

$$R = \{(1^n, 1^m 0 1^k 0^*) \mid n = m + k + 1\}$$

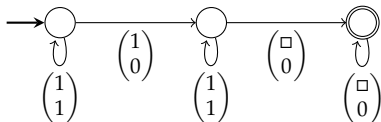
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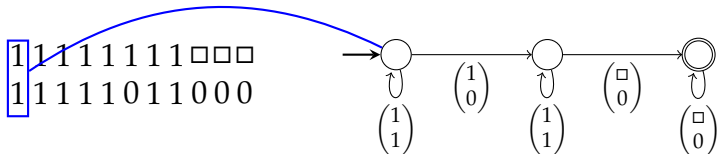
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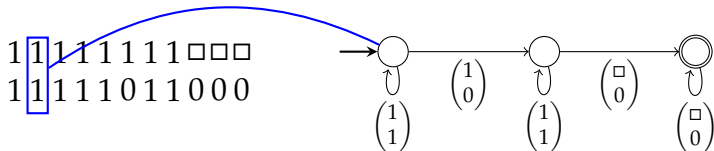
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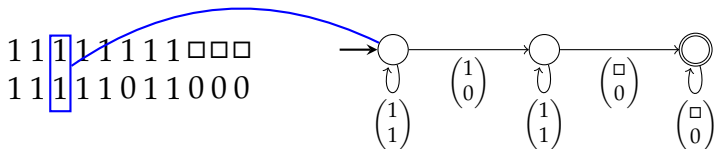
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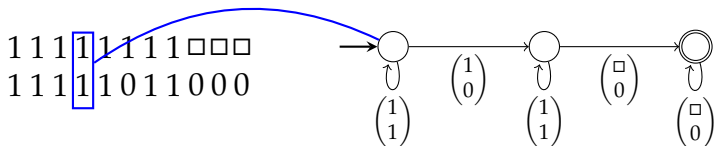
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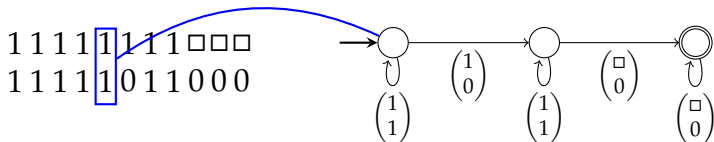
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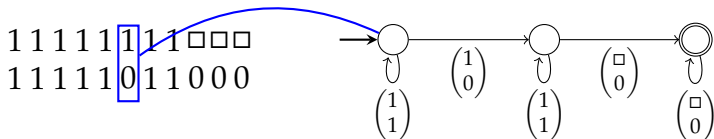
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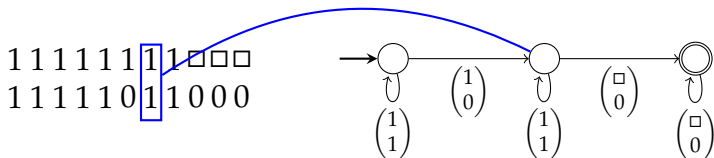
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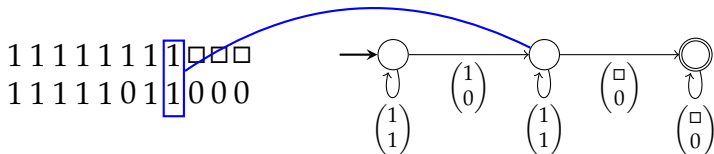
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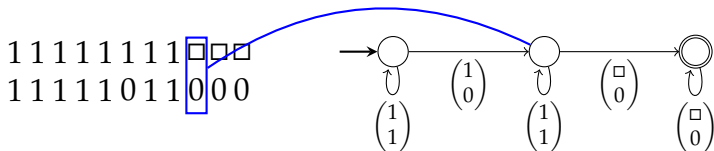
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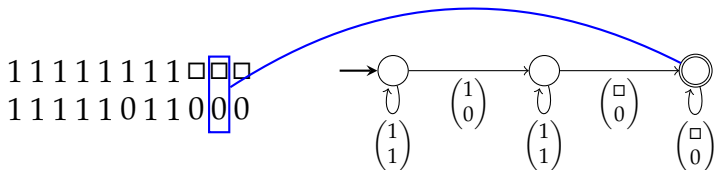
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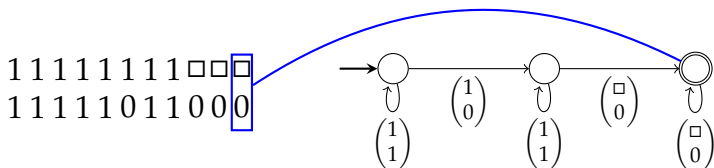
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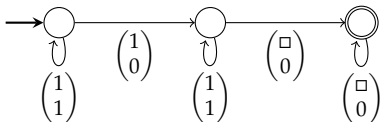


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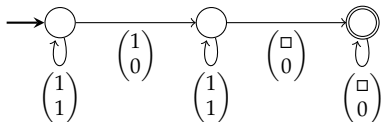
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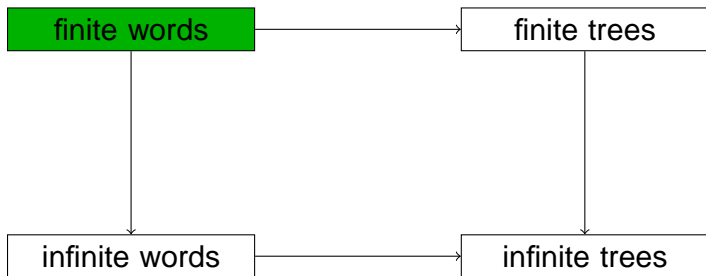
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Length-lexicographic uniformization: $f_R = \{(1^n, 01^{n-1})\}$

Theorem. For an automatic relation R over finite words the length-lexicographic uniformization f_R is also automatic.

Automatic Relations over Different Structures



Automatic Relations of Infinite Words

Example: $(0^\omega, (0^+1)^\omega) \cup (1^\omega, (1^+0)^\omega)$

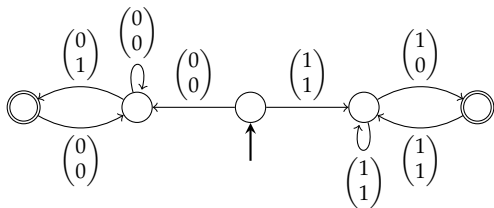
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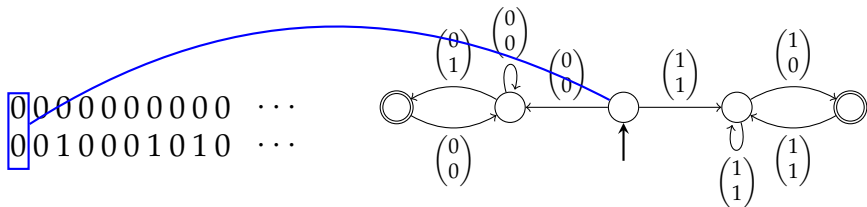
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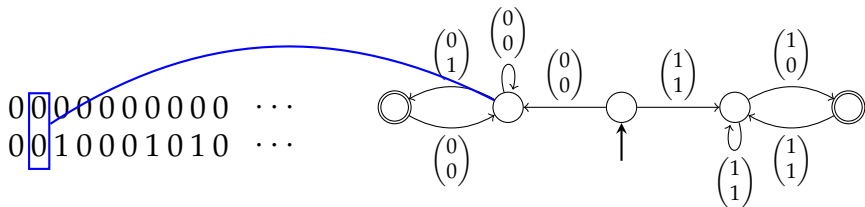
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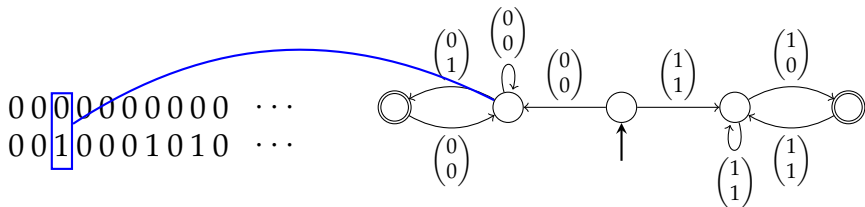
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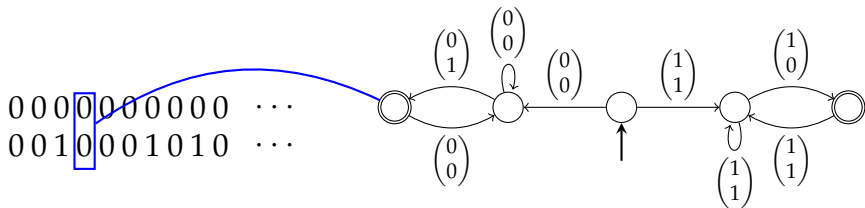
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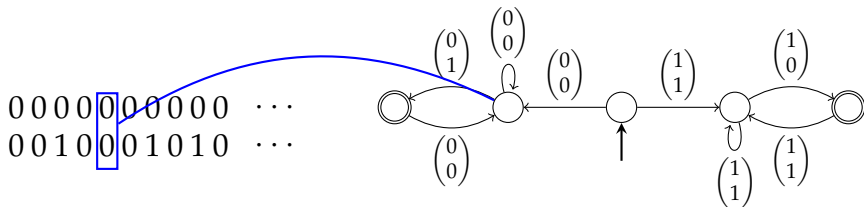
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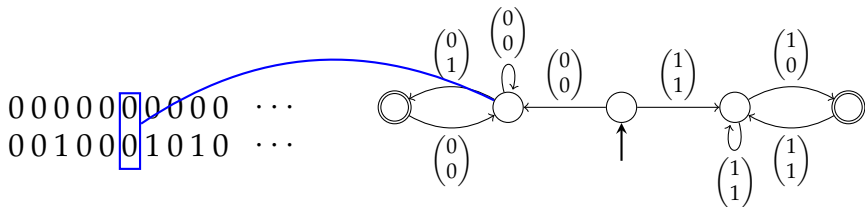
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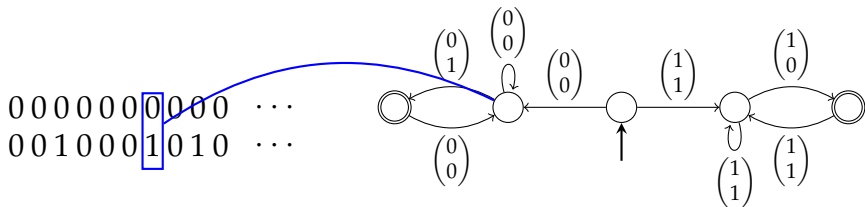
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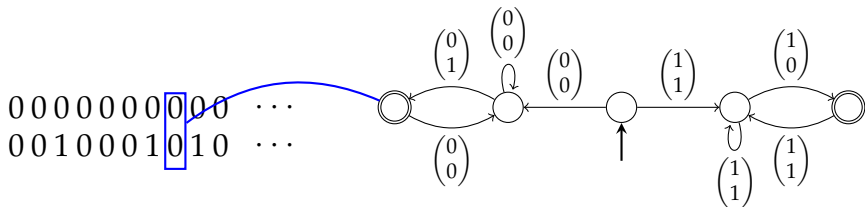
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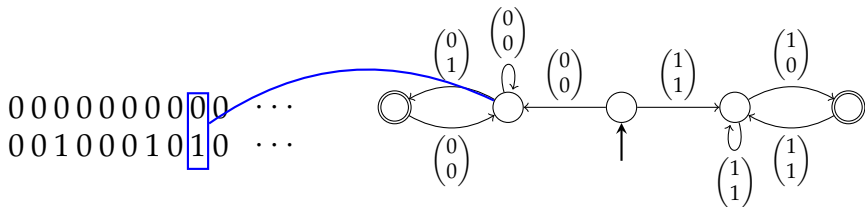
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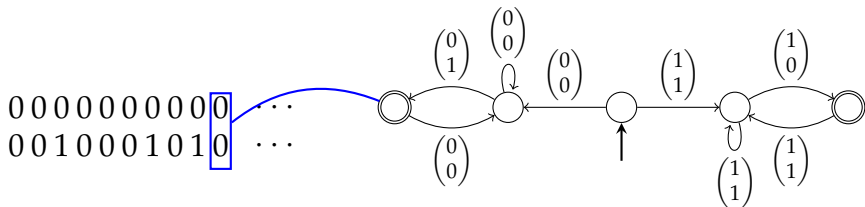
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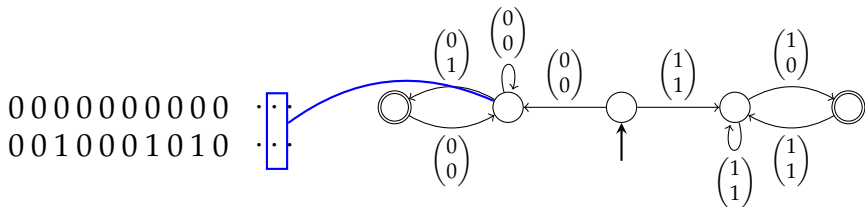
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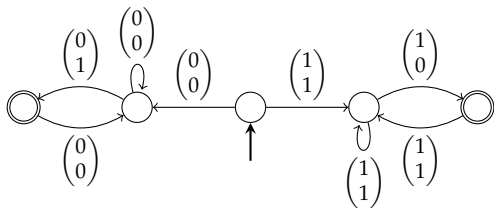
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Observation: lexicographic uniformization does not work

Solution: greedy ordering of accepting runs (visit accepting state as soon as possible)

Theorem (Siefkes'75, Choffrut/Grigorieff'99). Automatic relations over infinite words have automatic uniformizations.

Connection to Logic

- Infinite 0-1-sequences \leftrightarrow sets of natural numbers
- Monadic second-order logic (MSO) over the structure $(\mathbb{N}, +1)$
MSO $\hat{=}$ first-order logic + set quantification
- Relations of 0-1-sequences can be expressed by formulas $\varphi(X, Y)$

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$$\begin{aligned}\varphi(X, Y) = & (\forall x \neg X(x)) \rightarrow \\ & \forall y \exists z > y (Y(z) \wedge (Y(y) \rightarrow \neg Y(y + 1))) \\ & \dots\end{aligned}$$

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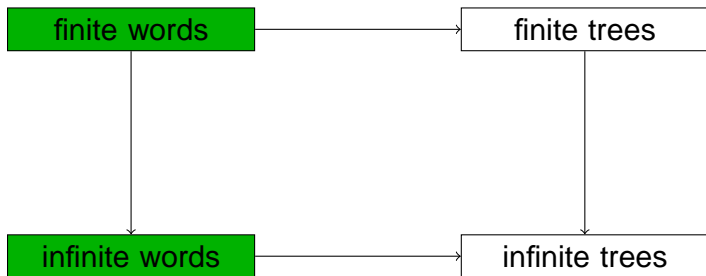
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Theorem (Büchi'60). Nondeterministic finite automata and MSO over infinite words have the same expressive power.

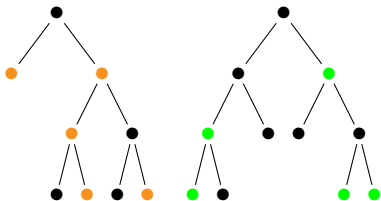
Corollary. For every MSO formula $\varphi(X, Y)$ there is a formula $\psi(X, Y)$ defining a uniformization of the relation defined by φ .

Automatic Relations over Different Structures



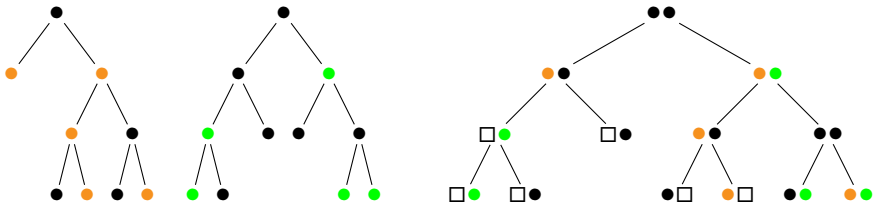
Finite Trees

How to combine trees?



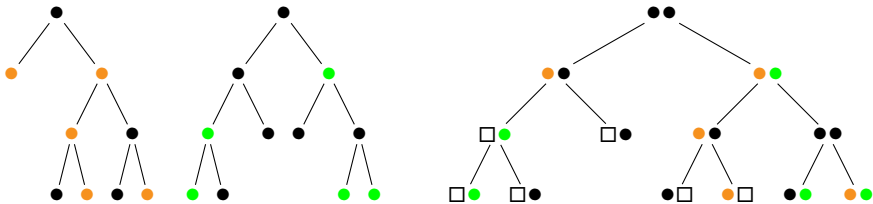
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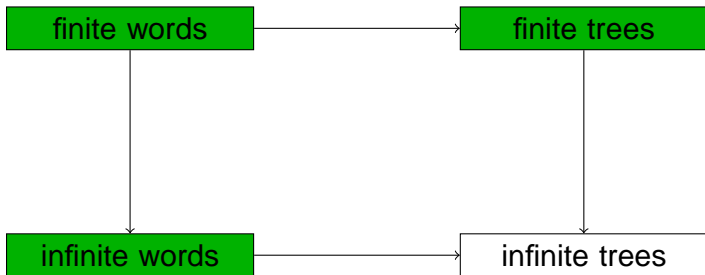
How to combine trees?



From results in Colcombet/L.'06 and Kuske/Weidner'11:

Theorem. Every tree automatic relation has a tree automatic uniformization.

Automatic Relations over Different Structures

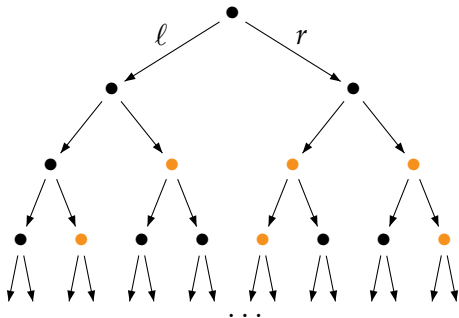


Infinite Trees

Infinite binary tree structure $T_2 = (\{\ell, r\}^*, S_\ell, S_r)$

A 0-1-labeling of T_2 corresponds to subset of $\{\ell, r\}^*$.

As for infinite words: Finite automata $\hat{=} \text{MSO over } T_2$ (Rabin'69)



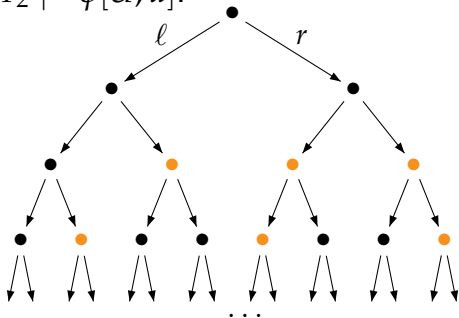
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Theorem(Gurevich/Shelah'83). There is no MSO-definable choice function over the infinite binary tree, i.e., there is no formula $\varphi(X, y)$ such that for each (nonempty) set U there is exactly one node $u \in U$ such that $T_2 \models \varphi[U, u]$.



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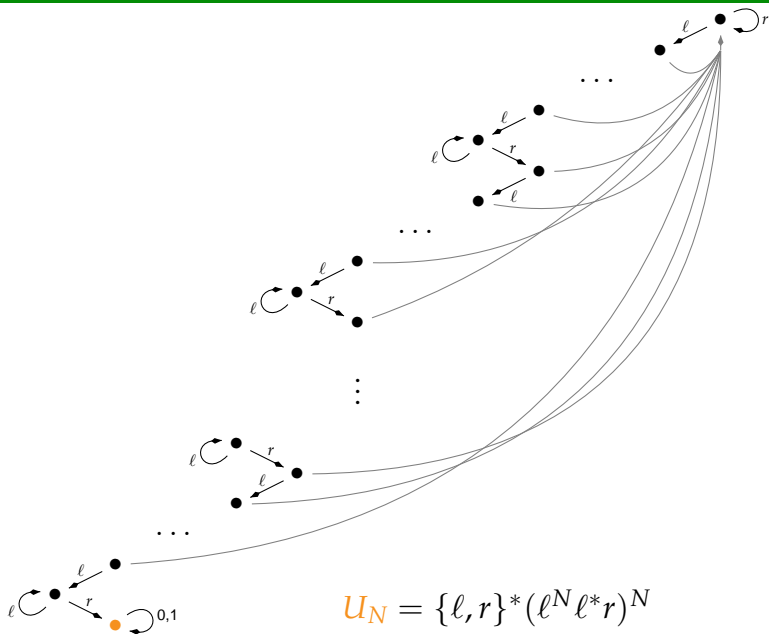
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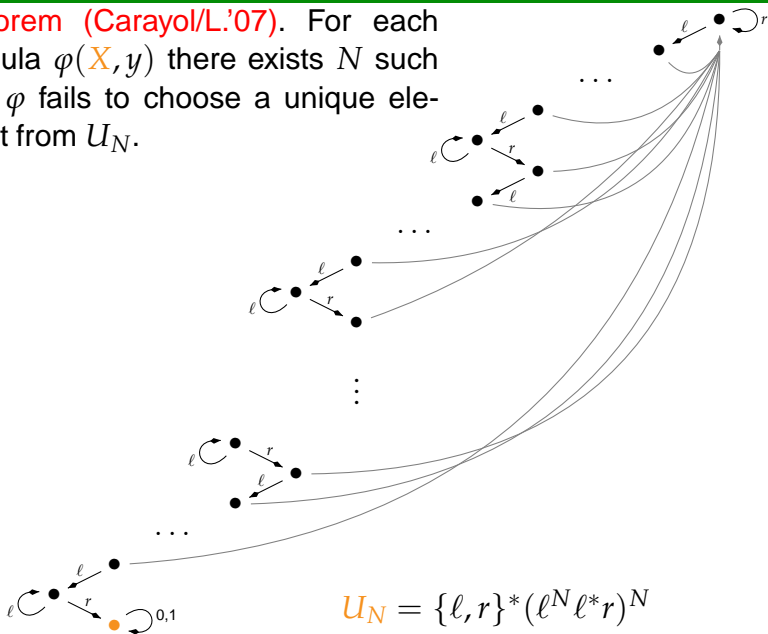
Remark: The proof of Gurevich/Shelah'83 used methods from set theory. A new automata theoretic proof yields a simple family of counter examples.

Counterexamples for MSO Choice



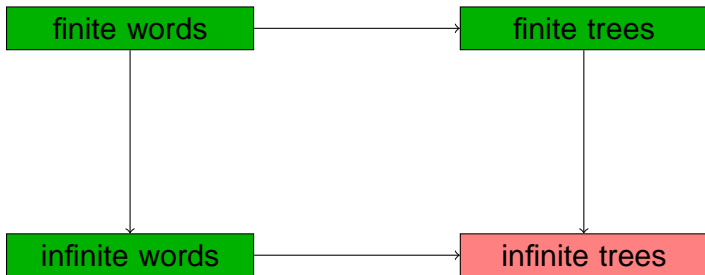
Counterexamples for MSO Choice

Theorem (Carayol/L.'07). For each formula $\varphi(X, y)$ there exists N such that φ fails to choose a unique element from U_N .



$$U_N = \{l, r\}^* (l^N l^* r)^N$$

Automatic Relations over Different Structures



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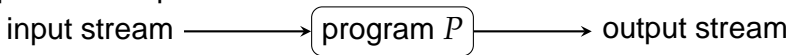
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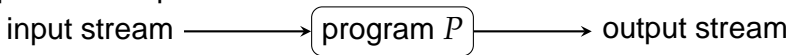
Back to Infinite Words

- Infinite words are used to model the behavior of non-terminating processes (e.g. protocols, controllers)
- Such processes are usually reactive: they receive inputs and produce outputs



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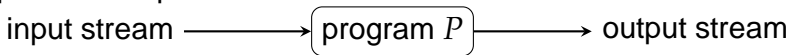
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- A specification relates the possible input sequences to allowed output sequences \rightsquigarrow relation of infinite words, e.g., “each request is eventually followed by a grant”
- Uniformization = Implementation?

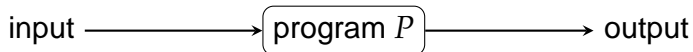
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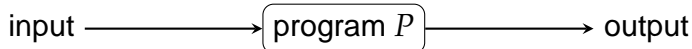
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No! An implementation has to produce the outputs “online”

Problem Setting



- Alphabets I and J for input and output (assume here $I = J = \{0, 1\}$)
- MSO-formula $\varphi(X, Y)$ defines specification

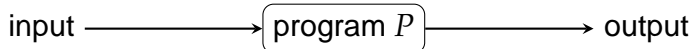
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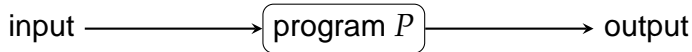
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$X \quad a_0$

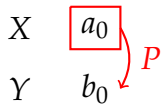
Y

Problem Setting

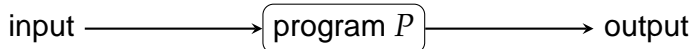


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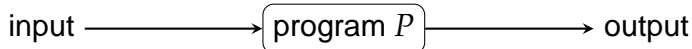
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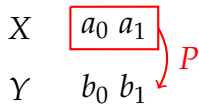
$Y \quad b_0$

Problem Setting

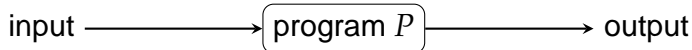


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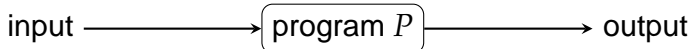
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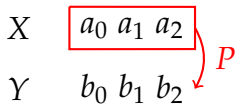
Y $b_0 b_1$

Problem Setting

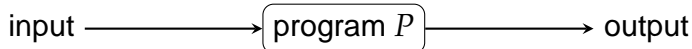


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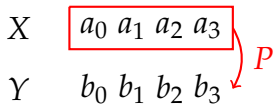
Y $b_0 b_1 b_2$

Problem Setting

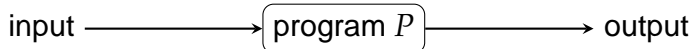


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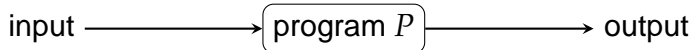
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X a_0 a_1 a_2 a_3 a_4

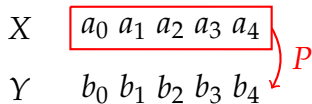
Y b_0 b_1 b_2 b_3

Problem Setting

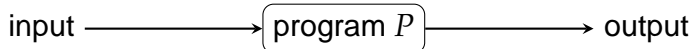


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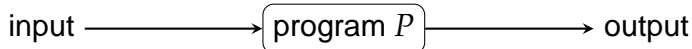


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Finite automata solution: P is a finite state machine (S, I, s_0, δ, f) with output function $f : S \times I \rightarrow J$.

Example

$$\varphi(X, Y) = \underbrace{\forall x \left(X(x) \rightarrow \exists y > x (Y(y)) \right)}_{\text{each input 1 later followed by output 1}} \wedge \underbrace{\forall x \exists y > x (\neg Y(y))}_{\text{infinitely often output 0}}$$

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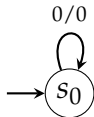
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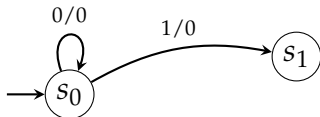
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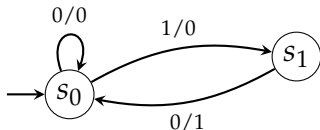
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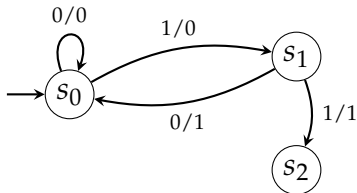
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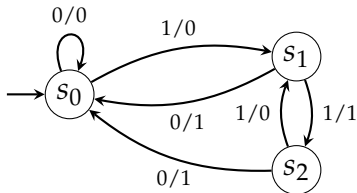
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Finite automata solution:



Büchi-Landweber Theorem

Theorem (Büchi/Landweber 1969). The synthesis problem for MSO specifications is solvable. If the specification is realizable, then a finite automaton solution can be constructed.

Proof idea:

- View problem as game between players Input and Output: game with simple rules (players play bits in alternation) but a complex winning condition (the formula)
- Reduction to a game with more complex rules but much simpler winning condition

Continuous Functions

$\{0,1\}^\omega$ as metric space: $d(\alpha, \beta) = \frac{1}{2^n}$

where n is the length of the longest common prefix of α and β

α	0010001	1	00	...	
β	0010001	0	10	...	$d(\alpha, \beta) = \frac{1}{2^7}$

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Previous synthesis question: exists program (function) P with

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Previous synthesis question: exists program (function) P with

$$d(P(\alpha), P(\beta)) \leq d(\alpha, \beta)?$$

Generalized question: exists program (function) P realizing a continuous function: Each finite prefix of the output only depends on a finite prefix of the input.

Delaying the Output

I

J

Delaying the Output

$I \quad a_0$

J

Delaying the Output

$I \quad a_0$

$J \quad b_0$

Delaying the Output

I $a_0 a_1$

J b_0

Delaying the Output

I $a_0 a_1$

J b_0 skip

Delaying the Output

$I \quad a_0 a_1 a_2$

$J \quad b_0$

Delaying the Output

$I \quad a_0 a_1 a_2$

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Delaying the Output

$I \quad a_0 \ a_1 \ a_2 \ a_3$

$J \quad b_0 \ b_1$

Delaying the Output

$I \quad a_0 \ a_1 \ a_2 \ a_3$

$J \quad b_0 \ b_1 \ \text{skip}$

Delaying the Output

$I \quad a_0 \ a_1 \ a_2 \ a_3 \ a_4$

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Delaying the Output

$I \quad a_0 a_1 a_2 a_3 a_4 \dots \models \varphi$

$J \quad b_0 b_1 b_2 \dots$

Delaying the Output

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Question:

Given a specification, does there exist a strategy (program)

$P : I^* \rightarrow (J \cup \{\text{skip}\})$ that

- produces an infinite output sequence for each input and
- realizes the specification?

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Can the specification be uniformized by a continuous function?

Examples

$$I = J = \{0, 1\}$$

- $\varphi(X, Y) = \forall x(Y(x) \leftrightarrow X(x + 1))$

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Output has to skip once at the beginning and then plays 1 iff the input is 1.

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Bounded Delay in Regular Games

Theorem (Hosch/Landweber'72,Holtmann/Kaiser/Thomas'10). For MSO specifications it is decidable if there is a strategy with delay realizing the specification. Furthermore, strategies with bounded delay are sufficient.

Corollary. It is decidable whether an MSO definable relation over infinite words can be uniformized by a continuous function.

Beyond Finite Automata

Use pushdown automata (finite automata + stack) instead of finite automata.

Without Delay:

Theorem (Walukiewicz'96). The synthesis problem for deterministic pushdown specifications is decidable. If the specification is realizable, then it can be implemented by a pushdown automaton.

Beyond Finite Automata

With Delay:

Example: Specification allows the following pairs of input/output sequences (with $I = J = \{0, 1\}$):

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}^\omega \text{ or}$$

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Example: Specification allows the following pairs of input/output sequences (with $I = J = \{0, 1\}$):

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With Delay:

Example: Specification allows the following pairs of input/output sequences (with $I = J = \{0, 1\}$):

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^n \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^{n+1} \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega$$

Beyond Finite Automata

With Delay:

Example: Specification allows the following pairs of input/output sequences (with $I = J = \{0, 1\}$):

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^n \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^{n+1} \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega$$

There is a strategy with linear delay:

I

J

Beyond Finite Automata

With Delay:

Example: Specification allows the following pairs of input/output sequences (with $I = J = \{0, 1\}$):

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^n \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^{n+1} \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega$$

There is a strategy with linear delay:

I 0

J

Beyond Finite Automata

With Delay:

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There is a strategy with linear delay:

I 0

J skip

Beyond Finite Automata

With Delay:

Example: Specification allows the following pairs of input/output sequences (with $I = J = \{0, 1\}$):

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^n \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^{n+1} \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega$$

There is a strategy with linear delay:

$I \quad 0 \quad 0$

J

Beyond Finite Automata

With Delay:

Example: Specification allows the following pairs of input/output sequences (with $I = J = \{0, 1\}$):

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^n \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^{n+1} \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega$$

There is a strategy with linear delay:

I 0 0

J 0

Beyond Finite Automata

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J 0

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There is a strategy with linear delay:

I 0 0 0

J 0 skip

Beyond Finite Automata

With Delay:

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$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^n \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^{n+1} \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega$$

There is a strategy with linear delay:

I 0 0 0 0

J 0

Beyond Finite Automata

With Delay:

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There is a strategy with linear delay:

I 0 0 0 0

J 0 0

Beyond Finite Automata

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$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^n \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^{n+1} \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega$$

There is a strategy with linear delay:

I 0 0 0 0 0

J 0 0

Beyond Finite Automata

With Delay:

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There is a strategy with linear delay:

I 0 0 0 0 0

J 0 0 skip

Beyond Finite Automata

With Delay:

Example: Specification allows the following pairs of input/output sequences (with $I = J = \{0, 1\}$):

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^n \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega \text{ or } \begin{pmatrix} 0 \\ 0 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}^{n+1} \begin{pmatrix} 1 \\ J \end{pmatrix} \begin{pmatrix} I \\ J \end{pmatrix}^\omega$$

There is a strategy with linear delay:

I 0 0 0 0 0 1

J 0 0

Beyond Finite Automata

With Delay:

Example: Specification allows the following pairs of input/output sequences (with $I = J = \{0, 1\}$):

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There is a strategy with linear delay:

I 0 0 0 0 0 1

J 0 0 1

Theorem (Fridman/L./Zimmerman'11).

- There are deterministic pushdown specifications for which there is a delay strategy but each such strategy needs non-elementary delay.
- For deterministic pushdown specifications it is undecidable if there is a strategy with delay realizing the specification.

Conclusion

Summary

- Uniformization in automata theory: effective theory of uniformization for relations definable by finite automata (or equivalently in MSO logic)
- Connection between synthesis of nonterminating programs and uniformization by continuous functions

Outlook

- Many more models to study: asynchronous automata, non-regular specifications
- Uniformization on infinite trees: decidability questions
- Implementation: make synthesis algorithms usable in practice

Using Determinancy of Games to Eliminate Quantifiers.

J. Richard Buchi, Purdue University

⋮

Some have dreamed about implementing such decision methods on the beautiful modern machines. Some feel that the complexity boys have spoiled these dreams. But then, if one was to heed present complexity theory, how would he dare implement propositional calculus, and how else was he going to use the machine, if he was to believe it can't handle truth tables.